## T-coercivity: a practical tool for the study of variational formulations

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#### 1 What is T-coercivity?

## 2 Stokes model

③ Neutron diffusion model

4 Neutron diffusion model with Domain Decomposition

#### 5 Further remarks

- First, analyse the variational formulation theoretically:
  - prove well-posedness;
  - existence, uniqueness and continuous dependence of the solution with respect to the data.

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- **2** Second, solve the variational formulation numerically:
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  - prove convergence.

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  - prove well-posedness;
  - existence, uniqueness and continuous dependence of the solution with respect to the data.
- **2** Second, solve the variational formulation numerically:
  - find suitable approximations;
  - prove convergence.

Within the framework of T-coercivity, steps 1 and 2 are very strongly correlated!

- V, W be Hilbert spaces;
- $a(\cdot, \cdot)$  be a continuous sesquilinear form on  $V \times W$ ;
- f be an element of W', the dual space of W.

Solve

(VF) Find  $u \in V$  s.t.  $\forall w \in W$ ,  $a(u, w) = {}_{W'}\langle f, w \rangle_W$ .

[Banach-Nečas-Babuška] The inf-sup condition writes

(isc) 
$$\exists \alpha > 0, \ \forall v \in V, \ \sup_{w \in W \setminus \{0\}} \frac{|a(v,w)|}{\|w\|_W} \ge \alpha \|v\|_V$$

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 s.t.  $\forall w \in W$ ,  $a(u, w) = {}_{W'}\langle f, w \rangle_W$ .

#### Definition (T-coercivity)

The form  $a(\cdot, \cdot)$  is T-coercive if

 $\exists \mathsf{T} \in \mathcal{L}(V, W) \text{ bijective, } \exists \underline{\alpha} > 0, \forall v \in V, |a(v, \mathsf{T}v)| \ge \underline{\alpha} \|v\|_V^2.$ 

NB. In other words, the form  $a(\cdot, \mathbf{T} \cdot)$  is coercive on  $V \times V$ .

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 s.t.  $\forall w \in W$ ,  $a(u, w) = {}_{W'}\langle f, w \rangle_W$ .

#### Theorem (Well-posedness)

The three assertions below are equivalent:

- (i) the Problem (VF) is well-posed;
- (ii) the form  $a(\cdot, \cdot)$  satisfies (isc) and  $\{w \in W \mid \forall v \in V, a(v, w) = 0\} = \{0\}$ ;
- (iii) the form  $a(\cdot, \cdot)$  is T-coercive.

The operator T realises the inf-sup condition (isc) explicitly: w = Tu works!

- $\bullet~V$  be a Hilbert space;
- $a(\cdot, \cdot)$  be a continuous, sesquilinear, *hermitian* form on  $V \times V$ ;
- f be an element of V', the dual space of V.

Solve

(VF) Find 
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 s.t.  $\forall w \in V$ ,  $a(u, w) = {}_{V'}\langle f, w \rangle_V$ .

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Definition (T-coercivity, hermitian case)

The form  $a(\cdot, \cdot)$  is T-coercive if

 $\exists \mathsf{T} \in \mathcal{L}(V), \ \exists \underline{\alpha} > 0, \ \forall v \in V, \ |a(v, \mathsf{T}v)| \ge \underline{\alpha} \, \|v\|_V^2.$ 

- V be a Hilbert space;
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Solve

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(VF) Find u \in V s.t. \forall w \in V, a(u, w) = {}_{V'}\langle f, w \rangle_V.
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#### Theorem (Well-posedness, hermitian case)

The three assertions below are equivalent:

- (i) the Problem (VF) is well-posed;
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- (iii) the form  $a(\cdot, \cdot)$  is T-coercive.

The operator T realises the inf-sup condition (isc) explicitly.

- $(V_{\delta})_{\delta}$  be a family of finite dimensional subspaces of V ;
- $(W_{\delta})_{\delta}$  be a family of finite dimensional subspaces of W.

Assume that  $\dim(V_{\delta}) = \dim(W_{\delta})$  for all  $\delta > 0$ . Solve

 $(VF)_{\delta}$  Find  $u_{\delta} \in V_{\delta}$  s.t.  $\forall w_{\delta} \in W_{\delta}, a(u_{\delta}, w_{\delta}) = {}_{W'}\langle f, w_{\delta} \rangle_{W}.$ 

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[Banach-Nečas-Babuška] The uniform discrete inf-sup condition writes

$$(\mathsf{udisc}) \quad \exists \alpha_{\dagger} > 0, \ \forall \delta > 0, \ \forall v_{\delta} \in V_{\delta}, \ \sup_{w_{\delta} \in W_{\delta} \setminus \{0\}} \frac{|a(v_{\delta}, w_{\delta})|}{\|w_{\delta}\|_{W}} \ge \alpha_{\dagger} \|v_{\delta}\|_{V}.$$

NB. When (udisc) is fulfilled,  $(VF)_{\delta}$  is well-posed for all  $\delta > 0$ .

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#### Definition (uniform $T_{\delta}$ -coercivity)

The form a is uniformly  $T_{\delta}$ -coercive if

 $\exists \underline{\alpha}_{\dagger}, \underline{\beta}_{\dagger} > 0, \ \forall \delta > 0, \ \exists \mathsf{T}_{\delta} \in \mathcal{L}(V_{\delta}, W_{\delta}), \ \||\mathsf{T}_{\delta}\|| \leq \underline{\beta}_{\dagger} \text{ and } \forall v_{\delta} \in V_{\delta}, \ |a(v_{\delta}, \mathsf{T}_{\delta}v_{\delta})| \geq \underline{\alpha}_{\dagger} \|v_{\delta}\|_{V}^{2}.$ 

NB. When a is uniformly  $T_{\delta}$ -coercive,  $(VF)_{\delta}$  is well-posed for all  $\delta > 0$ .

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 Find  $u_{\delta} \in V_{\delta}$  s.t.  $\forall w_{\delta} \in W_{\delta}, a(u_{\delta}, w_{\delta}) = {}_{W'}\langle f, w_{\delta} \rangle_{W}.$ 

#### Theorem (Céa's lemma)

Assume that the family  $(V_{\delta})_{\delta}$  fulfills the basic approximability property in V. In addition, assume that

- (i) either, the form  $a(\cdot, \cdot)$  satisfies (udisc);
- (ii) or, the form  $a(\cdot, \cdot)$  is uniformly  $T_{\delta}$ -coercive.

Then,  $\lim_{\delta \to 0} \|u - u_{\delta}\|_{V} = 0.$ 

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 Find  $u_{\delta} \in V_{\delta}$  s.t.  $\forall w_{\delta} \in W_{\delta}, a(u_{\delta}, w_{\delta}) = {}_{W'}\langle f, w_{\delta} \rangle_{W}.$ 

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Assume that the family  $(V_{\delta})_{\delta}$  fulfills the basic approximability property in V. In addition, assume that

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- (ii) or, the form  $a(\cdot, \cdot)$  is uniformly  $T_{\delta}$ -coercive.

Then,  $\lim_{\delta \to 0} \|u - u_{\delta}\|_{V} = 0$ . And error estimates whenever possible...



<sup>†</sup> = Abstract T-coercivity only.

#### Ocercive plus compact formulations. See for instance:

- integral equations: Buffa-Costabel-Schwab'02 [Θ-coercivity]; Buffa-Christiansen'03; Buffa-Christiansen'05; Buffa'05; Unger'21; Levadoux (2022, HAL report) [τ-coercivity].
- volume equations: Hiptmair'02 ["(X + S)-coercivity"]; Buffa'05; PC'12 ["elementary" proofs]; Hohage-Nannen'15 [S-coercivity]; Sayas-Brown-Hassell (2019)<sup>†</sup>; Halla'21a ["generalized" proofs].

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- for scalar models: BonnetBenDhia-PC-Zwölf'10; Nicaise-Venel'11; BonnetBenDhia-Chesnel-PC'12<sup>†</sup>; Chesnel-PC'13; Bunoiu-Ramdani'16<sup>†</sup>; Carvalho-Chesnel-PC'17; BonnetBenDhia-Carvalho-PC'18; Bunoiu-Ramdani-Timofte'21-'22<sup>†</sup>.
- for EM models: BonnetBenDhia-Chesnel-PC'14<sup>†</sup> (2D-3D); Halla'21b (2D); PC'22 (3D).

