

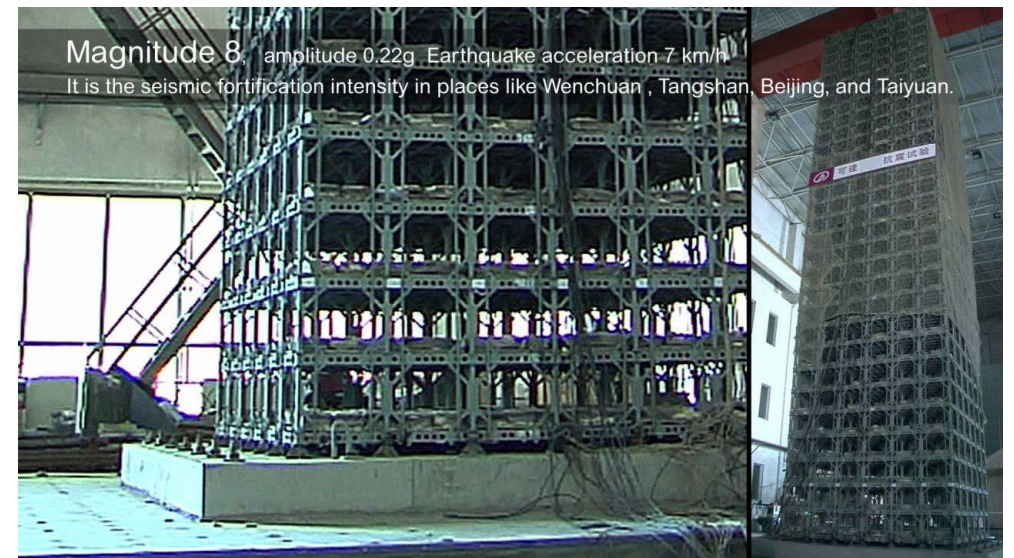
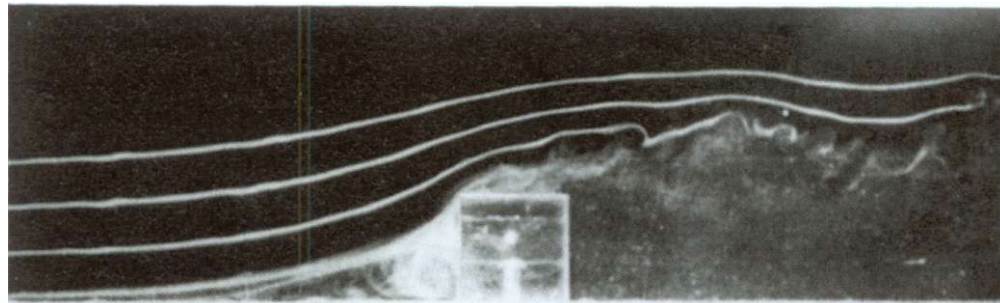
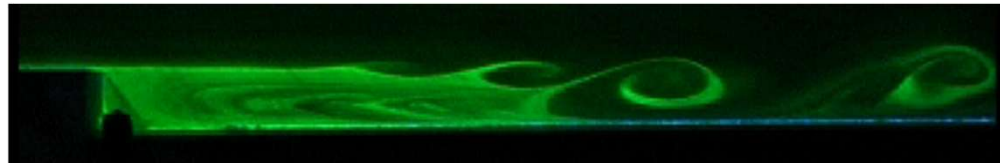
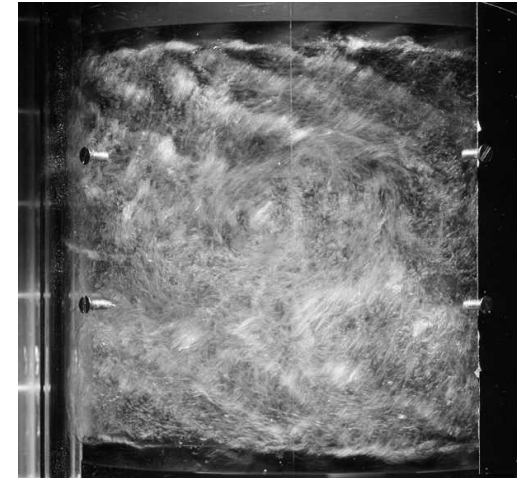
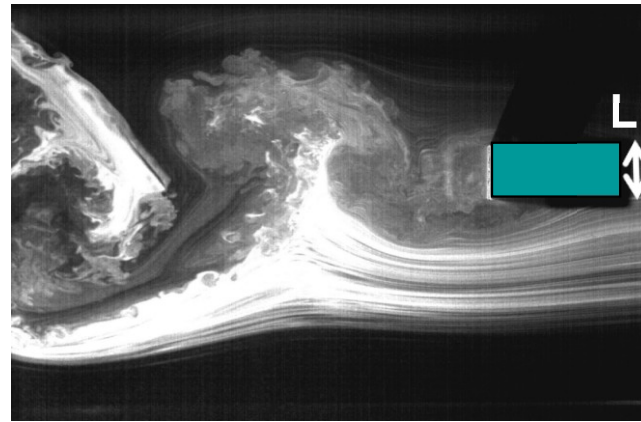
# Signal Processing

