

Electromagnetic wave propagation at classical material/meta-material interfaces

Anne-Sophie Bonnet-Bendhia, Patrick Ciarlet

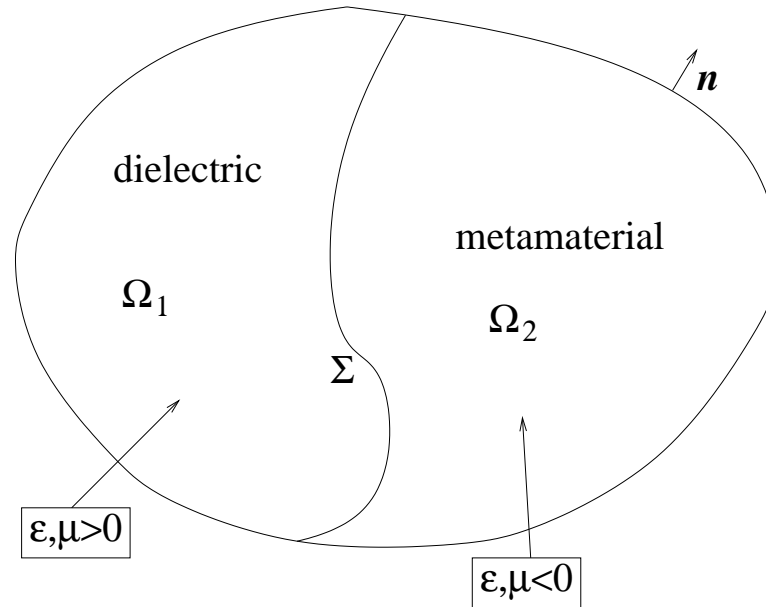
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POEMS, UMR 7231 CNRS-ENSTA-INRIA

Motivation

- *Goal:* Solve numerically a time-harmonic problem in electromagnetism, set in a heterogeneous medium like below.

The domain Ω :

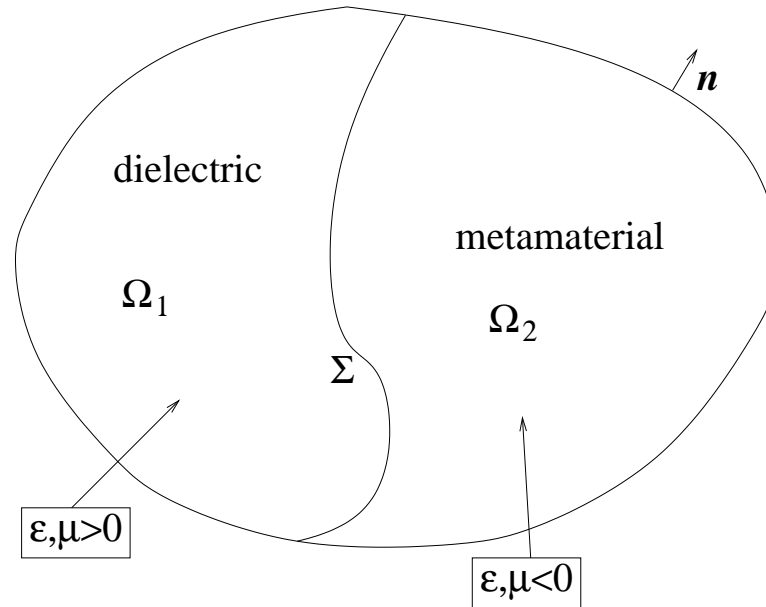


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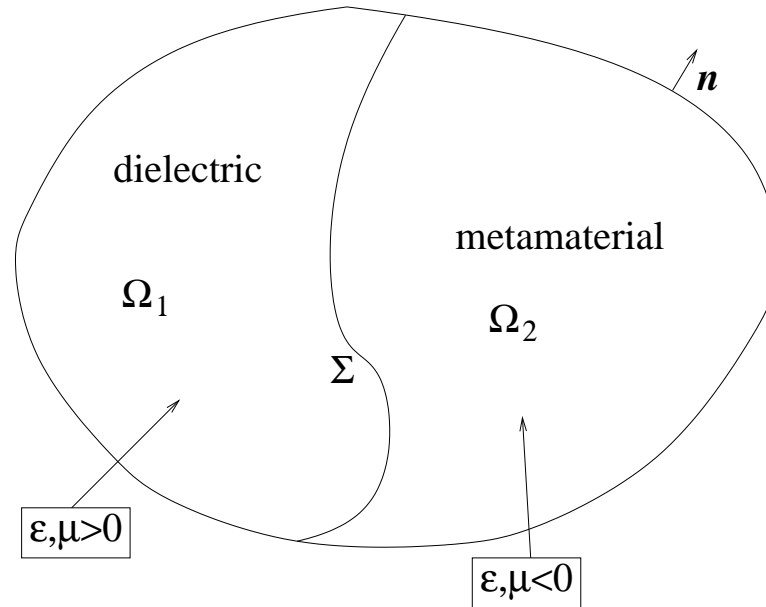


- *Possible practical applications:* perfect lens, invisibility cloaking, etc.