#### Mixed formulations.

- for the Stokes model: see below!
- for diffusion models: Jamelot-PC'13, see below!
- for the magnetic quasi-static model: Barré-PC (2022, HAL report).

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#### **Or Coercive plus compact formulations.** See for instance:

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NeutronDiffusion

**1** Let  $\Omega$  be a domain of  $\mathbb{R}^3$ . The "simplest" Stokes equations write

$$\begin{cases} -\nu \Delta \boldsymbol{u} + \nabla p = \boldsymbol{f} \text{ in } \Omega \\ \operatorname{div} \boldsymbol{u} = g \text{ in } \Omega \\ \boldsymbol{u} = 0 \text{ on } \partial \Omega, \end{cases}$$

for some  $\nu > 0$  (viscosity). For "classical" Stokes, g = 0.

• Assuming that  $f \in (H_0^1(\Omega))'$  and  $g \in L^2_{zmv}(\Omega)$ , one analyses mathematically the model

$$\begin{array}{l} \mbox{(Stokes)} \qquad \left\{ \begin{array}{l} \mbox{Find } (\boldsymbol{u},p) \in \boldsymbol{H}_0^1(\Omega) \times L^2_{zmv}(\Omega) \mbox{ such that} \\ -\nu \, \Delta \boldsymbol{u} + \nabla p = \boldsymbol{f} \mbox{ in } \Omega \\ \mbox{div } \boldsymbol{u} = g \mbox{ in } \Omega. \end{array} \right. \end{array}$$

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(Stokes) 
$$\begin{cases} \mathsf{Find} \ (\boldsymbol{u}, p) \in \boldsymbol{H}_0^1(\Omega) \times L^2_{zmv}(\Omega) \text{ such that} \\ -\nu \, \Delta \boldsymbol{u} + \nabla p = \boldsymbol{f} \text{ in } \Omega \\ \operatorname{div} \boldsymbol{u} = g \text{ in } \Omega. \end{cases}$$

Interpretation of the equivalent variational formulation writes

$$(\mathsf{FV}\text{-}\mathsf{Stokes}) \left\{ \begin{array}{l} \mathsf{Find} \ (\boldsymbol{u},p) \in \boldsymbol{H}_0^1(\Omega) \times L^2_{zmv}(\Omega) \text{ such that} \\ \forall (\boldsymbol{v},q) \in \boldsymbol{H}_0^1(\Omega) \times L^2_{zmv}(\Omega), \quad \nu \int_{\Omega} \boldsymbol{\nabla} \boldsymbol{u} : \boldsymbol{\nabla} \boldsymbol{v} \, d\Omega \\ - \int_{\Omega} p \operatorname{div} \boldsymbol{v} \, d\Omega - \int_{\Omega} q \operatorname{div} \boldsymbol{u} \, d\Omega = _{(\boldsymbol{H}_0^1(\Omega))'} \langle \boldsymbol{f}, \boldsymbol{v} \rangle_{\boldsymbol{H}_0^1(\Omega)} - \int_{\Omega} gq \, d\Omega. \end{array} \right.$$

**(**) Assuming that  $f \in (H_0^1(\Omega))'$  and  $g \in L^2_{zmv}(\Omega)$ , one analyses mathematically the model

(Stokes) 
$$\begin{cases} \mathsf{Find} \ (\boldsymbol{u}, p) \in \boldsymbol{H}_0^1(\Omega) \times L^2_{zmv}(\Omega) \text{ such that} \\ -\nu \, \Delta \boldsymbol{u} + \nabla p = \boldsymbol{f} \text{ in } \Omega \\ \operatorname{div} \boldsymbol{u} = g \text{ in } \Omega. \end{cases}$$

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Question: how to prove well-posedness "easily"?

• Assuming that  $f \in (H_0^1(\Omega))'$  and  $g \in L^2_{zmv}(\Omega)$ , one analyses mathematically the model (Stokes)  $\begin{cases} \operatorname{Find} (u, p) \in H_0^1(\Omega) \times L^2_{zmv}(\Omega) \text{ such that} \\ -\nu \Delta u + \nabla p = f \text{ in } \Omega \\ \operatorname{div} u = g \text{ in } \Omega. \end{cases}$ 

Interpretation of the equivalent variational formulation writes

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Question: how to prove well-posedness "easily"?

Use T-coercivity for the Stokes model!

Let

• 
$$V = H_0^1(\Omega) \times L_{zmv}^2(\Omega)$$
, endowed with the norm  $||(\boldsymbol{v}, q)||_V = (|\boldsymbol{v}|_{1,\Omega}^2 + ||q||^2)^{1/2}$ ;  
•  $a((\boldsymbol{v}, q), (\boldsymbol{w}, r)) = \nu \int_{\Omega} \nabla \boldsymbol{v} : \nabla \boldsymbol{w} \, d\Omega - \int_{\Omega} q \operatorname{div} \boldsymbol{w} \, d\Omega - \int_{\Omega} r \operatorname{div} \boldsymbol{v} \, d\Omega$ ;  
•  $_{V'}\langle f, (\boldsymbol{w}, r) \rangle_V = {}_{(\boldsymbol{H}_0^1(\Omega))'} \langle \boldsymbol{f}, \boldsymbol{w} \rangle_{\boldsymbol{H}_0^1(\Omega)} - \int_{\Omega} r \, g \, d\Omega$ .

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•  $_{V'}\langle f, (\boldsymbol{w}, r) \rangle_V = _{(\boldsymbol{H}_0^1(\Omega))'} \langle \boldsymbol{f}, \boldsymbol{w} \rangle_{\boldsymbol{H}_0^1(\Omega)} - \int_{\Omega} r \, g \, d\Omega$ .

The first goal is to prove the inf-sup condition, with the help of T-coercivity. NB. The form a is not coercive, because a((0,q), (0,q)) = 0 for  $q \in L^2_{zmv}(\Omega)$ .

Let

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The first goal is to prove the inf-sup condition, with the help of T-coercivity. Given  $(v,q) \in V \setminus \{(0,0)\}$ , we look for  $(w^*, r^*) \in V \setminus \{(0,0)\}$  with linear dependence such that

$$|a((\boldsymbol{v},q),(\boldsymbol{w}^{\star},r^{\star}))| \geq \underline{\alpha} \, \|(\boldsymbol{v},q)\|_{V}^{2},$$

with  $\underline{\alpha} > 0$  independent of  $(\boldsymbol{v}, q)$ . In other words, T is defined by  $T((\boldsymbol{v}, q)) = (\boldsymbol{w}^{\star}, r^{\star})$ .

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• 
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, endowed with the norm  $||(\boldsymbol{v}, q)||_V = (|\boldsymbol{v}|_{1,\Omega}^2 + ||q||^2)^{1/2}$ ;  
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•  $_{V'}\langle f, (\boldsymbol{w}, r) \rangle_V = _{(\boldsymbol{H}_0^1(\Omega))'} \langle \boldsymbol{f}, \boldsymbol{w} \rangle_{\boldsymbol{H}_0^1(\Omega)} - \int_{\Omega} r \, g \, d\Omega$ .

The first goal is to prove the inf-sup condition, with the help of T-coercivity. Given  $(v,q) \in V \setminus \{(0,0)\}$ , we look for  $(w^*, r^*) \in V \setminus \{(0,0)\}$  with linear dependence such that

 $|a((\boldsymbol{v},q),(\boldsymbol{w}^{\star},r^{\star}))| \geq \underline{\alpha} \, \|(\boldsymbol{v},q)\|_{V}^{2},$ 

with  $\underline{\alpha} > 0$  independent of  $(\boldsymbol{v}, q)$ . Three steps:

**1** q = 0;

- **2** v = 0;
- General case.