**Romain MONCHAUX**

UFR de Mécanique, ENSTA

Institut Polytechnique de Paris

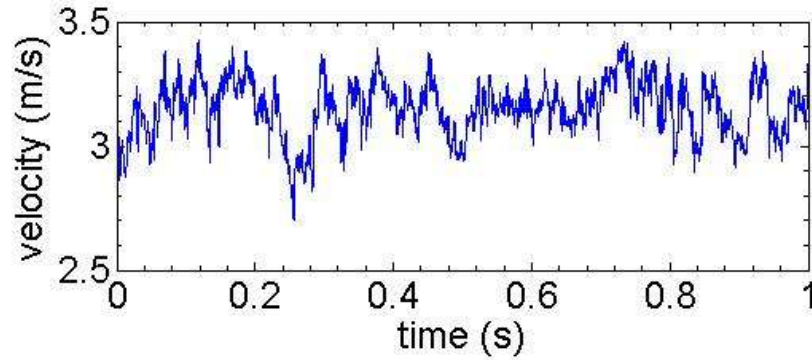
# Motivations



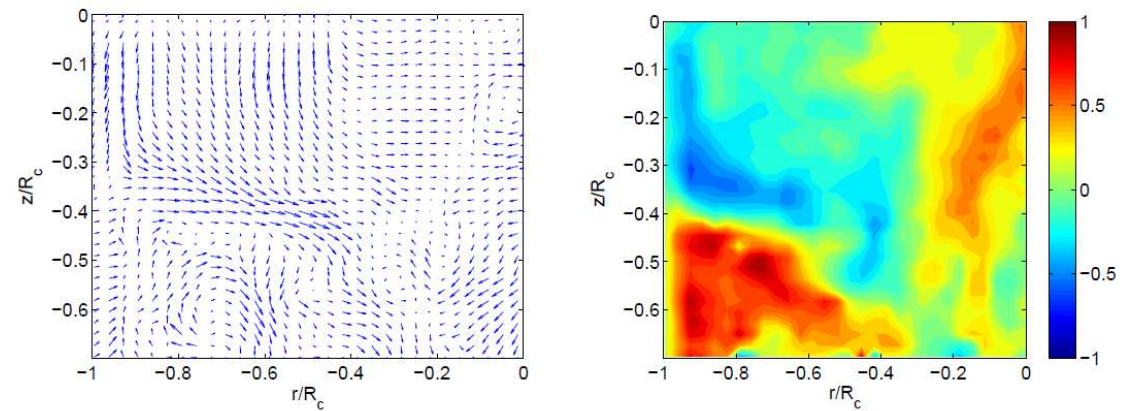
⇒ Visualise, quantify, characterise

# Signal processing: Motivations

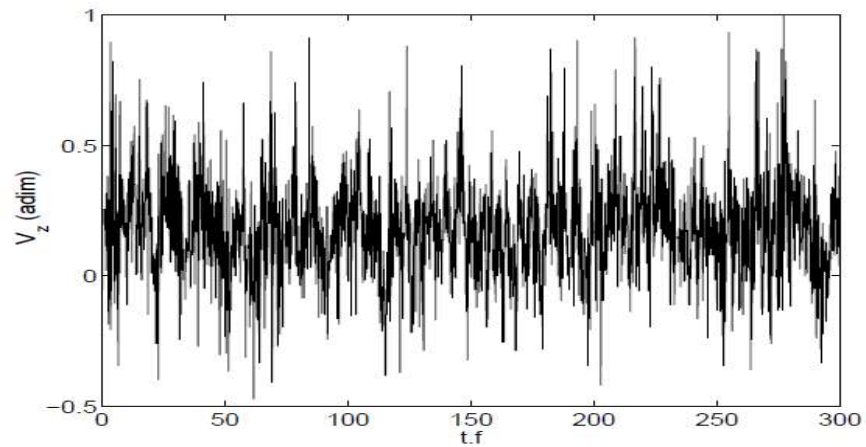
Turbulent jet: hot-wire acquisition



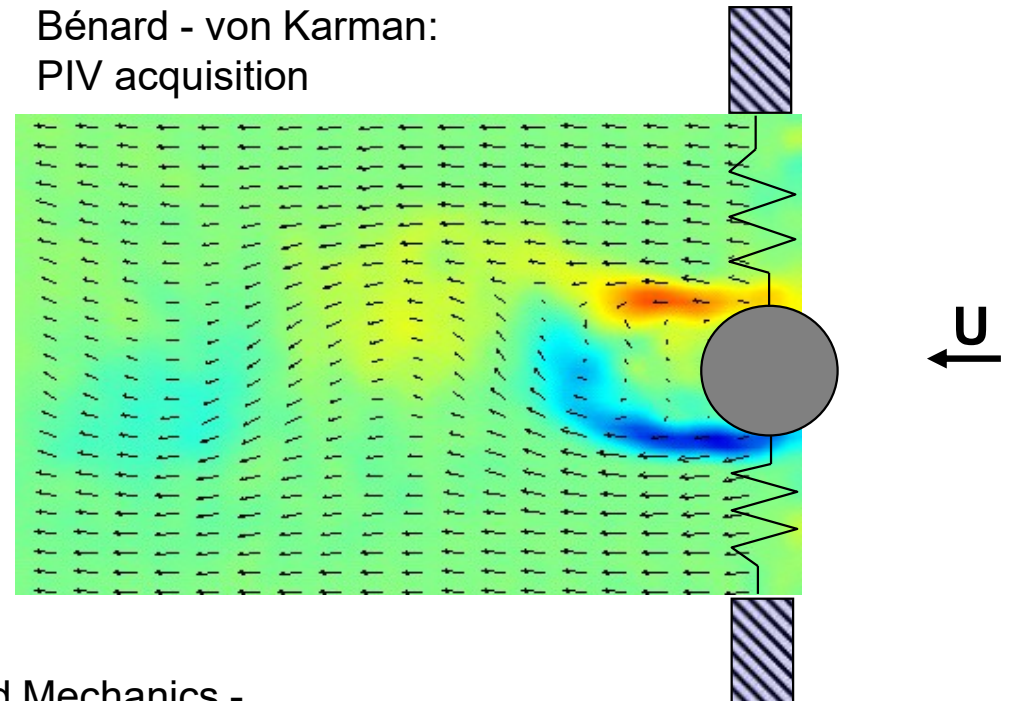
von Karman flow: SPIV acquisition

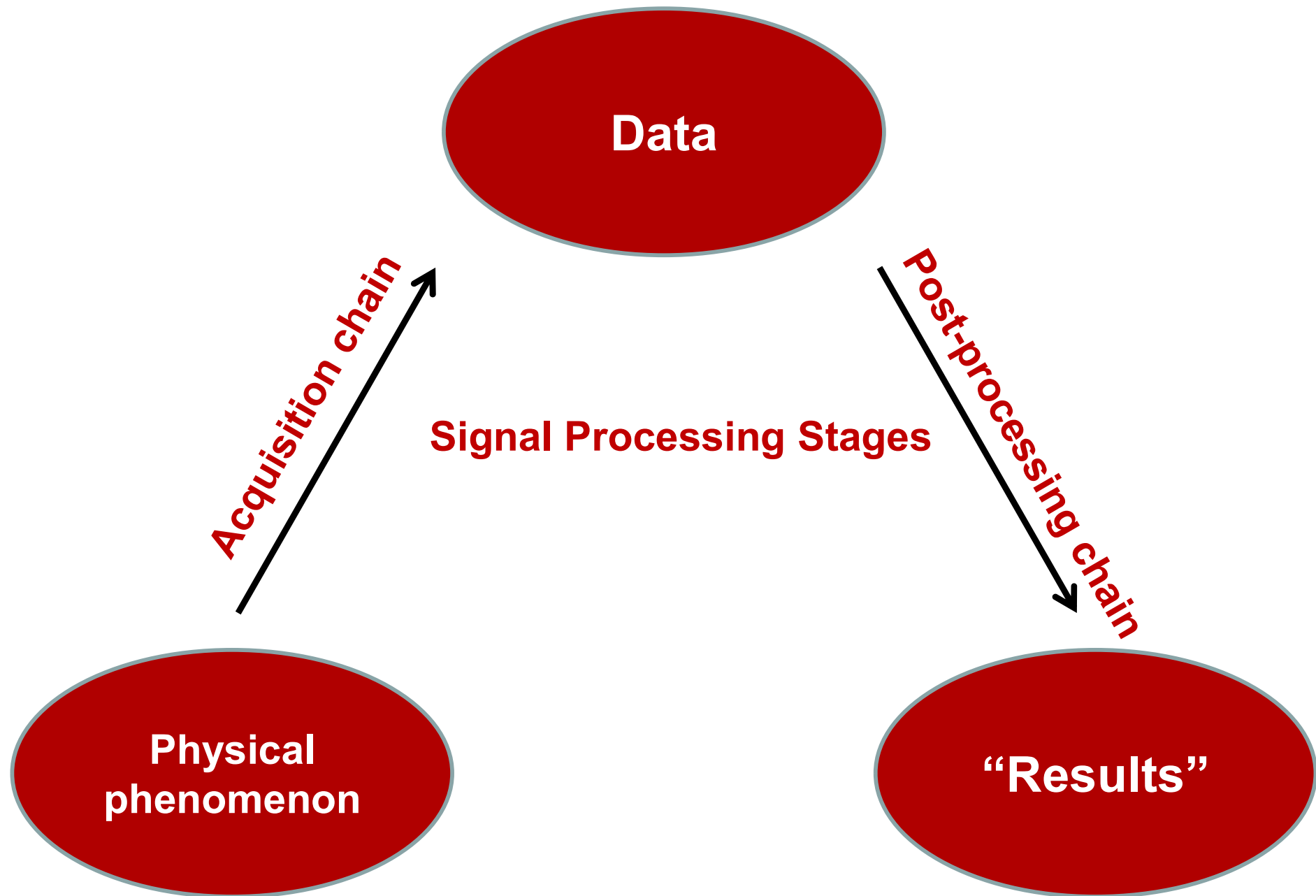


von Karman flow: LDA acquisition



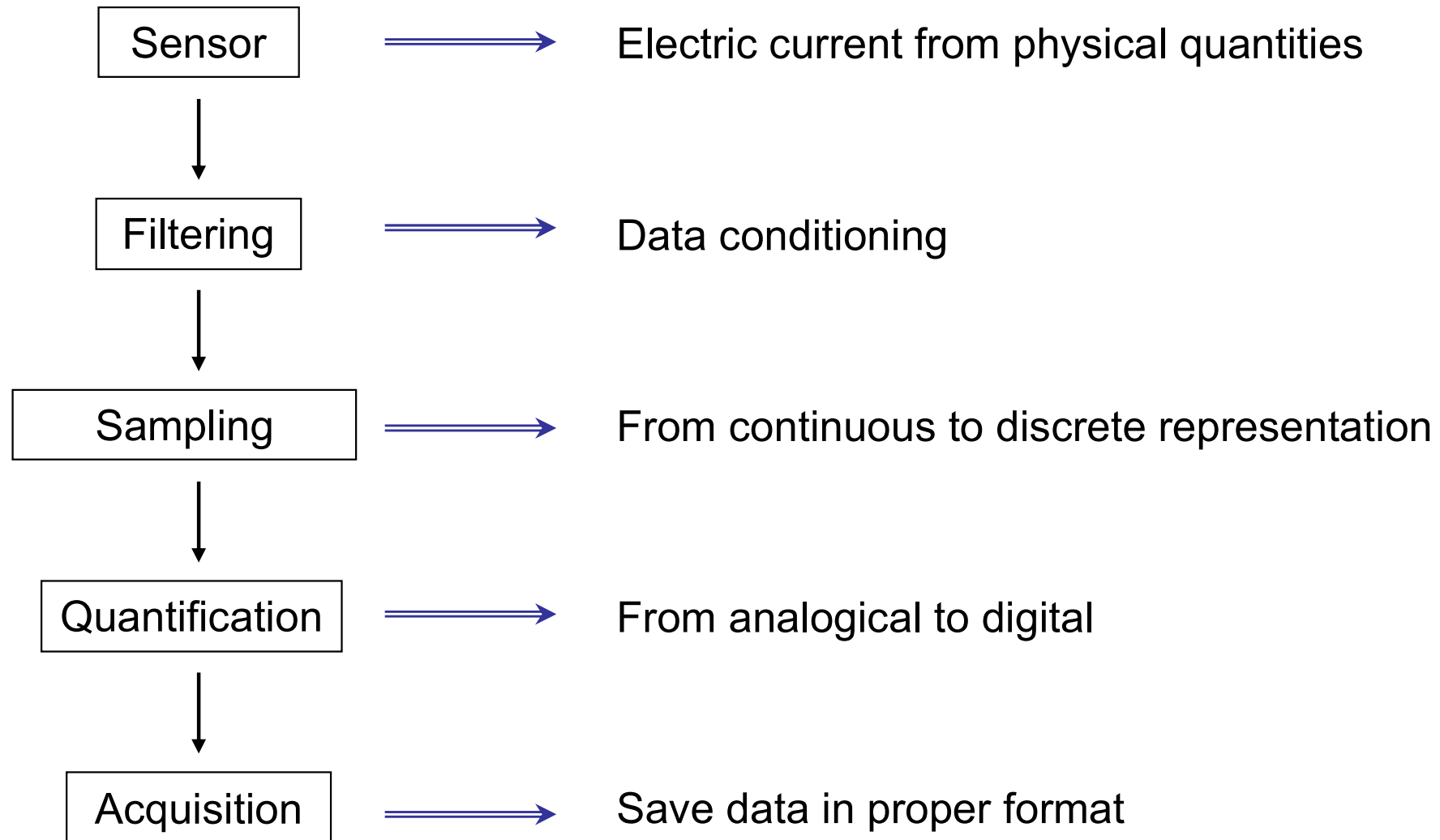
Bénard - von Karman:  
PIV acquisition







# Signal processing: acquisition chain



## Sensors

### Choose physical quantities

Pression  
Position  
Displacement  
Velocity  
Acceleration  
Vorticity  
Deformation  
Force  
...

### Choose the sensor:

Sampling frequency  
Sensitivity, dynamical range  
Spatial extend / Integration  
Intrusivity or not ?  
Life time  
...

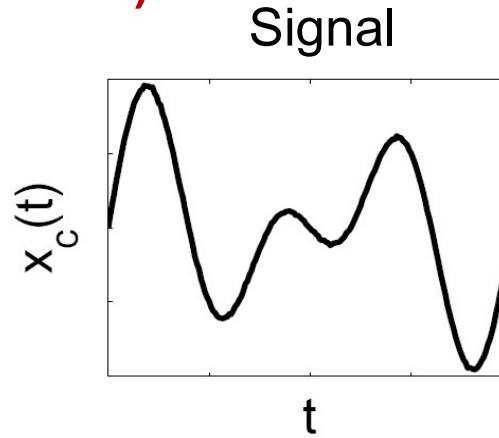
⇒ **Direct Measurement**

⇒ **Indirect Measurement**

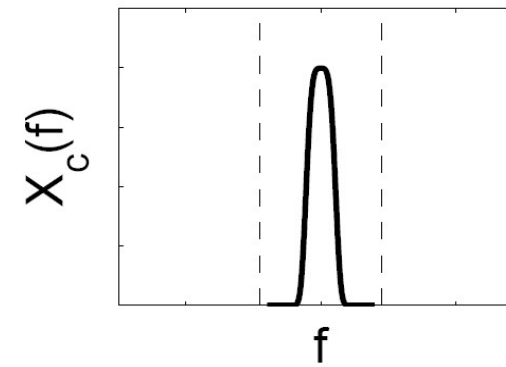


## Sampling (continuous – discrete)

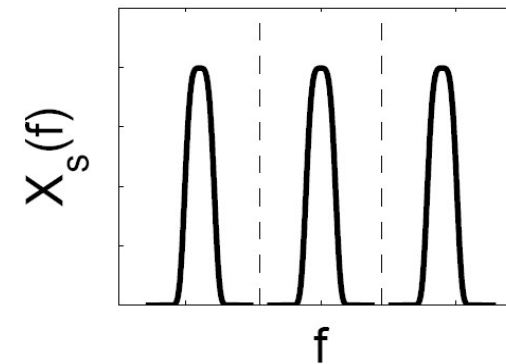
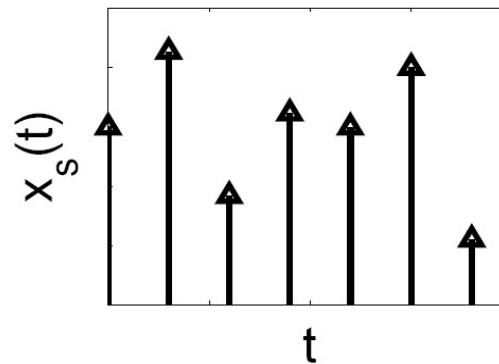
Original signal:



Fourier Transform



Sampled signal:

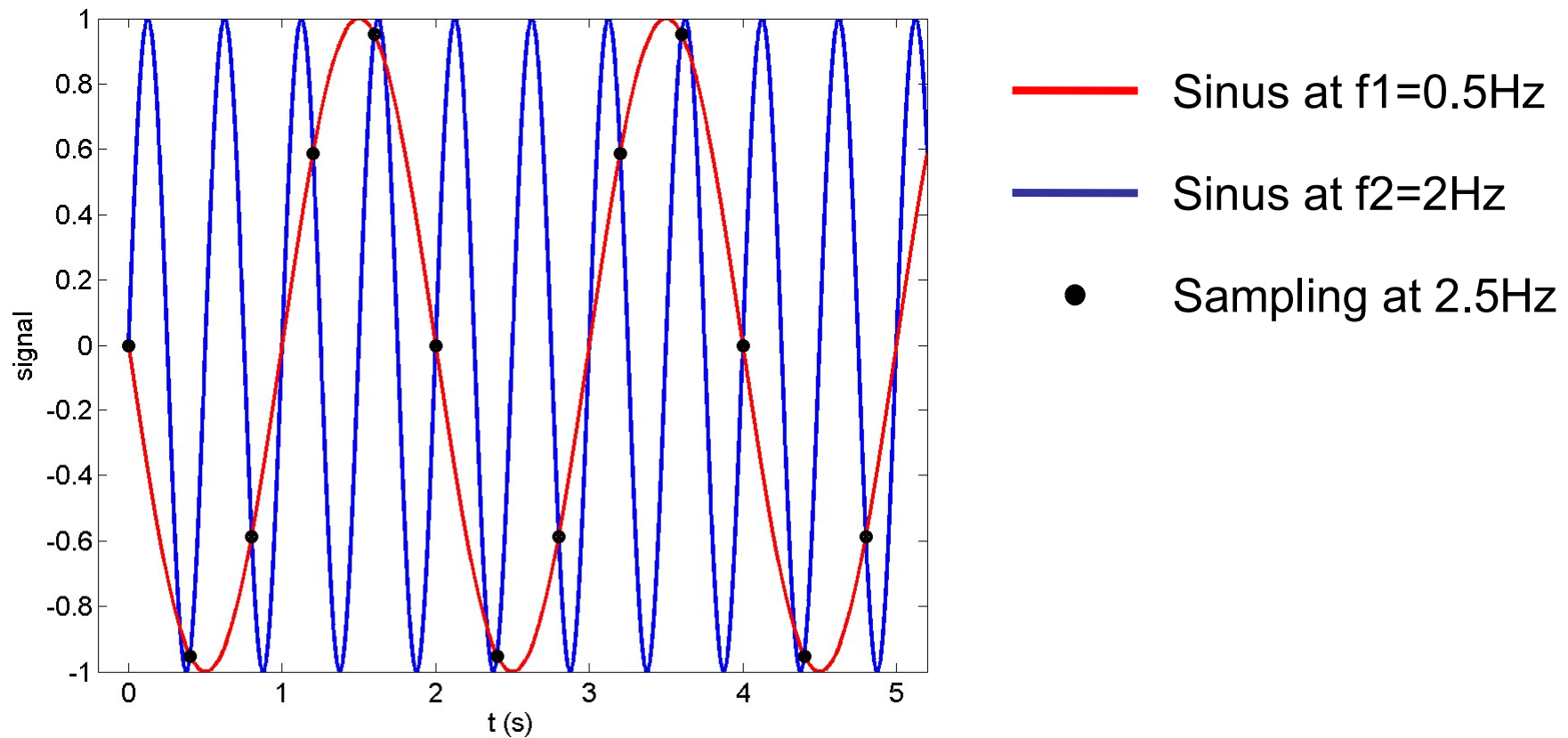


$$x_s(t) = x_c(t) \sum_{k=-\infty}^{+\infty} T_s \delta(t - kT_s)$$

$$X_s(f) = \int_{-\infty}^{+\infty} x_s(t) e^{-2\pi j f t} dt$$

$$X_s(f) = \frac{1}{T_s} \sum_{k=-\infty}^{+\infty} X_c\left(f - \frac{k}{T_s}\right)$$