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- *Questions:*
 - Is the problem to be solved *well-posed*?
 - How to *compute* a numerical approximation of the solution?

Maxwell problem (electric field)

- Given $\omega > 0$ and source term $\mathcal{F} \in L^2(\Omega)^3$ ($\mathcal{F} := i\omega\mathcal{J}$, $\operatorname{div} \mathcal{F} = 0$).
Find $\mathcal{E} \in L^2(\Omega)^3$ with $\operatorname{curl} \mathcal{E} \in L^2(\Omega)^3$ such that

$$\begin{cases} \operatorname{curl} \left(\frac{1}{\mu} \operatorname{curl} \mathcal{E} \right) - \omega^2 \varepsilon \mathcal{E} = \mathcal{F} & \text{in } \Omega ; \\ \mathcal{E} \times \mathbf{n} = 0 & \text{on } \partial\Omega. \end{cases}$$

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- When $\varepsilon, \mu > 0$ ($\varepsilon, \mu, \varepsilon^{-1}, \mu^{-1} \in L^\infty(\Omega)$):
which *functional space* to measure the electric field?
which associated *discretization*?
 - $\mathcal{H}_0(\operatorname{curl}; \Omega) := \{ \mathcal{F} \in L^2(\Omega)^3 \mid \operatorname{curl} \mathcal{F} \in L^2(\Omega)^3, \mathcal{F} \times \mathbf{n}|_{\partial\Omega} = 0 \}$ (Edge FE).

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- ◇ $\mathcal{X}_0(\varepsilon; \Omega) := \{ \mathcal{F} \in \mathcal{H}_0(\mathbf{curl}; \Omega) \mid \operatorname{div} \varepsilon \mathcal{F} \in L^2(\Omega) \}$ (Continuous Galerkin FE).

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- ◇ $L^2(\Omega)^3$ (Discontinuous Galerkin FE).

Etc.

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(Assumption: no singular electric fields).

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- Equivalent (Augmented) Variational Formulation:**
Find $\mathcal{E} \in \mathcal{X}_0(\varepsilon; \Omega)$ such that

$$\int_{\Omega} \left(\frac{1}{\mu} \operatorname{curl} \mathcal{E} \cdot \operatorname{curl} \bar{\mathcal{E}}' + s \operatorname{div} \varepsilon \mathcal{E} \operatorname{div} \varepsilon \bar{\mathcal{E}}' \right) d\Omega - \omega^2 \int_{\Omega} \varepsilon \mathcal{E} \cdot \bar{\mathcal{E}}' d\Omega = \int_{\Omega} \mathcal{F} \cdot \bar{\mathcal{E}}' d\Omega, \quad \forall \bar{\mathcal{E}}' \in \mathcal{X}_0(\varepsilon; \Omega).$$

Well-posedness, when $\varepsilon, \mu > 0 \dots$

Well-posedness stems from the two properties:

- (1) **coerciveness** over $\mathcal{X}_0(\varepsilon; \Omega)$ of

$$a(\mathcal{E}, \mathcal{E}') := \int_{\Omega} \left(\frac{1}{\mu} \mathbf{curl} \mathcal{E} \cdot \mathbf{curl} \bar{\mathcal{E}}' + s \operatorname{div} \varepsilon \mathcal{E} \operatorname{div} \varepsilon \bar{\mathcal{E}}' \right) d\Omega .$$

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- (2) **compactness** of the term

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- ◇ These two ingredients fundamentally rely on: $\varepsilon > \varepsilon_{\star} > 0$ and $\mu > \mu_{\star} > 0$ a.e. in Ω .
- ◇ *Numerical convergence* then follows, for sufficiently small meshsize $h \dots$

Study of a scalar model problem

- Assume that the problem is independent of z .
The third component $e := \mathcal{E}_z(x, y)$ is governed by
find $e \in H^1(\Omega)$ such that