Recall 
$$a((\boldsymbol{v},q),(\boldsymbol{w},r)) = \nu \int_{\Omega} \nabla \boldsymbol{v} : \nabla \boldsymbol{w} \, d\Omega - \int_{\Omega} q \operatorname{div} \boldsymbol{w} \, d\Omega - \int_{\Omega} r \operatorname{div} \boldsymbol{v} \, d\Omega.$$
  
**a** $((\boldsymbol{v},0),(\boldsymbol{w},r)) = \nu \int_{\Omega} \nabla \boldsymbol{v} : \nabla \boldsymbol{w} \, d\Omega - \int_{\Omega} r \operatorname{div} \boldsymbol{v} \, d\Omega:$  so choosing  $(\boldsymbol{w}^{\star},r^{\star}) = (\boldsymbol{v},0)$  yields  
 $|a((\boldsymbol{v},0),(\boldsymbol{w}^{\star},r^{\star}))| = \nu \int_{\Omega} |\nabla \boldsymbol{v}|^2 \, d\Omega = \nu \, \|(\boldsymbol{v},0)\|_V^2.$ 

Recall 
$$a((\boldsymbol{v},q),(\boldsymbol{w},r)) = \nu \int_{\Omega} \nabla \boldsymbol{v} : \nabla \boldsymbol{w} \, d\Omega - \int_{\Omega} q \operatorname{div} \boldsymbol{w} \, d\Omega - \int_{\Omega} r \operatorname{div} \boldsymbol{v} \, d\Omega.$$
  
**a** $((\boldsymbol{v},0),(\boldsymbol{w},r)) = \nu \int_{\Omega} \nabla \boldsymbol{v} : \nabla \boldsymbol{w} \, d\Omega - \int_{\Omega} r \operatorname{div} \boldsymbol{v} \, d\Omega:$  choose  $(\boldsymbol{w}^{\star}, r^{\star}) = (\boldsymbol{v}, 0).$   
**a** $((0,q),(\boldsymbol{w},r)) = -\int_{\Omega} q \operatorname{div} \boldsymbol{w} \, d\Omega:$  according to eg. Girault-Raviart'86,  
 $\exists C_{\operatorname{div}} > 0, \, \forall q \in L^{2}_{zmv}(\Omega), \, \exists \boldsymbol{w}_{q} \in \boldsymbol{H}^{1}_{0}(\Omega)$  such that  $\operatorname{div} \boldsymbol{w}_{q} = q$ , with  $|\boldsymbol{w}_{q}|_{1,\Omega} \leq C_{\operatorname{div}} ||q||.$   
So choosing  $(\boldsymbol{w}^{\star}, r^{\star}) = (-\boldsymbol{w}_{q}, 0)$  yields

$$|a((0,q),(\boldsymbol{w}^{\star},r^{\star}))| = \int_{\Omega} q^2 \, d\Omega = ||(0,q)||_V^2.$$

Recall 
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a  $a((\boldsymbol{v},0),(\boldsymbol{w},r)) = \nu \int_{\Omega} \nabla \boldsymbol{v} : \nabla \boldsymbol{w} \, d\Omega - \int_{\Omega} r \operatorname{div} \boldsymbol{v} \, d\Omega:$  choose  $(\boldsymbol{w}^{\star},r^{\star}) = (\boldsymbol{v},0).$   
a  $a((0,q),(\boldsymbol{w},r)) = -\int_{\Omega} q \operatorname{div} \boldsymbol{w} \, d\Omega:$  choose  $(\boldsymbol{w}^{\star},r^{\star}) = (-\boldsymbol{w}_{q},0).$   
General case: beginning with the linear combination  $\boldsymbol{w}^{\star} = \lambda \boldsymbol{v} - \mu \boldsymbol{w}_{q}, \, \lambda, \mu > 0$ , one finds

$$a((\boldsymbol{v},q),(\boldsymbol{w}^{\star},r)) = \lambda \nu \, |\boldsymbol{v}|_{1,\Omega}^2 - \mu \nu \int_{\Omega} \boldsymbol{\nabla} \boldsymbol{v} : \boldsymbol{\nabla} \boldsymbol{w}_q \, d\Omega - \int_{\Omega} (\lambda q + r) \operatorname{div} \boldsymbol{v} \, d\Omega + \mu \|q\|^2.$$

Recall 
$$a((\boldsymbol{v},q),(\boldsymbol{w},r)) = \nu \int_{\Omega} \nabla \boldsymbol{v} : \nabla \boldsymbol{w} \, d\Omega - \int_{\Omega} q \operatorname{div} \boldsymbol{w} \, d\Omega - \int_{\Omega} r \operatorname{div} \boldsymbol{v} \, d\Omega.$$
  
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 $a((\boldsymbol{v},q),(\boldsymbol{w}^{\star},r^{\star})) = \lambda \nu \, |\boldsymbol{v}|_{1,\Omega}^{2} + \mu \|q\|^{2} - \mu \nu \int_{\Omega} \nabla \boldsymbol{v} : \nabla \boldsymbol{w}_{q} \, d\Omega.$ 

Constructive proof of well-posedness with T-coercivity - 2

Recall 
$$a((\boldsymbol{v},q),(\boldsymbol{w},r)) = \nu \int_{\Omega} \nabla \boldsymbol{v} : \nabla \boldsymbol{w} \, d\Omega - \int_{\Omega} q \operatorname{div} \boldsymbol{w} \, d\Omega - \int_{\Omega} r \operatorname{div} \boldsymbol{v} \, d\Omega.$$
  
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Finally, the last term can be controlled by the first two terms, using Young's inequality.
### Stokes model

Constructive proof of well-posedness with T-coercivity - 2

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Finally, the last term can be controlled by the first two terms, using Young's inequality. Eg., choose  $(\lambda, \mu) = (\nu(C_{\text{div}})^2, 1)$ :  $T((\boldsymbol{v}, q)) = (\nu(C_{\text{div}})^2 \boldsymbol{v} - \boldsymbol{w}_q, -\nu(C_{\text{div}})^2 q)$ .

### Stokes model

F

Constructive proof of well-posedness with T-coercivity - 2

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Finally, the last term can be controlled by the first two terms, using Young's inequality. Eg., choose  $(\lambda, \mu) = (\nu(C_{\text{div}})^2, 1)$ :  $T((\boldsymbol{v}, q)) = (\nu(C_{\text{div}})^2 \boldsymbol{v} - \boldsymbol{w}_q, -\nu(C_{\text{div}})^2 q)$ . NB. Playing with Young's inequality, one finds that there is an "admissible" family of coefficients  $(\lambda, \mu)$  that yield T-coercivity. Regarding the proof with T-coercivity, one can make several observations:

- The result of Girault-Raviart'86 appears as a requirement to derive the inf-sup condition!
- The T-coercivity approach is flexible, in the sense that one has at hand a family of operators T (depending on the chosen linear combination). Among others, one may "optimize" the value of the stability constant with respect to v.
- The approach is easily transposed to the approximation, see below!

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The second goal is to prove the uniform discrete inf-sup condition, with the help of the uniform  $T_{\delta}$ -coercivity. Given finite dimensional subspaces  $(V_{\delta})_{\delta}$  of  $H_0^1(\Omega)$ , resp.  $(Q_{\delta})_{\delta}$  of  $L_{zmv}^2(\Omega)$ , one can build an approximation of the Stokes model. Question: how to choose them?

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Mimic the previous proof to guarantee uniform  $T_{\delta}$ -coercivity for the Stokes model!

$$(\mathsf{FV}\text{-}\mathsf{Stokes})_{\delta} \begin{cases} \mathsf{Find} \ (\boldsymbol{u}_{\delta}, p_{\delta}) \in \boldsymbol{V}_{\delta} \times Q_{\delta} \text{ such that} \\ \forall (\boldsymbol{v}_{\delta}, q_{\delta}) \in \boldsymbol{V}_{\delta} \times Q_{\delta}, \\ \nu \int_{\Omega} \boldsymbol{\nabla} \boldsymbol{u}_{\delta} : \boldsymbol{\nabla} \boldsymbol{v}_{\delta} \, d\Omega - \int_{\Omega} p_{\delta} \operatorname{div} \boldsymbol{v}_{\delta} \, d\Omega - \int_{\Omega} q_{\delta} \operatorname{div} \boldsymbol{u}_{\delta} \, d\Omega = {}_{V'} \langle f, (\boldsymbol{v}_{\delta}, q_{\delta}) \rangle_{V}. \end{cases}$$

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Given  $(\boldsymbol{v}_{\delta}, q_{\delta}) \in \boldsymbol{V}_{\delta} \times Q_{\delta} \setminus \{(0, 0)\}$ , we look for  $(\boldsymbol{w}_{\delta}^{\star}, r_{\delta}^{\star}) \in \boldsymbol{V}_{\delta} \times Q_{\delta} \setminus \{(0, 0)\}$  such that  $|a((\boldsymbol{v}_{\delta}, q_{\delta}), (\boldsymbol{w}_{\delta}^{\star}, r_{\delta}^{\star}))| \geq \underline{\alpha}_{\dagger} ||(\boldsymbol{v}_{\delta}, q_{\delta})||_{V}^{2},$ 

with  $\underline{\alpha}_{\dagger} > 0$  independent of  $\delta$  and of  $(\boldsymbol{v}_{\delta}, q_{\delta})$ .