## Sampling (aliasing)



Sensor

Filtering

Master 2 – Fluid Mechanics –

Sampling

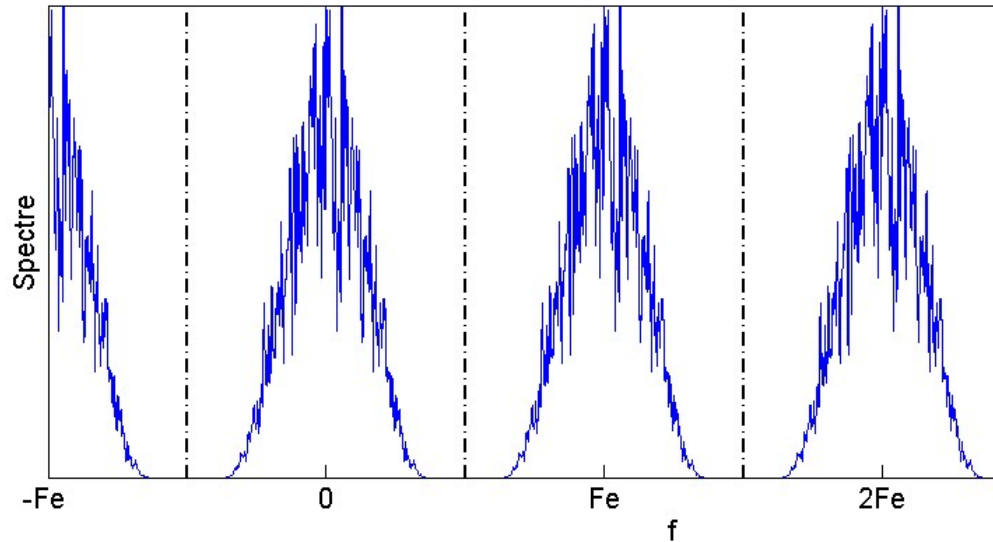
Quantification

Acquisition

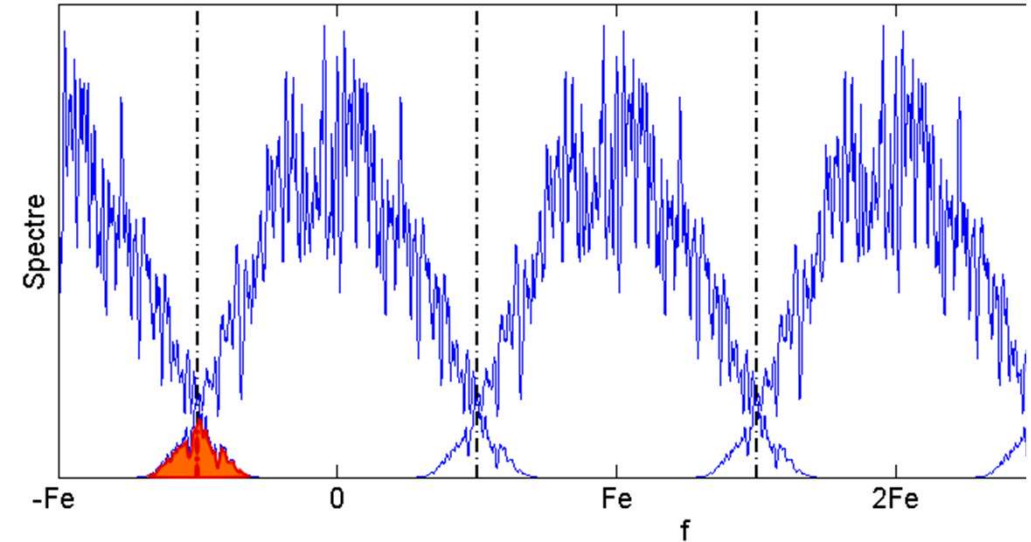


## Sampling (aliasing)

$$F_{\max} < F_e/2$$



$$F_{\max} > F_e/2$$



⇒ **Shannon criterion**

Sensor

Filtering

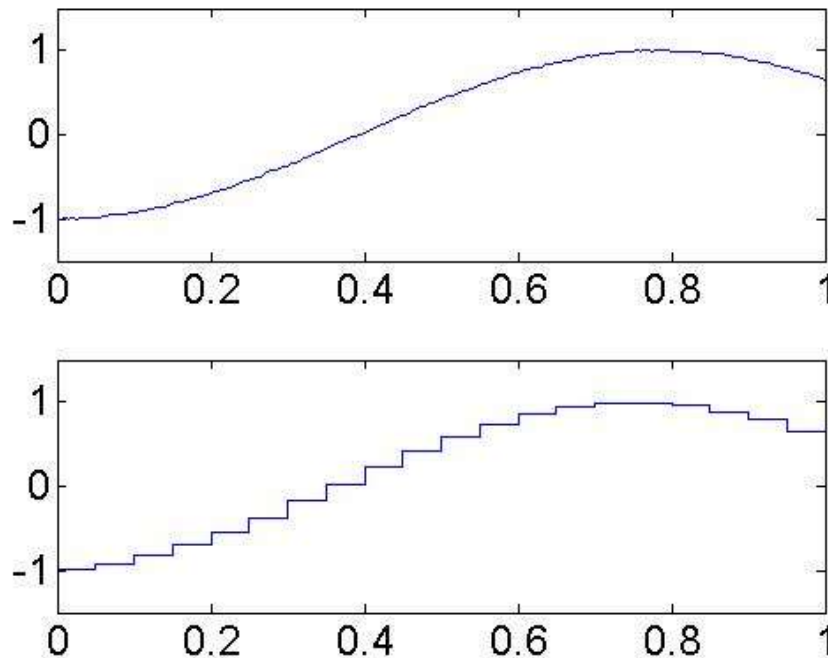
Master 2 – Fluid Mechanics –

Sampling

Quantification

Acquisition

## Quantification (analog- digital)



### Quantification noise:

Signal to noise ratio due to quantification

Nb bits	8	12	16
S/B	53 dB	77 dB	110 dB

Quantification level:  $n$  bits

Signal dynamics:  $\pm V_{max}$

No quantification:  $\delta V = \frac{2V_{max}}{2^n}$

Error spanned uniformly on:  $-\delta V/2 < e(n) < \delta V/2$

Noise power:

$$\sigma_e^2 = \int_{-\delta V/2}^{\delta V/2} e^2 \frac{1}{\delta V} = \frac{\delta V^2}{12} = \frac{V_{max}^2 2^{-2n}}{3}$$

## Acquisition

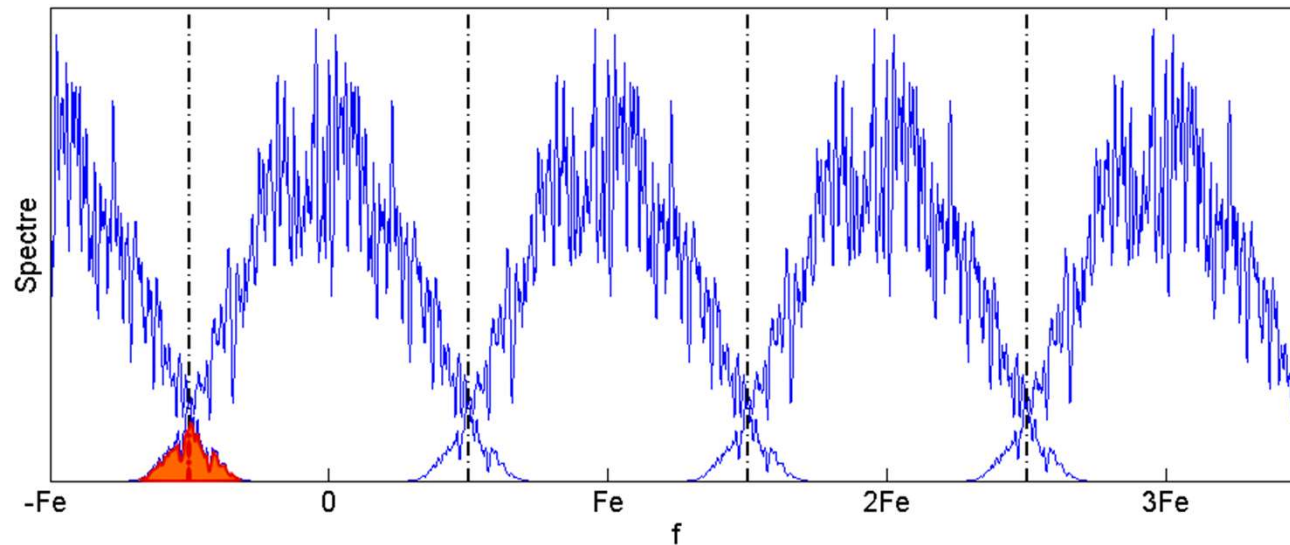
Irreversible action (cf. filtering)

Data flux:

- data quantity vs band width
- writing speed
- memory (RAM)



## Filtering



Low pass  
High pass  
Band pass

To respect Shannon criterion

To limit data volume

To reduce noise level

Sensor

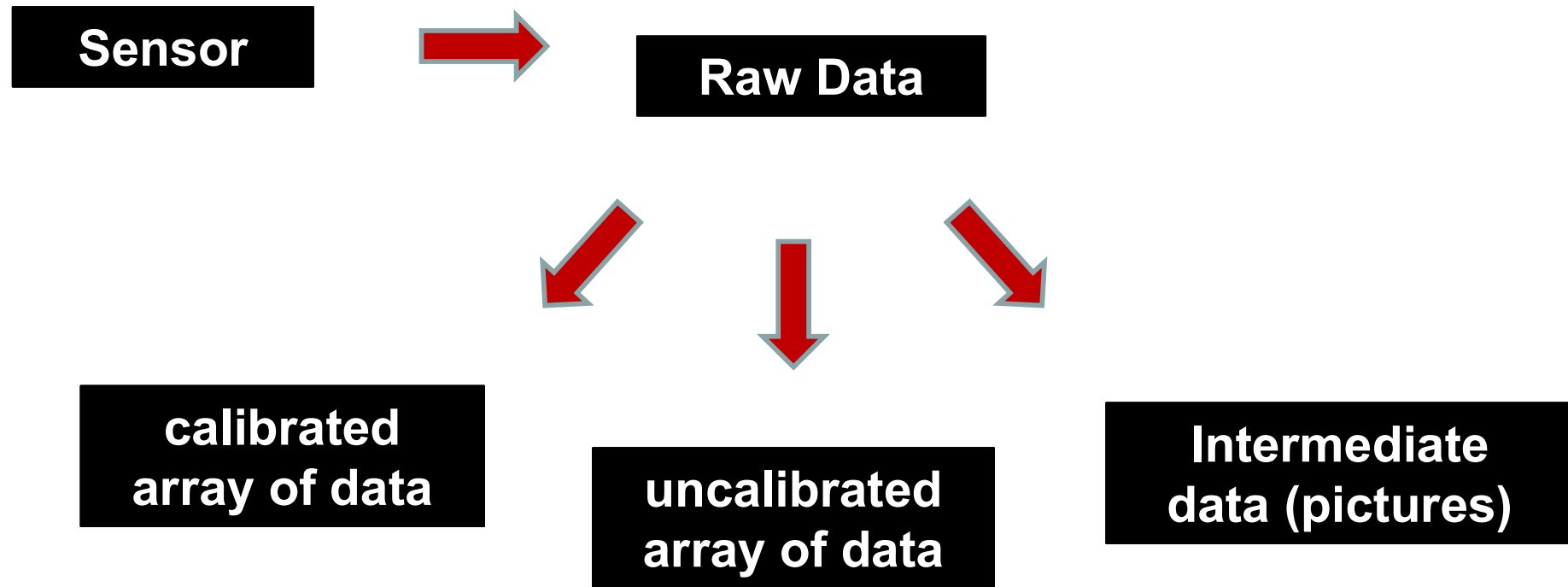
Filtering

Master 2 – Fluid Mechanics –

Sampling

Quantification

Acquisition



## Wish list

- accessible
- portable
- understandable
- long-life
- space saving
- ...

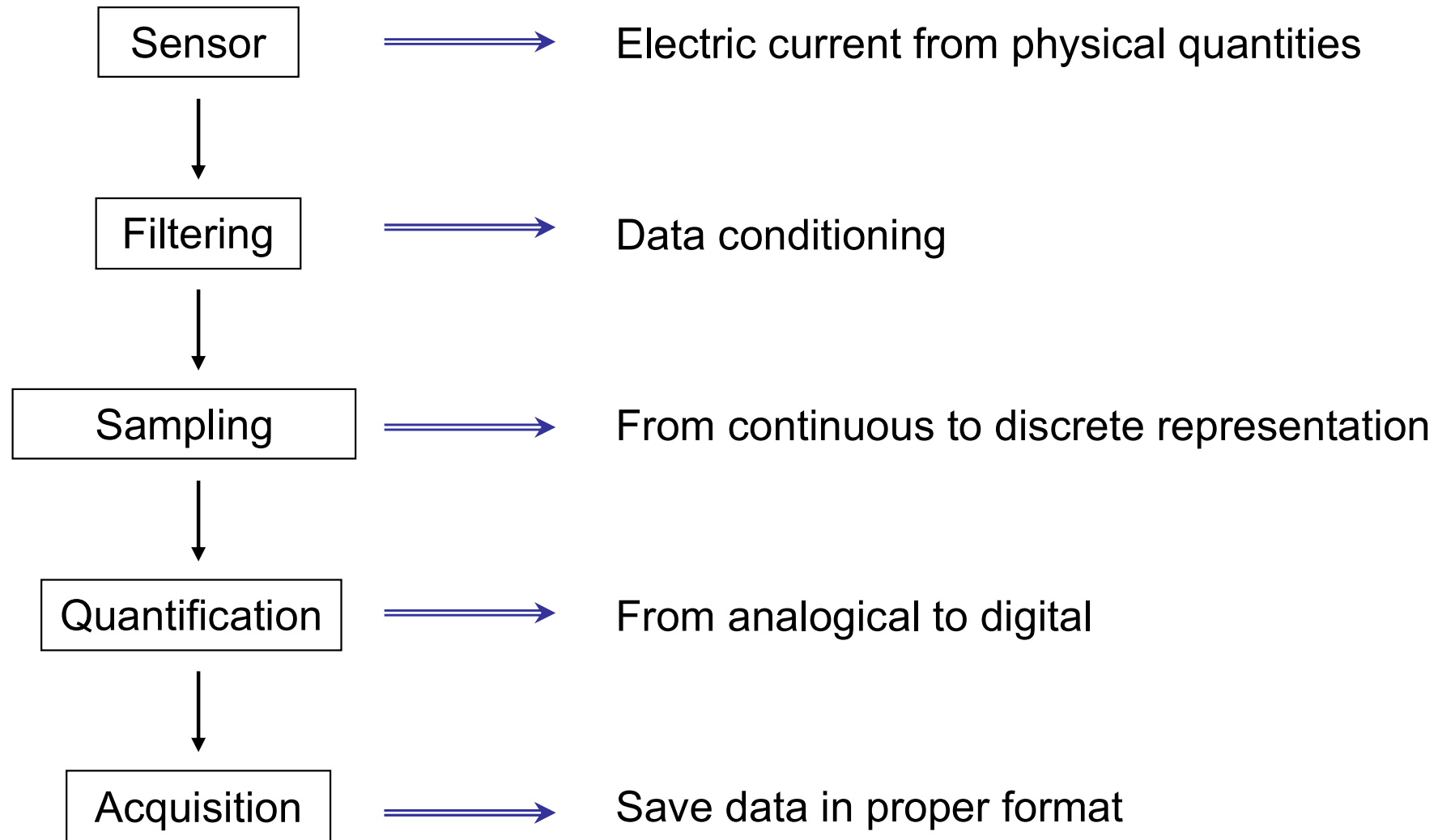
## Data representation

- Text files (.csv, .txt, ...)
- Binary files
- Proprietary formats
- .hdf5 or equivalent
- ...