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$$oldsymbol{w}^{\star}=
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with  $\boldsymbol{w}_{q_{\delta}} \in \boldsymbol{H}_{0}^{1}(\Omega)$  such that  $\operatorname{div} \boldsymbol{w}_{q_{\delta}} = q_{\delta}$ , and  $|\boldsymbol{w}_{q_{\delta}}|_{1,\Omega} \leq C_{\operatorname{div}} ||q_{\delta}||$ .

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with  $\boldsymbol{w}_{q_{\delta}} \in \boldsymbol{H}_{0}^{1}(\Omega)$  such that  $\operatorname{div} \boldsymbol{w}_{q_{\delta}} = q_{\delta}$ , and  $|\boldsymbol{w}_{q_{\delta}}|_{1,\Omega} \leq C_{\operatorname{div}} ||q_{\delta}||$ . Difficulty:  $\boldsymbol{w}_{q_{\delta}} \notin \boldsymbol{V}_{\delta}$  in general, whereas  $\boldsymbol{v}_{\delta} \in \boldsymbol{V}_{\delta}$  and  $r^{\star} \in Q_{\delta}$ . 117

How to overcome this difficulty to be able to conclude the proof?

Find  $\boldsymbol{w}_{\delta}^+ \in \boldsymbol{V}_{\delta}$  such that "div  $\boldsymbol{w}_{\delta}^+ = q_{\delta}$  weakly", and  $|\boldsymbol{w}_{\delta}^+|_{1,\Omega} \leq C^+ ||q_{\delta}||$  with  $C^+ > 0$  independent of  $\delta$ ,  $q_{\delta}$ .

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As a matter of fact, choosing  $\boldsymbol{w}_{\delta}^{\star} = \nu (C^+)^2 \boldsymbol{v}_{\delta} - \boldsymbol{w}_{\delta}^+$  and  $r_{\delta}^{\star} = -\nu (C^+)^2 q_{\delta}$  immediately yields the uniform discrete inf-sup condition!

Find  $\boldsymbol{w}_{\delta}^+ \in \boldsymbol{V}_{\delta}$  such that "div  $\boldsymbol{w}_{\delta}^+ = q_{\delta}$  weakly", and  $|\boldsymbol{w}_{\delta}^+|_{1,\Omega} \leq C^+ ||q_{\delta}||$  with  $C^+ > 0$  independent of  $\delta$ ,  $q_{\delta}$ .

As a matter of fact, choosing  $\boldsymbol{w}_{\delta}^{\star} = \nu (C^+)^2 \boldsymbol{v}_{\delta} - \boldsymbol{w}_{\delta}^+$  and  $r_{\delta}^{\star} = -\nu (C^+)^2 q_{\delta}$  immediately yields the uniform discrete inf-sup condition! How so? Just add  $\delta$ s to the previous computations!

Find  $\boldsymbol{w}_{\delta}^+ \in \boldsymbol{V}_{\delta}$  such that "div  $\boldsymbol{w}_{\delta}^+ = q_{\delta}$  weakly", and  $|\boldsymbol{w}_{\delta}^+|_{1,\Omega} \leq C^+ ||q_{\delta}||$  with  $C^+ > 0$  independent of  $\delta$ ,  $q_{\delta}$ .

To summarize, one is looking for pairs of discrete spaces  $(V_{\delta}, Q_{\delta})_{\delta}$  such that

$$\exists C^+ > 0, \ \forall \delta, \qquad \forall q_{\delta} \in Q_{\delta}, \ \exists \boldsymbol{w}_{\delta}^+ \in \boldsymbol{V}_{\delta} \text{ with the properties} \\ \forall q'_{\delta} \in Q_{\delta}, \quad \int_{\Omega} q'_{\delta} \operatorname{div} \boldsymbol{w}_{\delta}^+ d\Omega = \int_{\Omega} q'_{\delta} q_{\delta} d\Omega; \\ |\boldsymbol{w}_{\delta}^+|_{1,\Omega} \leq C^+ \|q_{\delta}\|.$$

Find  $w_{\delta}^+ \in V_{\delta}$  such that "div  $w_{\delta}^+ = q_{\delta}$  weakly", and  $|w_{\delta}^+|_{1,\Omega} \leq C^+ ||q_{\delta}||$  with  $C^+ > 0$  independent of  $\delta$ ,  $q_{\delta}$ .

In other words, one is looking for pairs of discrete spaces  $(V_{\delta}, Q_{\delta})_{\delta}$  such that

 $\exists C_{\pi} > 0, \ \forall \delta, \ \exists \pi_{\delta} \in \mathcal{L}(H_0^1(\Omega), V_{\delta}) \text{ with the properties}$ 

$$egin{aligned} & \forall oldsymbol{v} \in oldsymbol{H}_0^1(\Omega), \ orall q_\delta' \in oldsymbol{Q}_\delta, \quad \int_\Omega q_\delta' \operatorname{div}\left(\pi_\delta oldsymbol{v}
ight) d\Omega = \int_\Omega q_\delta' \operatorname{div}oldsymbol{v} d\Omega; \ & orall oldsymbol{v} \in oldsymbol{H}_0^1(\Omega), \quad |\pi_\delta oldsymbol{v}|_{1,\Omega} \leq C_\pi |oldsymbol{v}|_{1,\Omega}. \end{aligned}$$

Then one chooses  $|w_{\delta}^{+} = \pi_{\delta} w_{q_{\delta}}|$  to get the desired properties with  $C^{+} = C_{\pi} C_{\text{div}}$ .

Find  $\boldsymbol{w}_{\delta}^+ \in \boldsymbol{V}_{\delta}$  such that "div  $\boldsymbol{w}_{\delta}^+ = q_{\delta}$  weakly", and  $|\boldsymbol{w}_{\delta}^+|_{1,\Omega} \leq C^+ ||q_{\delta}||$  with  $C^+ > 0$  independent of  $\delta$ ,  $q_{\delta}$ .

By browsing the book by Boffi-Brezzi-Fortin (2013), one finds that:

- the MINI FE of order  $k \ge 1$  does the job!
- the Taylor-Hood FE of order  $k \ge 1$  does the job!

Convergence and error estimates follow...

Regarding the proof with uniform  $T_{\delta}$ -coercivity, one can make further observations:

- The so-called Fortin lemma appears "naturally" in the proof.
- One needs to have some knowledge of finite element spaces.
- **3** The proof is "simple"!

Regarding the proof with uniform  $T_{\delta}$ -coercivity, one can make further observations:

- The so-called Fortin lemma appears "naturally" in the proof.
- One needs to have some knowledge of finite element spaces.
- The proof is "simple"!

<sup>T</sup>-coercivity and uniform  $T_{\delta}$ -coercivity are indeed strongly correlated for the Stokes model!

# Outline

#### 1 What is T-coercivity?

#### 2 Stokes model

3 Neutron diffusion model

4 Neutron diffusion model with Domain Decomposition

#### 5 Further remarks

→ Further remarks

**(**) Let  $\Omega$  be a domain of  $\mathbb{R}^3$ . The basic brick of neutron diffusion writes

$$\begin{cases} -\operatorname{div} \mathbb{D}\nabla u + \sigma u = S_f \text{ in } \Omega\\ u = 0 \text{ on } \partial\Omega, \end{cases}$$

or, equivalently, with the additional unknown  $oldsymbol{p}=-\mathbb{D}
abla u$ ,

$$\begin{cases} \operatorname{div} \boldsymbol{p} + \sigma \boldsymbol{u} = S_f \text{ in } \Omega\\ \boldsymbol{u} = 0 \text{ on } \partial\Omega, \end{cases}$$

for some uniformly positive symmetric tensor  $x \mapsto \mathbb{D}(x)$  (diffusion tensor), and uniformly positive  $x \mapsto \sigma(x)$  (macroscopic absorption cross section).

The model

() Assuming that  $S_f \in L^2(\Omega)$ , one analyses mathematically the model

(Diffusion) 
$$\begin{cases} \text{Find } (u, \boldsymbol{p}) \in H^1_0(\Omega) \times \boldsymbol{H}(\operatorname{div}; \Omega) \text{ such that} \\ \operatorname{div} \boldsymbol{p} + \sigma u = S_f \text{ in } \Omega \\ \mathbb{D}^{-1}\boldsymbol{p} + \nabla u = 0 \text{ in } \Omega. \end{cases}$$

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② After elementary manipulations, the equivalent variational formulation writes

(FV-Diffusion) 
$$\begin{cases} \mathsf{Find} \ (u, p) \in L^2(\Omega) \times \boldsymbol{H}(\operatorname{div}; \Omega) \text{ such that} \\ \forall (w, r) \in L^2(\Omega) \times \boldsymbol{H}(\operatorname{div}; \Omega), \\ \int_{\Omega} \Big( -\mathbb{D}^{-1} \boldsymbol{p} \cdot \boldsymbol{r} + u \operatorname{div} \boldsymbol{r} + w \operatorname{div} \boldsymbol{p} + \sigma u w \Big) d\Omega = \int_{\Omega} S_f w \, d\Omega. \end{cases}$$

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Question: how to prove well-posedness "easily"?

The model

• Assuming that  $S_f \in L^2(\Omega)$ , one analyses mathematically the model

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Question: how to prove well-posedness "easily"?

Use T-coercivity for the neutron diffusion model!

Constructive proof of well-posedness with T-coercivity -  $\mathbf{1}$ 

Let

• 
$$V = L^2(\Omega) \times \boldsymbol{H}(\operatorname{div};\Omega)$$
, endowed with the norm  $||(v,\boldsymbol{q})||_V = (||v||^2 + ||\boldsymbol{q}||^2_{\boldsymbol{H}(\operatorname{div};\Omega)})^{1/2}$ ;  
•  $a((v,\boldsymbol{q}),(w,\boldsymbol{r})) = -\int_{\Omega} \mathbb{D}^{-1}\boldsymbol{q} \cdot \boldsymbol{r} \, d\Omega + \int_{\Omega} v \operatorname{div} \boldsymbol{r} \, d\Omega + \int_{\Omega} w \operatorname{div} \boldsymbol{q} \, d\Omega + \int_{\Omega} \sigma v w \, d\Omega$ ;  
•  $_{V'}\langle f,(w,\boldsymbol{r})\rangle_V = \int_{\Omega} S_f w \, d\Omega$ .

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•  $_{V'}\langle f,(w,\boldsymbol{r})\rangle_V = \int_{\Omega} S_f w \, d\Omega$ .  
The first goal is to prove the inf-sup condition, with the help of T-coercivity.

NB. The form a is not coercive, because  $|a((0, \boldsymbol{q}), (0, \boldsymbol{q}))| = \int_{\Omega} \mathbb{D}^{-1} \boldsymbol{q} \cdot \boldsymbol{q} \, d\Omega$  controls  $||\boldsymbol{q}||^2$ , but not  $||\boldsymbol{q}||^2$ 

not  $\|\boldsymbol{q}\|_{\boldsymbol{H}(\operatorname{div};\Omega)}^2$ .

Constructive proof of well-posedness with T-coercivity - 1

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•  $a((v,\boldsymbol{q}),(w,\boldsymbol{r})) = -\int_{\Omega} \mathbb{D}^{-1}\boldsymbol{q} \cdot \boldsymbol{r} \, d\Omega + \int_{\Omega} v \operatorname{div} \boldsymbol{r} \, d\Omega + \int_{\Omega} w \operatorname{div} \boldsymbol{q} \, d\Omega + \int_{\Omega} \sigma v w \, d\Omega$ ;  
•  $_{V'}\langle f,(w,\boldsymbol{r})\rangle_V = \int_{\Omega} S_f w \, d\Omega$ .

The first goal is to prove the inf-sup condition, with the help of T-coercivity. Given  $(v, q) \in V \setminus \{(0, 0)\}$ , we look for  $(w^*, r^*) \in V \setminus \{(0, 0)\}$  with linear dependence such that

 $|a((v, \boldsymbol{q}), (w^{\star}, \boldsymbol{r}^{\star}))| \geq \underline{\alpha} \, \|(v, \boldsymbol{q})\|_{V}^{2},$ 

with  $\underline{\alpha} > 0$  independent of (v, q). T is defined by  $T((v, q)) = (w^{\star}, r^{\star})$ .

Constructive proof of well-posedness with T-coercivity - 1

Let

• 
$$V = L^2(\Omega) \times \boldsymbol{H}(\operatorname{div};\Omega)$$
, endowed with the norm  $||(v,\boldsymbol{q})||_V = (||v||^2 + ||\boldsymbol{q}||^2_{\boldsymbol{H}(\operatorname{div};\Omega)})^{1/2}$ ;  
•  $a((v,\boldsymbol{q}),(w,\boldsymbol{r})) = -\int_{\Omega} \mathbb{D}^{-1}\boldsymbol{q} \cdot \boldsymbol{r} \, d\Omega + \int_{\Omega} v \operatorname{div} \boldsymbol{r} \, d\Omega + \int_{\Omega} w \operatorname{div} \boldsymbol{q} \, d\Omega + \int_{\Omega} \sigma v w \, d\Omega$ ;  
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with  $\underline{\alpha} > 0$  independent of (v, q). Three steps:

**0** q = 0;

2) 
$$v=0$$
 and  $oldsymbol{q}$  such that  $\operatorname{div}oldsymbol{q}=0$  ;

General case.

Constructive proof of well-posedness with T-coercivity - 2

Recall 
$$a((v, \boldsymbol{q}), (w, \boldsymbol{r})) = -\int_{\Omega} \mathbb{D}^{-1} \boldsymbol{q} \cdot \boldsymbol{r} \, d\Omega + \int_{\Omega} v \operatorname{div} \boldsymbol{r} \, d\Omega + \int_{\Omega} w \operatorname{div} \boldsymbol{q} \, d\Omega + \int_{\Omega} \sigma v w \, d\Omega.$$
  
One finds that  
**a** $((v, 0), (w, \boldsymbol{r})) = \int_{\Omega} v \operatorname{div} \boldsymbol{r} \, d\Omega + \int_{\Omega} \sigma v w \, d\Omega$ : choose  $(w^{\star}, \boldsymbol{r}^{\star}) = (v, 0).$ 

Constructive proof of well-posedness with T-coercivity - 2

Recall 
$$a((v, \boldsymbol{q}), (w, \boldsymbol{r})) = -\int_{\Omega} \mathbb{D}^{-1} \boldsymbol{q} \cdot \boldsymbol{r} \, d\Omega + \int_{\Omega} v \operatorname{div} \boldsymbol{r} \, d\Omega + \int_{\Omega} w \operatorname{div} \boldsymbol{q} \, d\Omega + \int_{\Omega} \sigma v w \, d\Omega$$
.  
One finds that

• 
$$a((v,0), (w, \mathbf{r})) = \int_{\Omega} v \operatorname{div} \mathbf{r} \, d\Omega + \int_{\Omega} \sigma v w \, d\Omega$$
: choose  $(w^{\star}, \mathbf{r}^{\star}) = (v, 0)$ .  
•  $a((0, \mathbf{q}), (w, \mathbf{r})) = -\int_{\Omega} \mathbb{D}^{-1} \mathbf{q} \cdot \mathbf{r} \, d\Omega$  (with div  $\mathbf{q} = 0$ ): choose  $(w^{\star}, \mathbf{r}^{\star}) = (0, -\mathbf{q})$ .

Constructive proof of well-posedness with T-coercivity - 2

Recall 
$$a((v, \boldsymbol{q}), (w, \boldsymbol{r})) = -\int_{\Omega} \mathbb{D}^{-1} \boldsymbol{q} \cdot \boldsymbol{r} \, d\Omega + \int_{\Omega} v \operatorname{div} \boldsymbol{r} \, d\Omega + \int_{\Omega} w \operatorname{div} \boldsymbol{q} \, d\Omega + \int_{\Omega} \sigma v w \, d\Omega$$
  
One finds that

• 
$$a((v,0), (w, r)) = \int_{\Omega} v \operatorname{div} r \, d\Omega + \int_{\Omega} \sigma v w \, d\Omega$$
: choose  $(w^*, r^*) = (v, 0)$ .  
•  $a((0, q), (w, r)) = -\int_{\Omega} \mathbb{D}^{-1} q \cdot r \, d\Omega$  (with div  $q = 0$ ): choose  $(w^*, r^*) = (0, -q)$ .