## Data location

- on computer
- on hard drive
- on servers
- on cloud
- ...

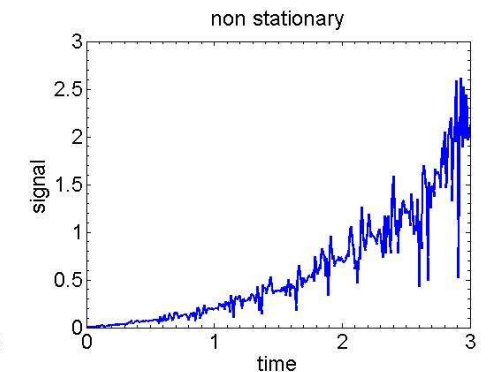
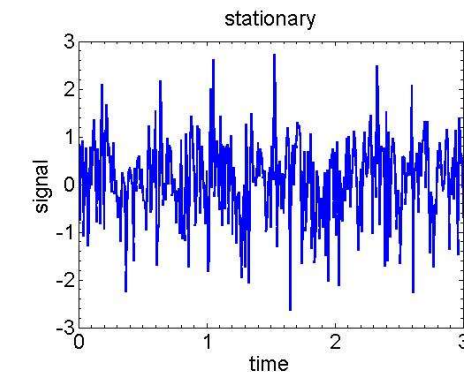
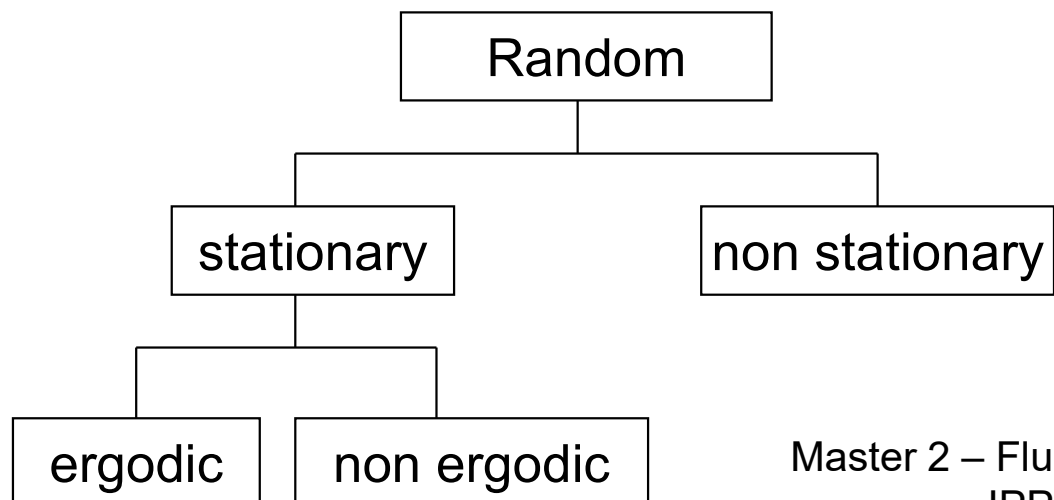
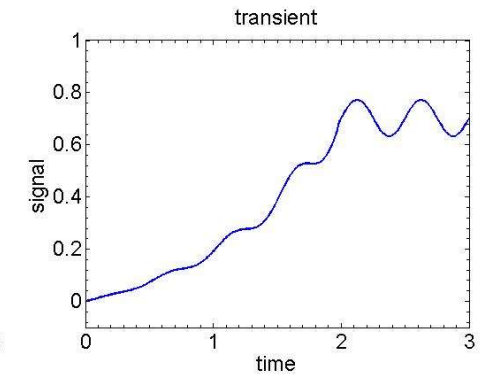
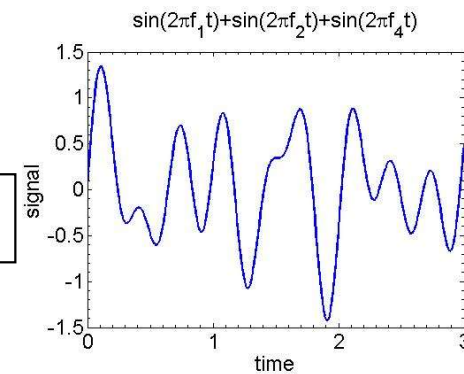
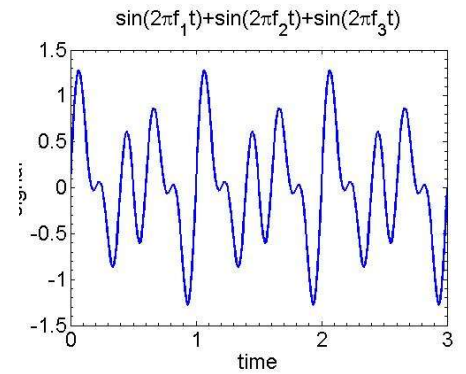
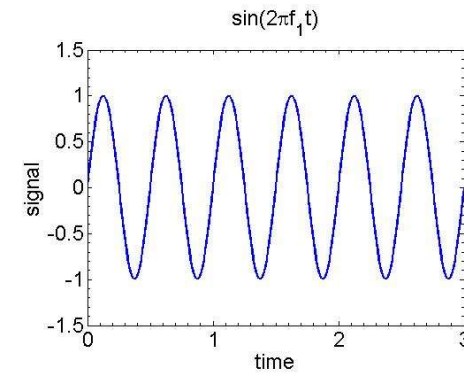
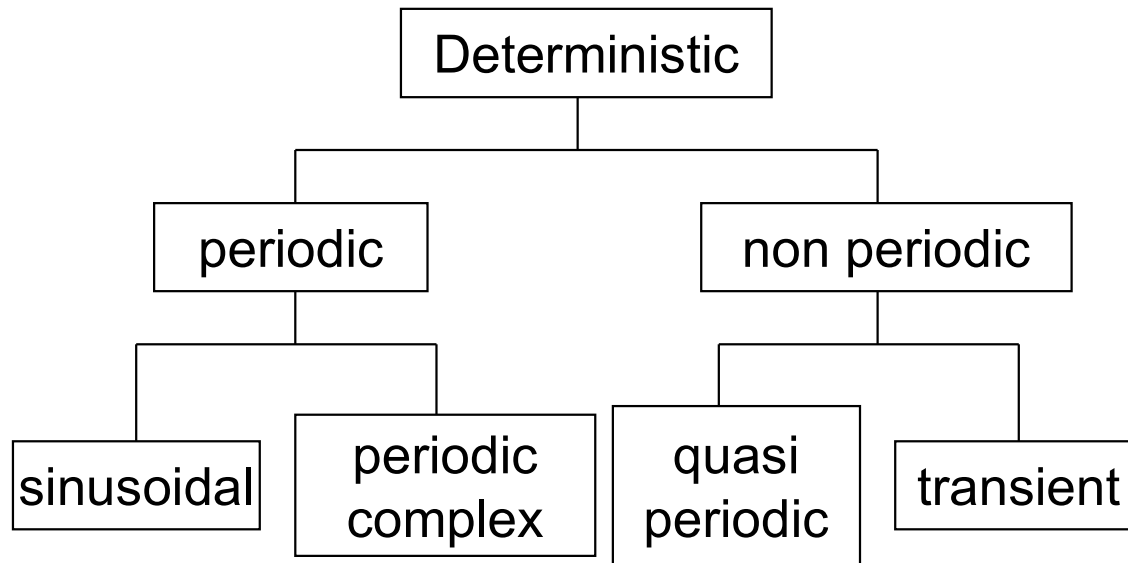
# Signal processing: acquisition chain



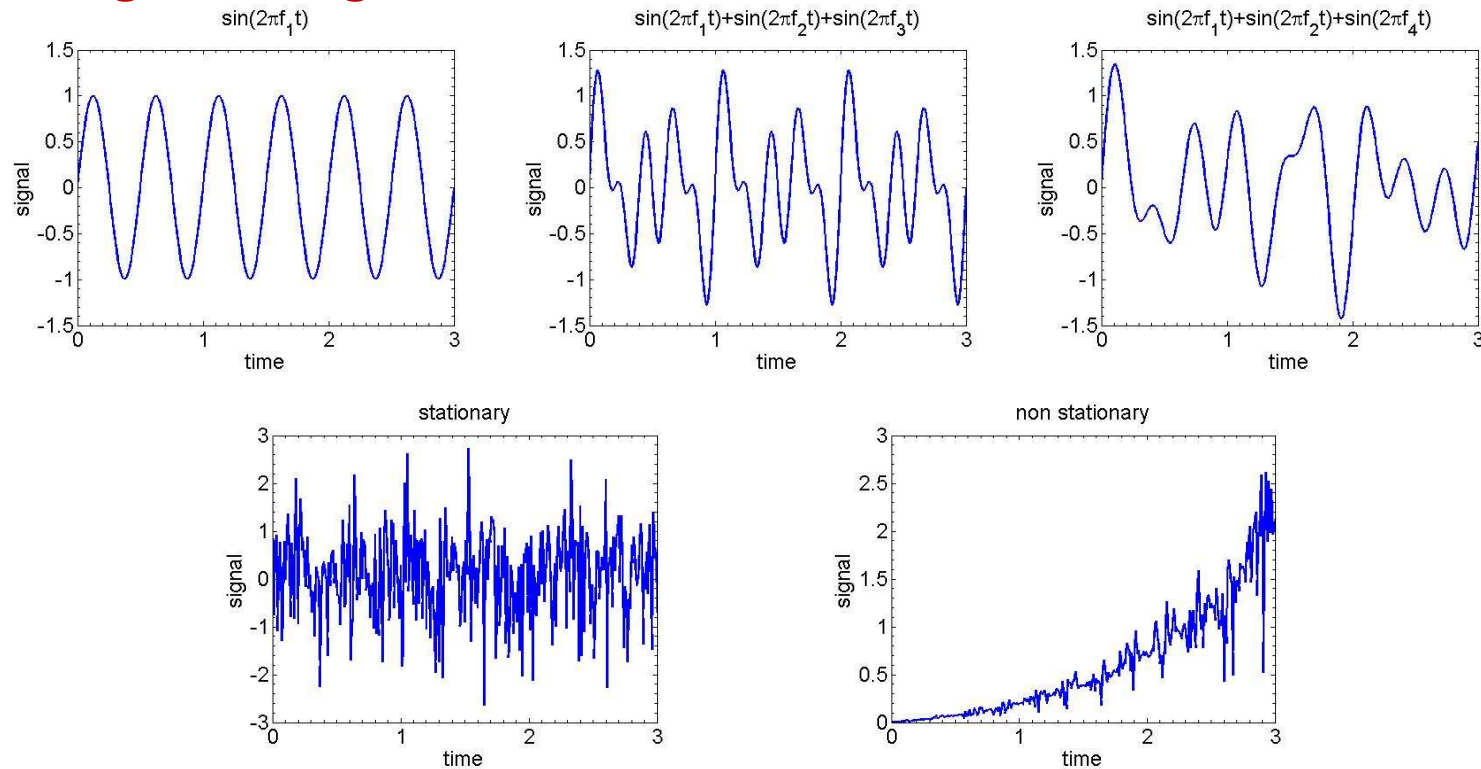
**Time to analyse these signals**



## Deterministic vs random signals



## Post-processing challenges



### Statistical quantities:

- mean, standard deviation
- correlations

### Probability densities:

- fluctuation asymmetry
- complex effect identification

### Spectral content:

- rich informations (see practical session)