**③** General case: beginning with  $r^{\star} = -q$ , one finds

$$a((v, \boldsymbol{q}), (w, \boldsymbol{r}^{\star})) = \int_{\Omega} \mathbb{D}^{-1} \boldsymbol{q} \cdot \boldsymbol{q} \, d\Omega + \int_{\Omega} (w - v) \operatorname{div} \boldsymbol{q} \, d\Omega + \int_{\Omega} \sigma v w \, d\Omega.$$

Constructive proof of well-posedness with T-coercivity - 2

Recall 
$$a((v, \boldsymbol{q}), (w, \boldsymbol{r})) = -\int_{\Omega} \mathbb{D}^{-1} \boldsymbol{q} \cdot \boldsymbol{r} \, d\Omega + \int_{\Omega} v \operatorname{div} \boldsymbol{r} \, d\Omega + \int_{\Omega} w \operatorname{div} \boldsymbol{q} \, d\Omega + \int_{\Omega} \sigma v w \, d\Omega$$
.  
One finds that

$$a((v,0),(w,r)) = \int_{\Omega} v \operatorname{div} r \, d\Omega + \int_{\Omega} \sigma v w \, d\Omega: \text{ choose } (w^{\star}, r^{\star}) = (v,0).$$

$$a((0,q),(w,r)) = -\int_{\Omega} \mathbb{D}^{-1} q \cdot r \, d\Omega \text{ (with div } q = 0): \text{ choose } (w^{\star}, r^{\star}) = (0,-q).$$

 $\label{eq:General case: r^* = -q. Next, $w^* = \eta(v + \sigma^{-1} {\rm div} \, q)$, $\eta > 0$ leads to}$ 

$$\begin{split} a((v,\boldsymbol{q}),(w^{\star},\boldsymbol{r}^{\star})) &= \int_{\Omega} \mathbb{D}^{-1}\boldsymbol{q} \cdot \boldsymbol{q} \, d\Omega + \eta \int_{\Omega} \sigma^{-1} (\operatorname{div} \boldsymbol{q})^2 \, d\Omega + \eta \int_{\Omega} \sigma v^2 \, d\Omega \\ &+ (2\eta - 1) \int_{\Omega} v \operatorname{div} \boldsymbol{q} \, d\Omega. \end{split}$$

Constructive proof of well-posedness with T-coercivity - 2

Recall 
$$a((v, \boldsymbol{q}), (w, \boldsymbol{r})) = -\int_{\Omega} \mathbb{D}^{-1} \boldsymbol{q} \cdot \boldsymbol{r} \, d\Omega + \int_{\Omega} v \operatorname{div} \boldsymbol{r} \, d\Omega + \int_{\Omega} w \operatorname{div} \boldsymbol{q} \, d\Omega + \int_{\Omega} \sigma v w \, d\Omega$$
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: choose  $(w^{\star}, r^{\star}) = (v, 0)$ .  
•  $a((0, q), (w, r)) = -\int \mathbb{D}^{-1} q \cdot r \, d\Omega$  (with div  $q = 0$ ): choose  $(w^{\star}, r^{\star}) = (0)$ 

2 
$$a((0, \boldsymbol{q}), (w, \boldsymbol{r})) = -\int_{\Omega} \mathbb{D}^{-1} \boldsymbol{q} \cdot \boldsymbol{r} \, d\Omega$$
 (with div  $\boldsymbol{q} = 0$ ): choose  $(w^*, \boldsymbol{r}^*) = (0, -\boldsymbol{q})$ .

Solution General case:  $r^{\star} = -q$ . Next,  $w^{\star} = \eta (v + \sigma^{-1} \operatorname{div} q)$ ,  $\eta > 0$  leads to

$$\begin{aligned} a((v,\boldsymbol{q}),(w^{\star},\boldsymbol{r}^{\star})) &= \int_{\Omega} \mathbb{D}^{-1}\boldsymbol{q} \cdot \boldsymbol{q} \, d\Omega + \eta \int_{\Omega} \sigma^{-1} (\operatorname{div} \boldsymbol{q})^2 \, d\Omega + \eta \int_{\Omega} \sigma v^2 \, d\Omega \\ &+ (2\eta - 1) \int_{\Omega} v \operatorname{div} \boldsymbol{q} \, d\Omega. \end{aligned}$$

So, choosing  $(w^{\star}, \boldsymbol{r}^{\star}) = (\frac{1}{2}(v + \sigma^{-1} \mathrm{div} \, \boldsymbol{q}), -\boldsymbol{q})$  yields T-coercivity.

Constructive proof of convergence with uniform  $T_{\delta}$ -coercivity

We assume that  $\sigma$  is constant (general case, see PC-Jamelot-Kpadonou'17). The second goal is to prove the uniform discrete inf-sup condition, with the help of the uniform  $T_{\delta}$ -coercivity. Given finite dimensional subspaces  $(V_{\delta})_{\delta}$  of  $L^2(\Omega)$ , resp.  $(Q_{\delta})_{\delta}$  of  $H(\operatorname{div}; \Omega)$ , one can build an approximation of the neutron diffusion model. Question: how to choose them?

<sup>■</sup>Mimic the previous proof!

Constructive proof of convergence with uniform  $\mathtt{T}_{\delta}\text{-coercivity}$ 

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 $|a((v_{\delta}, \boldsymbol{q}_{\delta}), (w_{\delta}^{\star}, \boldsymbol{r}_{\delta}^{\star}))| \geq \underline{\alpha}_{\dagger} ||(v_{\delta}, \boldsymbol{q}_{\delta})||_{V}^{2},$ 

with  $\underline{\alpha}_{\dagger} > 0$  independent of  $\delta$  and of  $(v_{\delta}, q_{\delta})$ .

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$$w^{\star} = rac{1}{2}(v_{\delta} + \sigma^{-1} ext{div} \, oldsymbol{q}_{\delta}) ext{ and } oldsymbol{r}^{\star} = -oldsymbol{q}_{\delta}.$$

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$$w^{\star} = rac{1}{2}(v_{\delta} + \sigma^{-1} ext{div} \, oldsymbol{q}_{\delta}) ext{ and } oldsymbol{r}^{\star} = -oldsymbol{q}_{\delta}.$$

Difficulty: div  $q_{\delta} \in V_{\delta}$ ? Whereas  $v_{\delta} \in V_{\delta}$  and  $q_{\delta} \in Q_{\delta}$ .
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All pairs of discrete spaces  $(V_{\delta}, Q_{\delta})_{\delta}$  such that  $\operatorname{div} [Q_{\delta}] \subset V_{\delta}$  do the job! By browsing the book by Boffi-Brezzi-Fortin (2013), one now finds that: one can choose the Raviart-Thomas FE of order  $k \geq 0$  (for  $Q_{\delta}$ ). Constructive proof of convergence with uniform  $\mathtt{T}_{\delta}\text{-coercivity}$ 

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## Outline

1 What is T-coercivity?

### 2 Stokes model

3 Neutron diffusion model

4 Neutron diffusion model with Domain Decomposition

#### 5 Further remarks

→ Further remarks

#### Neutron diffusion model with Domain Decomposition The partition of the domain

- The domain  $\Omega$  is split into N disjoint subdomains  $(\Omega_i)_{i=1,N}$ :  $\overline{\Omega} = \bigcup_{i=1,N} \overline{\Omega_i}$ . For v defined over  $\Omega$ , let  $v_i = v_{|\Omega_i}$  for i = 1, N.
- 2 Let Γ<sub>ij</sub> = int(Ω<sub>i</sub> ∩ Ω<sub>j</sub>) if dim<sub>H</sub>(Ω<sub>i</sub> ∩ Ω<sub>j</sub>) = 2, otherwise Γ<sub>ij</sub> = Ø, for i ≠ j. Let Γ = ∪<sub>i<j</sub>Γ<sub>ij</sub> denote the global interface. For Γ<sub>ij</sub> ≠ Ø, let [q]<sub>ij</sub> denote the jump across Γ<sub>ij</sub>. Then, let [q] denote the global jump: [q]<sub>|Γ<sub>ij</sub></sub> = [q]<sub>ij</sub> for i ≠ j.