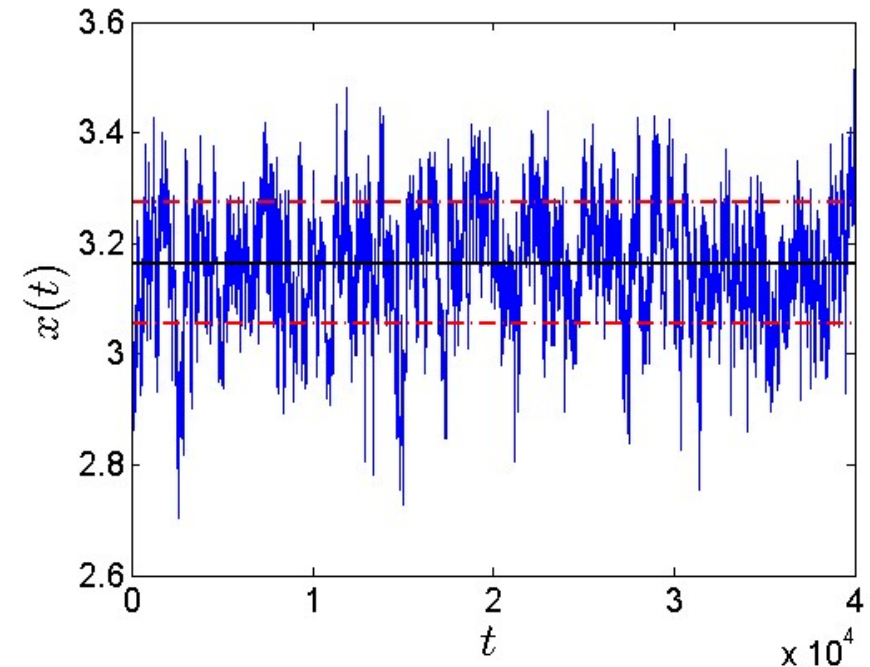
### Drifts:

- in space or time
- data quality, non trivial long time effects

## Mean and standard deviation

$$\bar{p} = \frac{1}{M} \sum_{n=0}^{M-1} p[n]$$

$$p_{rms} = \left( \frac{1}{M-1} \sum_{n=0}^{M-1} (p[n] - \bar{p})^2 \right)^{1/2}$$



### Standard deviation:

- careful to estimation bias!
- fluctuation measurement
- distribution width
- data dispersion
- empirical error bars

### Steady signal:

- obvious meaning

### Unsteady signal:

- meaningless quantities
- moving moment estimation

## Averages:

**Ensemble average :**  $\langle T(\vec{x}, t) \rangle = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N T_i(\vec{x}, t)$

N times the same experiment

Average on realisations

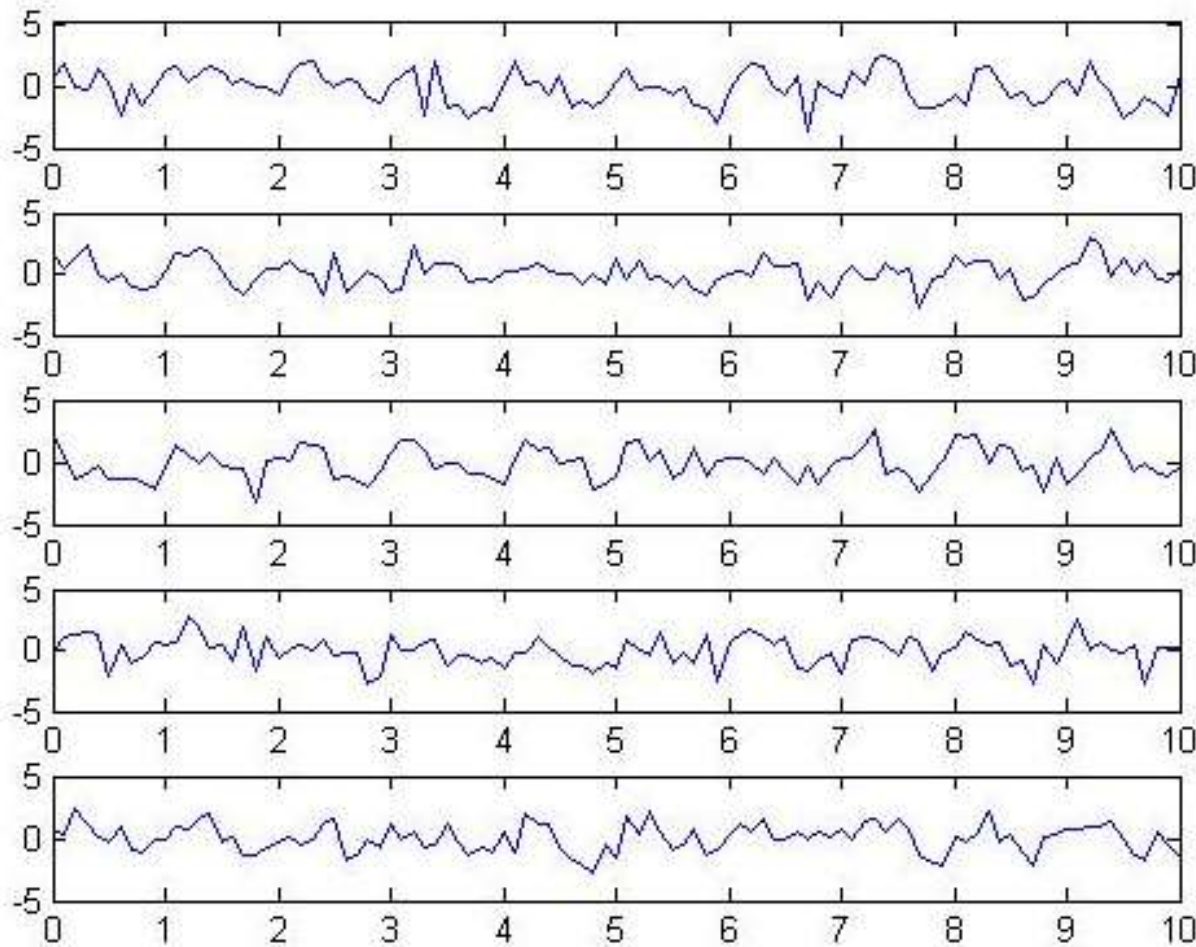
**Time average :**  $\overline{T}_a(\vec{x}, t) = \frac{1}{2a} \int_{-a}^a T(\vec{x}, t + s) ds$

$$\overline{T}(\vec{x}) = \lim_{a \rightarrow \infty} \overline{T}_a(\vec{x}, t)$$

**Ergodicity if both are identical**

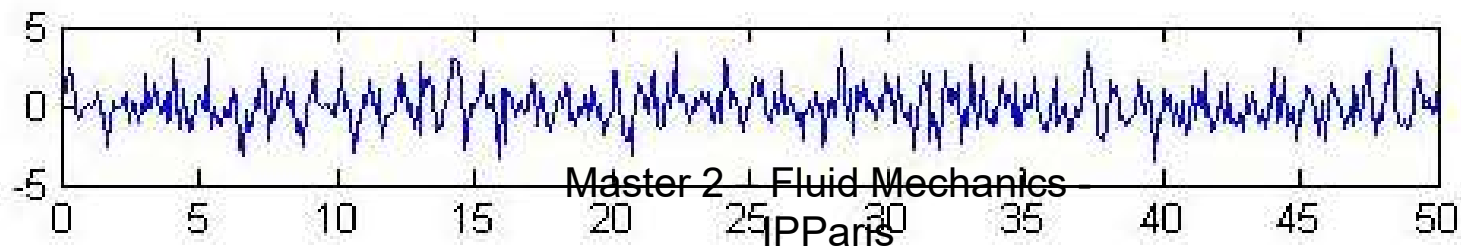
# Signal processing: post-processing chain