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 $\begin{array}{l} \textcircled{O} \quad \text{Let } M = \prod_{i < j} L^2(\Gamma_{ij}), \text{ with norm } \|v_{\Gamma}\|_M = \left(\sum_{i < j} \|v_{\Gamma|\Gamma_{ij}}\|_{L^2(\Gamma_{ij})}^2\right)^{1/2}. \\ \text{Let } Q = \left\{ q = (q_i)_i \in L^2(\Omega) \, | \, \text{div } q_i \in L^2(\Omega_i), \ i = 1, N, \text{ and } [q \cdot n] \in M \right\}, \text{ with norm} \end{array}$ 

$$\|oldsymbol{q}\|_{oldsymbol{Q}} = \Big(\sum_{i=1,N} \|oldsymbol{q}_i\|_{oldsymbol{H}(\operatorname{div},\Omega_i)}^2 + ||[oldsymbol{q}\cdotoldsymbol{n}]||_M^2 \Big)^{1/2}.$$

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• Let  $M = \prod_{i < j} L^2(\Gamma_{ij})$ , with norm  $\|v_{\Gamma}\|_M = \left(\sum_{i < j} \|v_{\Gamma|\Gamma_{ij}}\|_{L^2(\Gamma_{ij})}^2\right)^{1/2}$ . Let  $Q = \left\{ q = (q_i)_i \in L^2(\Omega) \mid \text{div } q_i \in L^2(\Omega_i), i = 1, N, \text{ and } [q \cdot n] \in M \right\}$ , with norm

$$\| \boldsymbol{q} \|_{\boldsymbol{Q}} = \Big( \sum_{i=1,N} \| \boldsymbol{q}_i \|_{\boldsymbol{H}( ext{div},\Omega_i)}^2 + \| [ \boldsymbol{q} \cdot \boldsymbol{n} ] \|_M^2 \Big)^{1/2}.$$

Similar Finally, let  $V_{DD} = L^2(\Omega) \times \mathbf{Q} \times \mathbf{M}$ , endowed with the norm

 $\|(v, \boldsymbol{q}, v_{\Gamma})\|_{V_{DD}} = (\|v\|^2 + \|\boldsymbol{q}\|_{\boldsymbol{Q}}^2 + \|v_{\Gamma}\|_{M}^2)^{1/2}.$ 

# Neutron diffusion model with Domain Decomposition $_{\mbox{The model}}$

Of. PC-Jamelot-Kpadonou'17, an equivalent variational formulation to the neutron diffusion model with Domain Decomposition writes

$$(\mathsf{FV}\text{-Diff-DD}) \quad \begin{cases} \mathsf{Find} \ (u, \boldsymbol{p}, u_{\Gamma}) \in V_{DD} \text{ such that} \\ \forall (w, \boldsymbol{r}, w_{\Gamma}) \in V_{DD}, \\ \sum_{i=1,N} \int_{\Omega_i} \left( -\mathbb{D}^{-1} \boldsymbol{p}_i \cdot \boldsymbol{r}_i + u_i \operatorname{div} \boldsymbol{r}_i + w_i \operatorname{div} \boldsymbol{p}_i + \sigma u_i w_i \right) d\Omega \\ - \int_{\Gamma} \left( [\boldsymbol{p} \cdot \boldsymbol{n}] w_{\Gamma} + [\boldsymbol{r} \cdot \boldsymbol{n}] u_{\Gamma} \right) d\Gamma = \int_{\Omega} S_f w \ d\Omega. \end{cases}$$

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Question: how to prove well-posedness "easily"?

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• Cf. PC-Jamelot-Kpadonou'17, an equivalent variational formulation to the neutron diffusion model with Domain Decomposition writes

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Question: how to prove well-posedness "easily"?

Use T-coercivity for the neutron diffusion model with Domain Decomposition!

Constructive proof of well-posedness with T-coercivity -  $\ensuremath{\mathbf{1}}$ 

•  $V_{DD} = L^2(\Omega) \times \mathbf{Q} \times M$  is endowed with  $||(v, \mathbf{q}, v_{\Gamma})||_{V_{DD}} = (||v||^2 + ||\mathbf{q}||_{\mathbf{Q}}^2 + ||v_{\Gamma}||_M^2)^{1/2}$ . • Let

• 
$$a_{DD}((v, \boldsymbol{q}, v_{\Gamma}), (w, \boldsymbol{r}, w_{\Gamma})) = \sum_{i=1,N} \int_{\Omega_i} \left( -\mathbb{D}^{-1} \boldsymbol{q}_i \cdot \boldsymbol{r}_i + v_i \operatorname{div} \boldsymbol{r}_i + w_i \operatorname{div} \boldsymbol{q}_i + \sigma v_i w_i \right) d\Omega$$
  
 $- \int_{\Gamma} \left( [\boldsymbol{q} \cdot \boldsymbol{n}] w_{\Gamma} + [\boldsymbol{r} \cdot \boldsymbol{n}] v_{\Gamma} \right) d\Gamma;$   
•  $V_{DD'} \langle f, (w, \boldsymbol{r}, w_{\Gamma}) \rangle_{V_{DD}} = \int_{\Omega} S_f w \, d\Omega.$ 

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 $- \int_{\Gamma} \left( [\boldsymbol{q} \cdot \boldsymbol{n}] w_{\Gamma} + [\boldsymbol{r} \cdot \boldsymbol{n}] v_{\Gamma} \right) d\Gamma;$   
•  $V_{DD'} \langle f, (w, \boldsymbol{r}, w_{\Gamma}) \rangle_{V_{DD}} = \int_{\Omega} S_f w \, d\Omega.$ 

Again, the first goal is to prove the inf-sup condition, with the help of T-coercivity.

Constructive proof of well-posedness with T-coercivity - 1

•  $V_{DD} = L^2(\Omega) \times \mathbf{Q} \times M$  is endowed with  $||(v, \mathbf{q}, v_{\Gamma})||_{V_{DD}} = (||v||^2 + ||\mathbf{q}||_{\mathbf{Q}}^2 + ||v_{\Gamma}||_M^2)^{1/2}$ . • Let

• 
$$a_{DD}((v, \boldsymbol{q}, v_{\Gamma}), (w, \boldsymbol{r}, w_{\Gamma})) = \sum_{i=1,N} \int_{\Omega_i} \left( -\mathbb{D}^{-1} \boldsymbol{q}_i \cdot \boldsymbol{r}_i + v_i \operatorname{div} \boldsymbol{r}_i + w_i \operatorname{div} \boldsymbol{q}_i + \sigma v_i w_i \right) d\Omega$$
  
 $- \int_{\Gamma} \left( [\boldsymbol{q} \cdot \boldsymbol{n}] w_{\Gamma} + [\boldsymbol{r} \cdot \boldsymbol{n}] v_{\Gamma} \right) d\Gamma;$   
•  $V_{DD'} \langle f, (w, \boldsymbol{r}, w_{\Gamma}) \rangle_{V_{DD}} = \int_{\Omega} S_f w \, d\Omega.$ 

Again, the first goal is to prove the inf-sup condition, with the help of T-coercivity. Given  $(v, q, v_{\Gamma}) \in V_{DD} \setminus \{(0, 0, 0)\}$ , we look for  $(w^{\star}, r^{\star}, w_{\Gamma}^{\star}) \in V_{DD} \setminus \{(0, 0, 0)\}$  with linear dependence such that

$$|a_{DD}((v, \boldsymbol{q}, v_{\Gamma}), (w^{\star}, \boldsymbol{r}^{\star}, w_{\Gamma}^{\star}))| \geq \underline{\alpha} \, \|(v, \boldsymbol{q}, v_{\Gamma})\|_{V_{DD}}^{2},$$

with  $\underline{\alpha} > 0$  independent of  $(v, q, v_{\Gamma})$ , and T is defined by  $T((v, q, v_{\Gamma})) = (w^{\star}, r^{\star}, w_{\Gamma}^{\star})$ .

Constructive proof of well-posedness with T-coercivity -  $1 \label{eq:constructive}$ 

•  $V_{DD} = L^2(\Omega) \times \mathbf{Q} \times \mathbf{M}$  is endowed with  $||(v, \mathbf{q}, v_{\Gamma})||_{V_{DD}} = (||v||^2 + ||\mathbf{q}||_{\mathbf{Q}}^2 + ||v_{\Gamma}||_{\mathbf{M}}^2)^{1/2}$ . • Let

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with  $\alpha > 0$  independent of  $(v, q, v_{\Gamma})$ . Two steps (incremental proof):

- **1**  $v_{\Gamma} = 0$  ;
- ② General case.

Constructive proof of well-posedness with T-coercivity - 2

Recall 
$$a_{DD}((v, \boldsymbol{q}, v_{\Gamma}), (w, \boldsymbol{r}, w_{\Gamma})) = \sum_{i=1,N} \int_{\Omega_i} \left( -\mathbb{D}^{-1} \boldsymbol{q}_i \cdot \boldsymbol{r}_i + v_i \operatorname{div} \boldsymbol{r}_i + w_i \operatorname{div} \boldsymbol{q}_i + \sigma v_i w_i \right) d\Omega$$
  
 $- \int_{\Gamma} \left( [\boldsymbol{q} \cdot \boldsymbol{n}] w_{\Gamma} + [\boldsymbol{r} \cdot \boldsymbol{n}] v_{\Gamma} \right) d\Gamma.$   
**3** One finds that  $a_{DD}((v, \boldsymbol{q}, 0), (w, \boldsymbol{r}, w_{\Gamma})) = \sum_{i=1,N} \int_{\Omega_i} \left( -\mathbb{D}^{-1} \boldsymbol{q}_i \cdot \boldsymbol{r}_i + v_i \operatorname{div} \boldsymbol{r}_i + w_i \operatorname{div} \boldsymbol{q}_i + \sigma v_i w_i \right) d\Omega - \int_{\Gamma} [\boldsymbol{q} \cdot \boldsymbol{n}] w_{\Gamma} d\Gamma.$   
Choose  $((w_i^{\star})_i, (\boldsymbol{r}_i^{\star})_i) = \left( \frac{1}{2} (v_i + \sigma^{-1} \operatorname{div} \boldsymbol{q}_i)_i, -(\boldsymbol{q}_i)_i \right)$  "as before", and  $w_{\Gamma}^{\star} = -[\boldsymbol{q} \cdot \boldsymbol{n}]!$ 

Constructive proof of well-posedness with T-coercivity - 2

Recall 
$$a_{DD}((v, \boldsymbol{q}, v_{\Gamma}), (w, \boldsymbol{r}, w_{\Gamma})) = \sum_{i=1,N} \int_{\Omega_i} \left( -\mathbb{D}^{-1} \boldsymbol{q}_i \cdot \boldsymbol{r}_i + v_i \operatorname{div} \boldsymbol{r}_i + w_i \operatorname{div} \boldsymbol{q}_i + \sigma v_i w_i \right) d\Omega$$
  
 $- \int_{\Gamma} \left( [\boldsymbol{q} \cdot \boldsymbol{n}] w_{\Gamma} + [\boldsymbol{r} \cdot \boldsymbol{n}] v_{\Gamma} \right) d\Gamma.$   
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Choose  $((w_i^{\star})_i, (\boldsymbol{r}_i^{\star})_i) = (\frac{1}{2}(v_i + \sigma^{-1} \operatorname{div} \boldsymbol{q}_i)_i, -(\boldsymbol{q}_i)_i)$  "as before", and  $w_{\Gamma}^{\star} = -[\boldsymbol{q} \cdot \boldsymbol{n}]!$   
General case [sketched]: for  $i = 1, N$ , one introduces a lifting  $\boldsymbol{v}_i(v_{\Gamma}) \in \boldsymbol{H}(\operatorname{div}; \Omega_i)$  of

 $(v_{\Gamma})_{|\partial\Omega_i}$ , by solving a Neumann problem.

Constructive proof of well-posedness with T-coercivity - 2

Recall 
$$a_{DD}((v, q, v_{\Gamma}), (w, r, w_{\Gamma})) = \sum_{i=1,N} \int_{\Omega_i} \left( -\mathbb{D}^{-1} q_i \cdot r_i + v_i \operatorname{div} r_i + w_i \operatorname{div} q_i + \sigma v_i w_i \right) d\Omega$$
  
 $-\int_{\Gamma} \left( [q \cdot n] w_{\Gamma} + [r \cdot n] v_{\Gamma} \right) d\Gamma.$   
One finds that  $a_{DD}((v, q, 0), (w, r, w_{\Gamma})) = \sum_{i=1,N} \int_{\Omega_i} \left( -\mathbb{D}^{-1} q_i \cdot r_i + v_i \operatorname{div} r_i + w_i \operatorname{div} q_i + \sigma v_i w_i \right) d\Omega - \int_{\Gamma} [q \cdot n] w_{\Gamma} d\Gamma.$   
Choose  $((w_i^*)_i, (r_i^*)_i) = \left( \frac{1}{2} (v_i + \sigma^{-1} \operatorname{div} q_i)_i, -(q_i)_i \right)$  "as before", and  $w_{\Gamma}^* = -[q \cdot n]!$   
General case [sketched]: for  $i = 1, N$ , one introduces a lifting  $v_i(v_{\Gamma}) \in H(\operatorname{div}; \Omega_i)$  of  $(v_{\Gamma})_{|\partial\Omega_i}$ , by solving a Neumann problem.  
Choose  $((w^*)_i, (r_i^*)_i, w_{\Gamma}^*) = \left( \frac{1}{2} (v_i + \sigma^{-1} \operatorname{div} q_i)_i, -(q_i + \eta v_i(v_{\Gamma}))_i, v_{\Gamma} - [q \cdot n] \right)$ , and find ad hoc  $\eta > 0$  (independent of the lifting) to yield T-coercivity.

Constructive proof of convergence with uniform  $\mathtt{T}_{\delta}\text{-coercivity}$ 

The second goal is to prove the uniform discrete inf-sup condition, with the help of the uniform  $T_{\delta}$ -coercivity. Given finite dimensional subspaces  $(V_{\delta})_{\delta}$  of  $L^2(\Omega)$ ,  $(Q_{\delta})_{\delta}$  of Q and  $(M_{\delta})_{\delta}$  of M, one builds an approximation of the neutron diffusion model with Domain Decomposition. Question: how to choose them?

Mimic the previous proofs!

Constructive proof of convergence with uniform  $T_{\delta}$ -coercivity

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Given  $\delta$ , the difficulty is to find how the normal jumps of elements of  $Q_{\delta}$  should interact with elements of  $M_{\delta}$ . We refer to PC-Jamelot-Kpadonou'17 for the technicalities...

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- In a subdomain Ω<sub>i</sub> (cf. step 1.), the Raviart-Thomas FE of order k ≥ 0 can be used to define the pair (V<sub>δ</sub>, Q<sub>δ</sub>) restricted to Ω<sub>i</sub>.
- Then, on the interface  $\Gamma_{ij}$ , one can choose  $M_{\delta} = (\mathbf{Q}_{\delta} \cdot \mathbf{n}_i)_{|\Gamma_{ij}} + (\mathbf{Q}_{\delta} \cdot \mathbf{n}_j)_{|\Gamma_{ij}}$  (no crosspoint/no regularity issues).

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- In a subdomain  $\Omega_i$  (cf. step 1.), the Raviart-Thomas FE of order  $k \ge 0$  can be used to define the pair  $(V_{\delta}, Q_{\delta})$  restricted to  $\Omega_i$ .
- Then, on the interface  $\Gamma_{ij}$ , one can choose  $M_{\delta} = (\boldsymbol{Q}_{\delta} \cdot \boldsymbol{n}_i)_{|\Gamma_{ij}} + (\boldsymbol{Q}_{\delta} \cdot \boldsymbol{n}_j)_{|\Gamma_{ij}}$  (no crosspoint/no regularity issues).

The proof has now become very "technical"! However it has been made possible by using T-coercivity incrementally (from one to several subdomains; from the exact to the discrete variational formulations...).

Convergence and error estimates follow.

Some extensions:

- Stokes model: see Jamelot (2022, HAL report) for a non-conforming discretisation (Crouzeix-Raviart FE or Fortin-Soulié FE); see master's thesis by MRoueh (2022) for DG discretisation; see Barré-Grandmont-Moireau'22 for a poromechanics model.
- ② diffusion model: see PhD thesis by Giret (2018) for a SPN multigroup model.
- O 2D elastodynamics: see Falletta-Ferrari-Scuderi (2023, arXiv report) for a virtual element method.
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- Iclassical" mixed variational formulations: see Barré-PC (2022, HAL report).
- in Banach spaces, T-coercivity implies Hilbert structure, see Ern-Guermont II (2021).
- if possible, discretise the variational formulation with operator T, see Chesnel-PC'13.
- T-coercivity still usable with the Strang lemmas (approximate forms).

## Thank you for your attention!