## Averages:



5 realisations  
over 10 time units

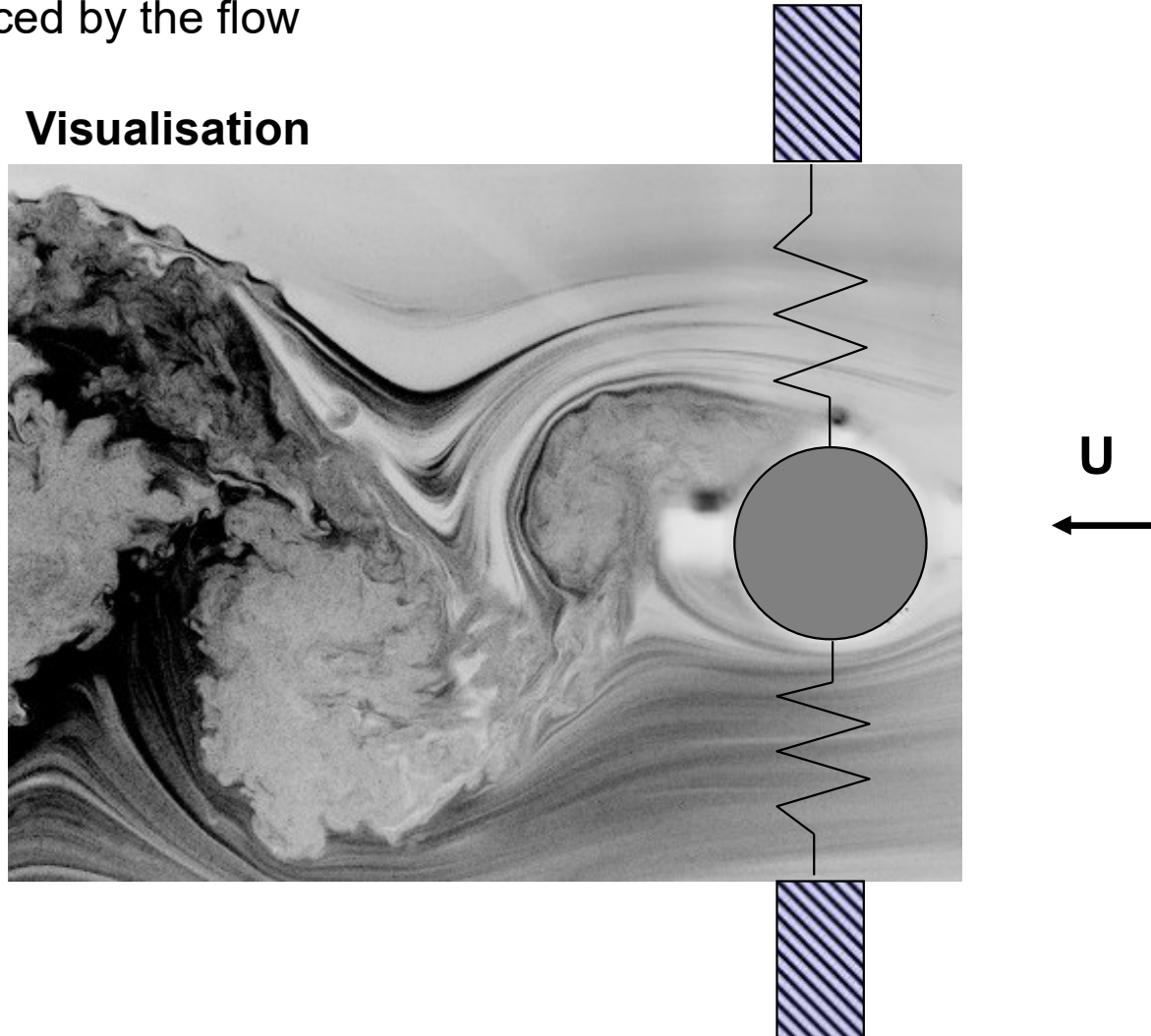
1 realisation over 50 time units



## Time and ensemble averages :

Cylinder wake with oscillations  
forced by the flow

**Visualisation**

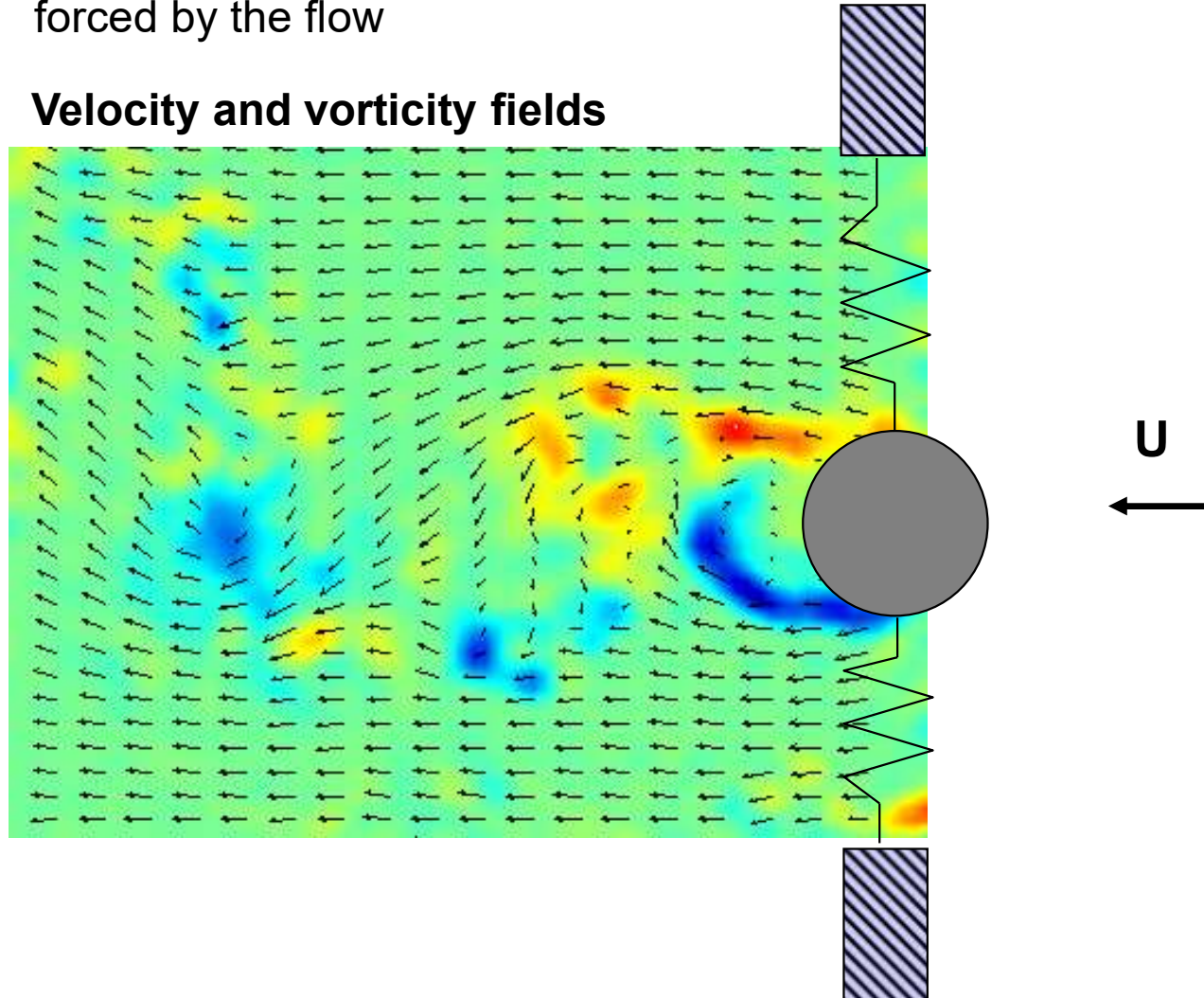




## Time and ensemble averages :

Cylinder wake with oscillations  
forced by the flow

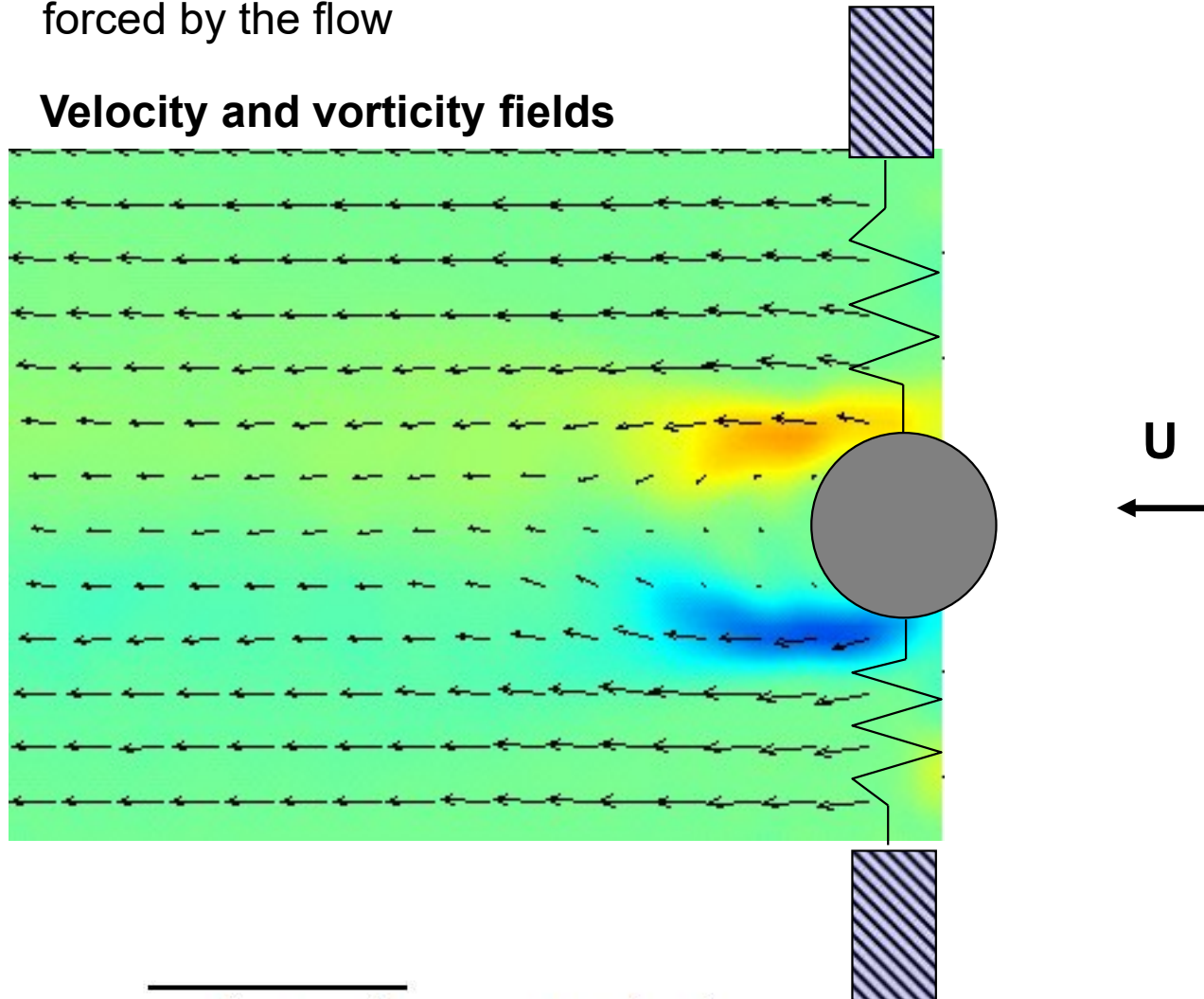
**Velocity and vorticity fields**



## Time and ensemble averages :

Cylinder wake with oscillations  
forced by the flow

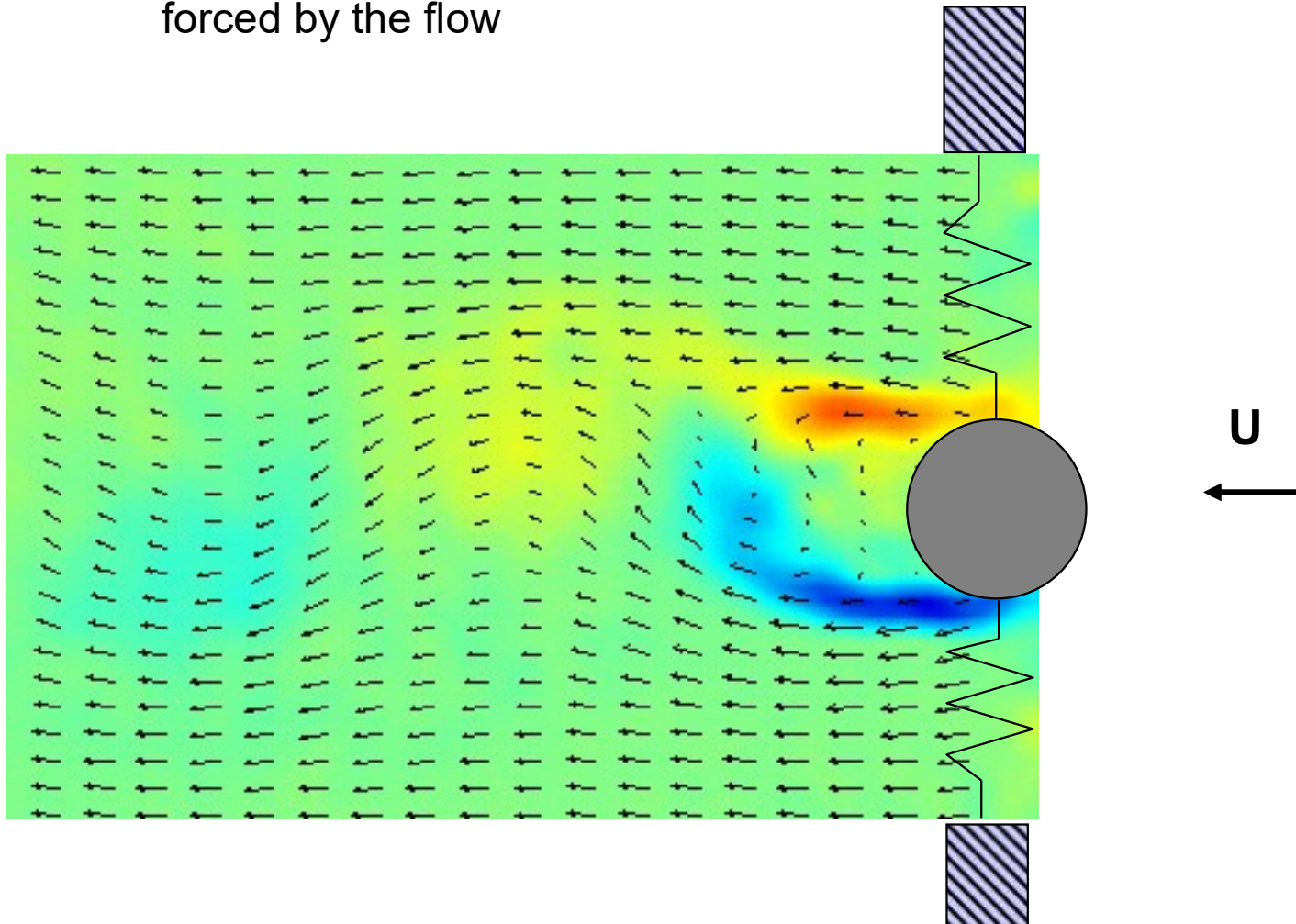
Velocity and vorticity fields



Time average :  $\overline{u(\vec{x}, t)} = U(\vec{x})$

## Time and ensemble averages :

Cylinder wake with oscillations  
forced by the flow



Ensemble average :

$$\overline{u(\vec{x}, t_1)} \quad \text{Master 2 - Fluid Mechanics - IPParis}$$

## Probability density function

Cumulated probability:

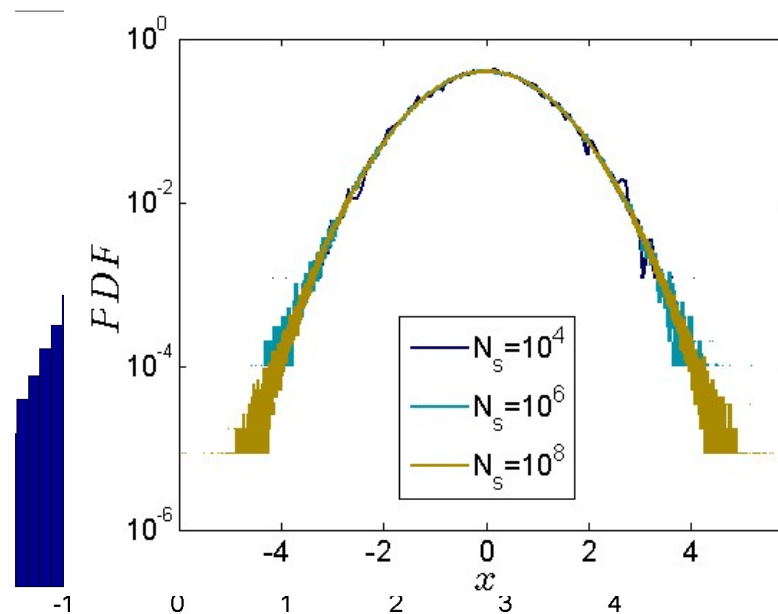
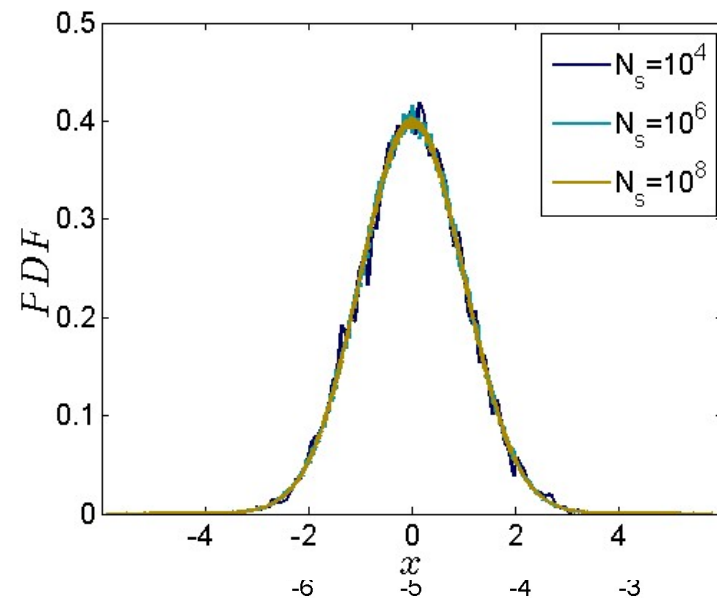
$$\mathcal{F}(x) = P(X < x)$$

Probability density function:

$$f(x) = \frac{d\mathcal{F}}{dx}$$

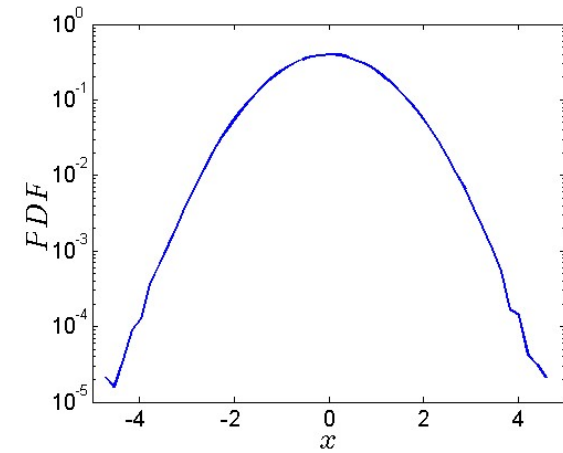
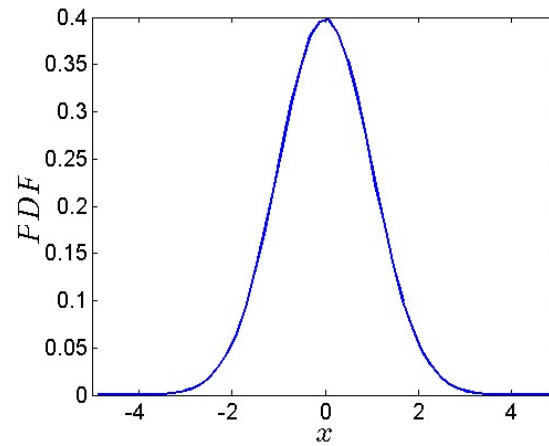
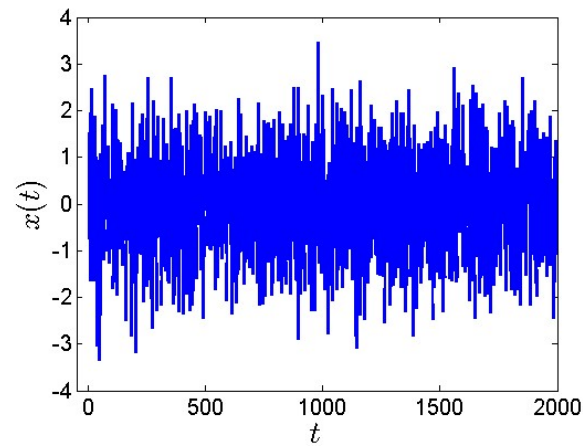
## Practically:

- histogram estimation
- histogram normalisation

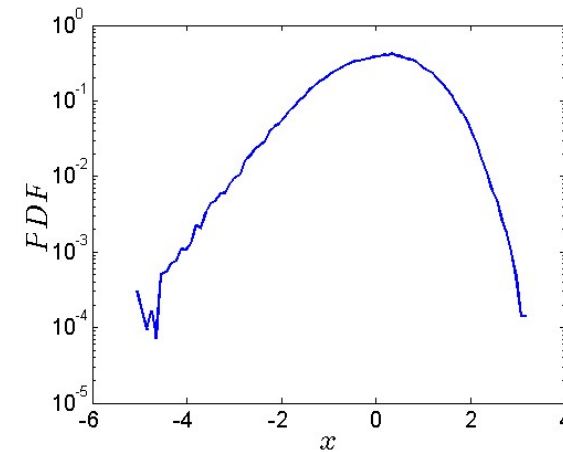
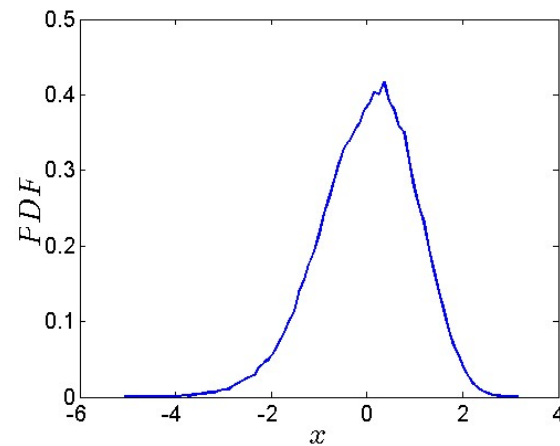
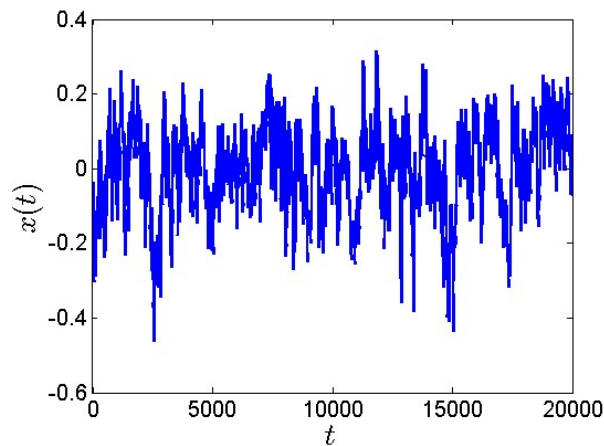


## Probability density

### Gaussian white noise



### Turbulent jet





## Power spectrum (definition)

### Fourier transform (continuous signals)

$$X(f) = \langle x, e^{2\pi j f t} \rangle = \int_{-\infty}^{+\infty} x(\tau) e^{-2\pi j f \tau} d\tau$$
$$x(t) = \int_{-\infty}^{+\infty} X(f) e^{2\pi j f \tau} df$$

### Fourier transform (discrete signals)

$$X(\lambda) = \sum_{n=-\infty}^{+\infty} x[n] e^{-2j\pi\lambda n}, \quad \lambda \in [-0.5, 0.5]$$
$$x[n] = \int_{-0.5}^{0.5} X(\lambda) e^{2j\pi\lambda n} d\lambda$$



## Power spectrum (definition)

### Energy vs. power

$$P(x) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{+T/2} |x(t)|^2 dt. \quad (\text{infinite signals})$$

$$E(x) = \int_{-\infty}^{+\infty} |x(t)|^2 dt. \quad (\text{finite signals})$$

### Parseval theorem

$$E(x) = \int_{-\infty}^{+\infty} |x(t)|^2 dt = \int_{-\infty}^{+\infty} |X(f)|^2 df$$

 **Energy can be measured  
in spectral or physical space**

## Power spectrum (practical calculation)

**Mean periodogram:**

$$\text{PSD}_x(f) = \frac{1}{M} \sum_{i=0}^M |X_i(f)|^2$$



with  $X_i(f) = FFT[f(n)x(n + iP)]$

**Required:**

- segment number
- segment length
- windowing

**Correlogram:**

$$\text{PSD}_x(f) = \int_{-\infty}^{\infty} R_{xx}(t) dt$$



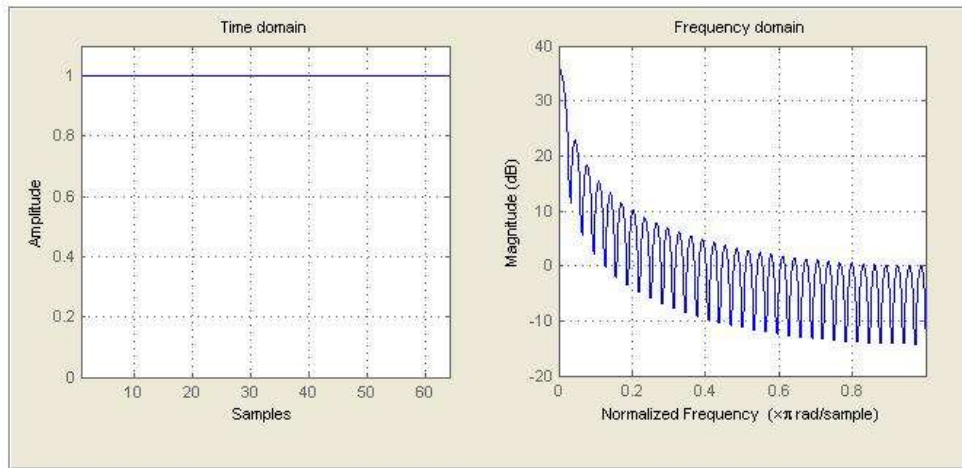
**Required:**

- autocorrélation estimation
- Fourier transform calculation

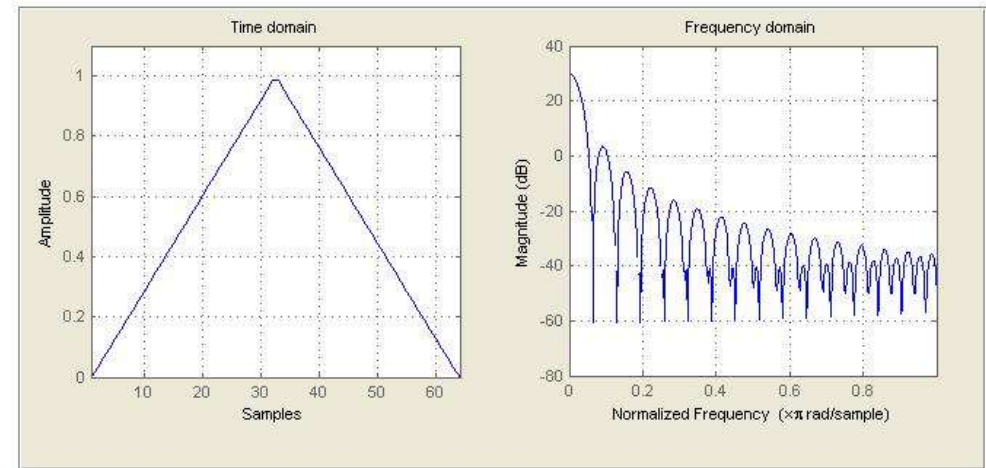
Wiener-Khintchine formula

## Power spectrum (windows)

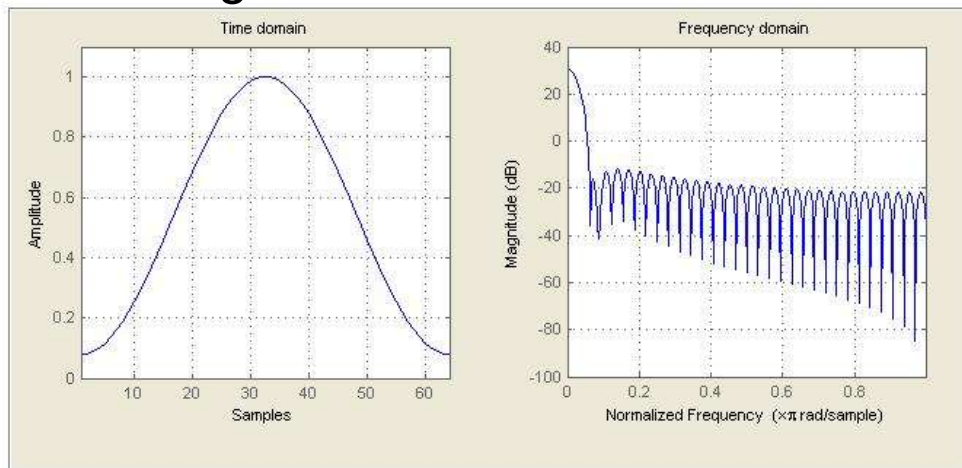
### Rectangle



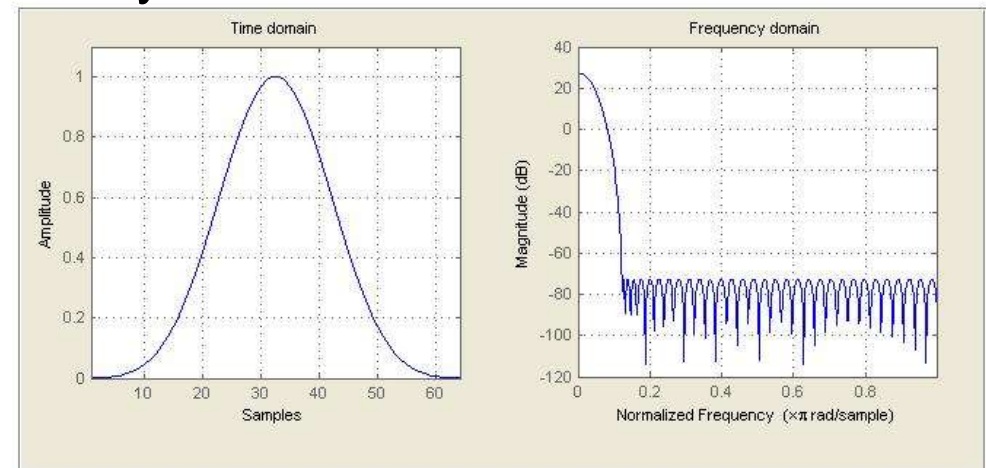
### Bartlet



### Hamming



### Chebyshev



➡ No ideal choice  
Case to case decision  
Master 2 – Fluid Mechanics  
IPParis

## Correlations

$$R_x(\tau) = \overline{x(t)x(t + \tau)}$$

$$R_f(\tau) = \int_{-\infty}^{+\infty} f(t)f(t - \tau)dt$$

Auto-correlation

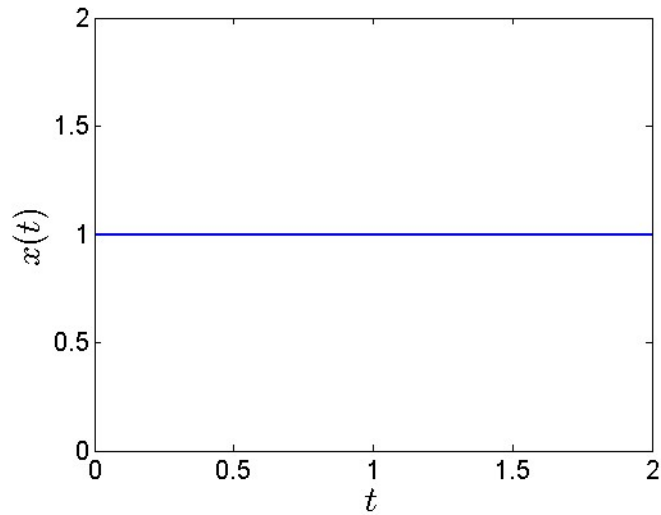
$$R_{xy}(\tau) = \overline{x(t)y(t + \tau)}$$

$$R_{fg}(\tau) = \int_{-\infty}^{+\infty} f(t)g(t - \tau)dt$$

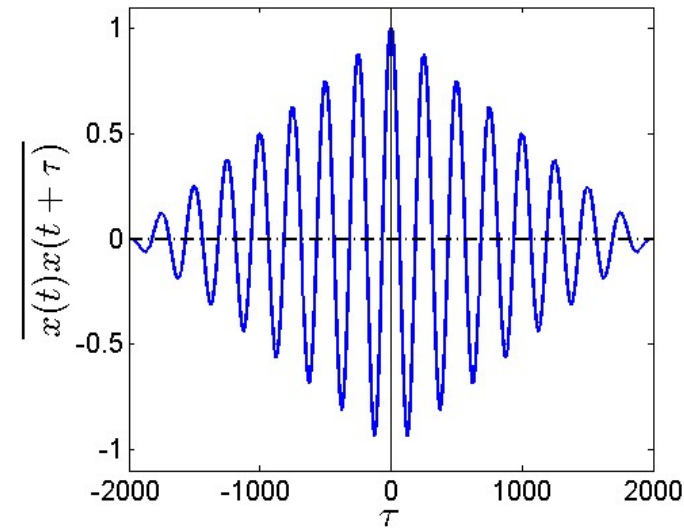
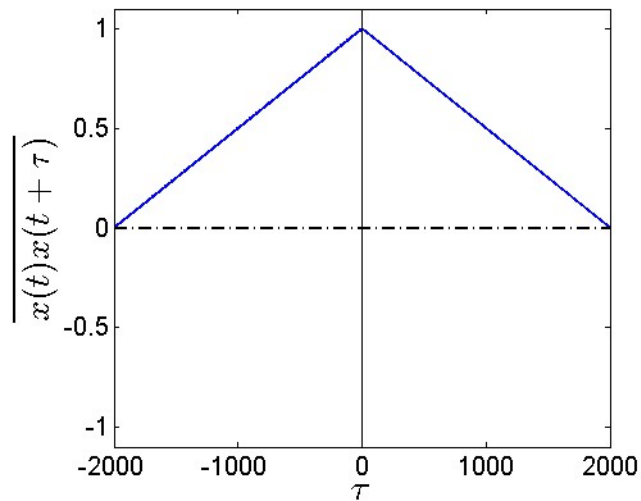
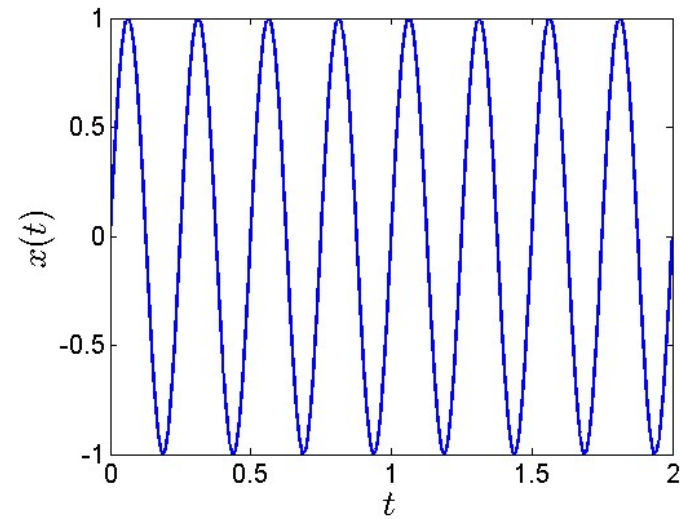
Cross-correlation

## Correlations

Constant



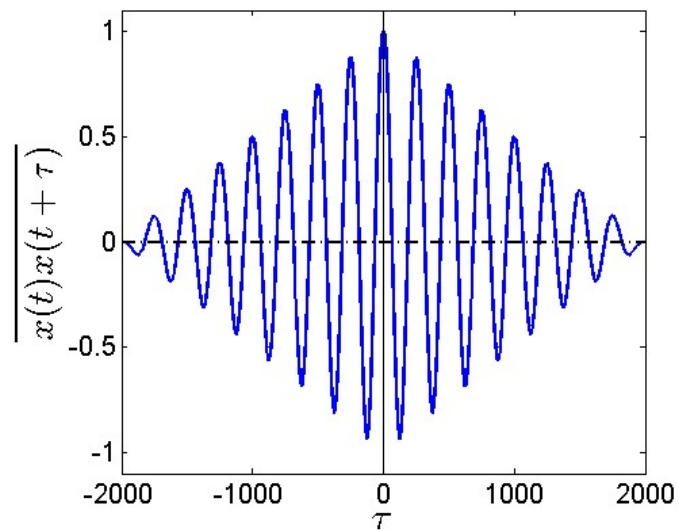
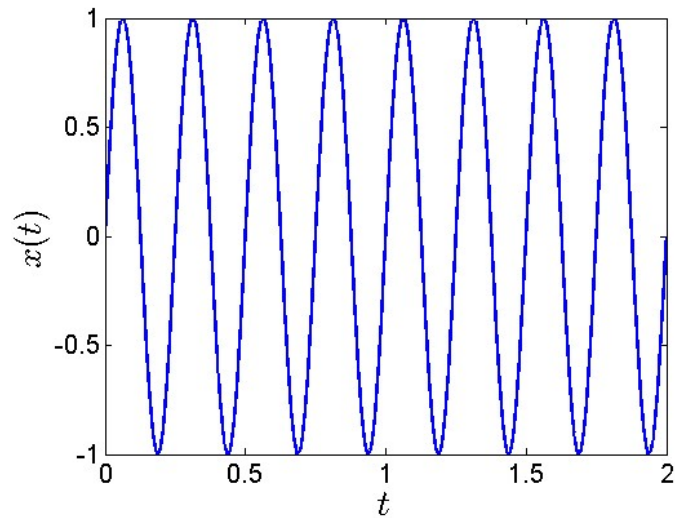
Sinusoid



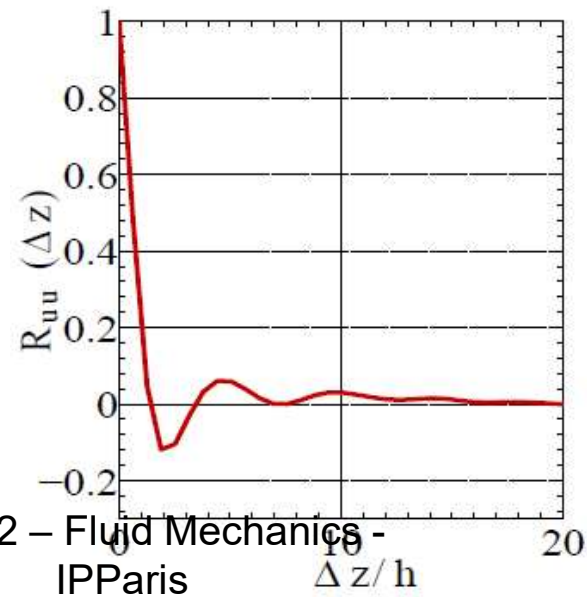
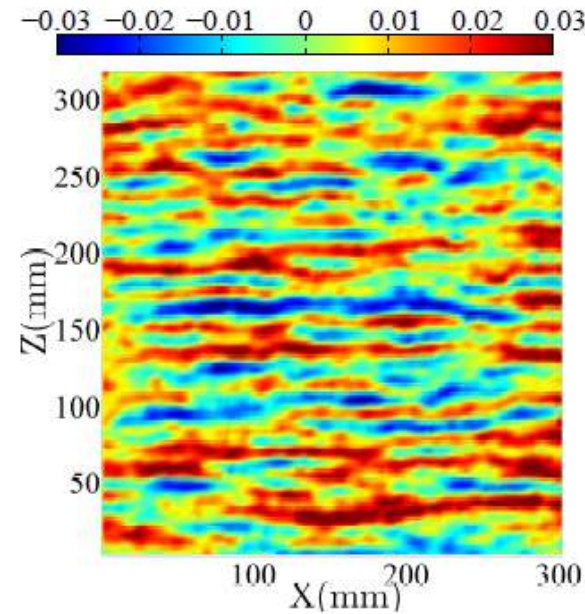
**Soustrait mean value!**

## Correlations

Sinusoid



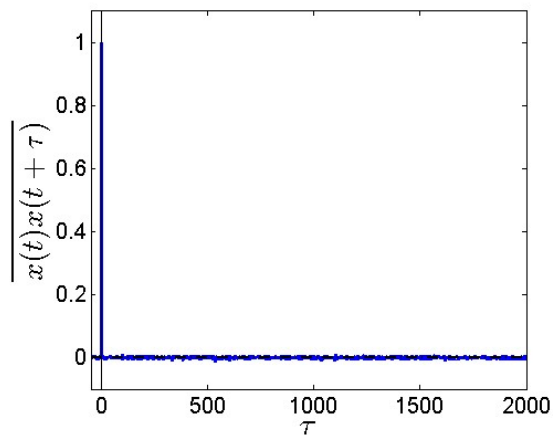
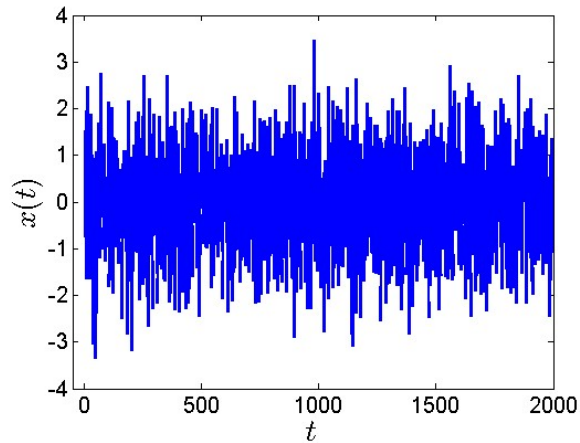
Plane Couette velocity



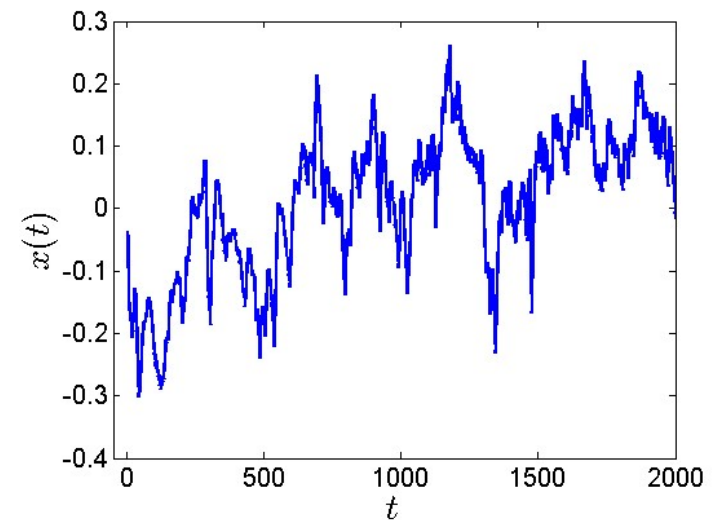
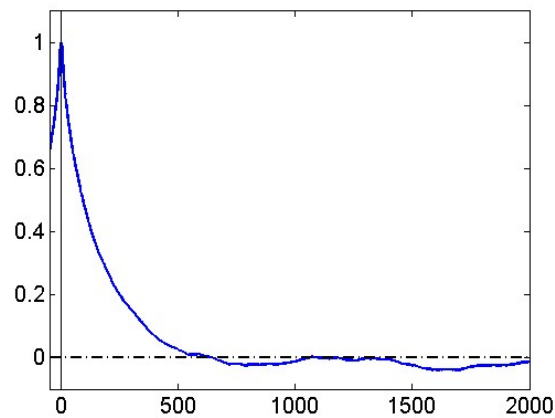
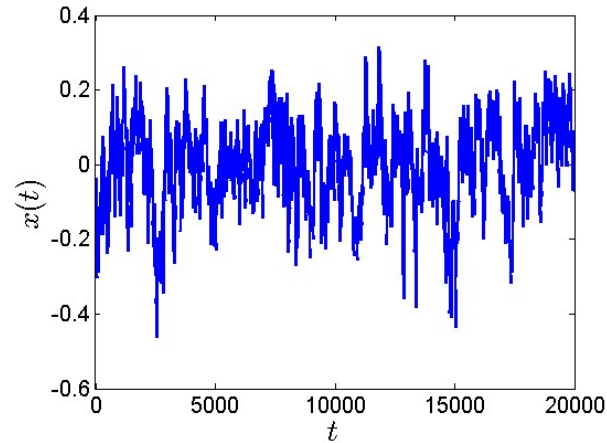


## Correlations

Gaussian white noise



Turbulent jet



⇒ **Be careful for statistical estimations**