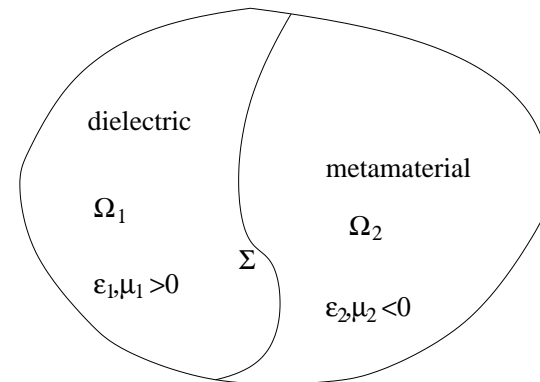
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To fix ideas: ε and μ constant over Ω_i , $i = 1, 2$
($\varepsilon_i := \varepsilon|_{\Omega_i}$, $\mu_i := \mu|_{\Omega_i}$)



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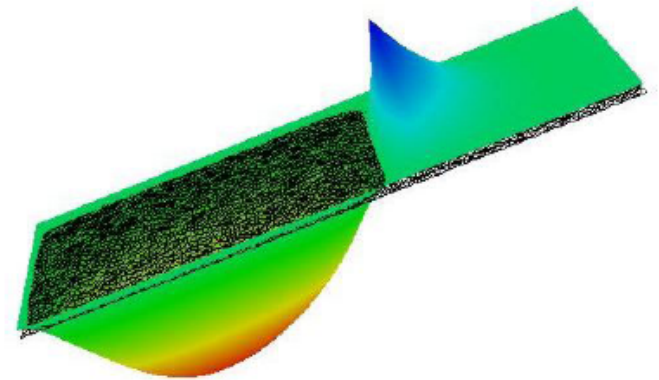
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Jump of the trace of the
normal derivative across
the interface (with $\kappa_\mu < 0$)



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- Define the (negative) **contrasts**: $\kappa_\varepsilon := \frac{\varepsilon_1}{\varepsilon_2}$, $\kappa_\mu := \frac{\mu_1}{\mu_2}$.
- State of the art.* [Costabel-Stephan'85], [Bonnet-Dauge-Ramdani'99], [Ramdani'99].
 - If $\kappa_\mu = -1$, the problem is always ill-posed.
 - If the interface Σ is smooth, then the problem is well-posed (except for resonance frequencies) as soon as $\kappa_\mu \neq -1$.
 - If Σ is piecewise smooth (ie. in the presence of corners), then the problem is well-posed (except for resonance frequencies) as soon as

$$\kappa_\mu \notin]\kappa_\mu^{\inf}, \kappa_\mu^{\sup}[, \text{ with } -1 \in]\kappa_\mu^{\inf}, \kappa_\mu^{\sup}[.$$

Discretization (1): the two-field formulation

- Introduce the new – magnetic-like – "unknown" $\underline{\mathbf{h}}_2 := \left(\frac{1}{|\mu_2|} \mathbf{curl} e \right)_{|\Omega_2}$.

Define a new formulation, with unknowns e over Ω and $\underline{\mathbf{h}}_2$ over Ω_2 :

$$\left\{ \begin{array}{l} e \in H_0^1(\Omega) \\ \underline{\mathbf{h}}_2 \in \{ \mathbf{p} \in H(\mathbf{curl}; \Omega_2) \mid \operatorname{div} |\mu_2| \mathbf{p} \in L^2(\Omega_2), |\mu_2| \mathbf{p} \cdot \mathbf{n}|_{\partial\Omega_2 \setminus \Sigma} = 0 \} \end{array} \right. .$$

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- [Bonnet-Jr-Zwölf'07].

Well-posedness can be recovered, provided $|\kappa_\mu|$ is "large enough".

(The new formulation fits into the *coercive+compact framework*).

Numerical convergence then follows.

Added cost (related to $\underline{\mathbf{h}}_2^h$) reasonable if Ω_2 is "small" wrt Ω_1 .

Numerical experiments can be found in [Zwölf'07].

Discretization (2): the natural formulation

- *Discretize directly* the "standard" variational formulation.

Find $e \in H_0^1(\Omega)$ such that

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Find $e \in H_0^1(\Omega)$ such that

$$\int_{\Omega} \frac{1}{\mu} \mathbf{curl} e \cdot \mathbf{curl} \bar{e}' d\Omega - \omega^2 \int_{\Omega} \varepsilon e \bar{e}' d\Omega = \int_{\Omega} f \bar{e}' d\Omega, \quad \forall e' \in H_0^1(\Omega).$$

Everything goes well numerically, provided $|\kappa_{\mu}|$ is "large enough" (cf. [\[Zwölf'07\]](#)).

Why?

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$$=: a_{scal}(e, e').$$

- [Bonnet-Jr-Zwölf'09].

Replace the coercivity of the bilinear form $a_{scal}(\cdot, \cdot)$ by the more general \mathbb{T} -coercivity, where \mathbb{T} is a bijective, continuous linear operator of $H_0^1(\Omega)$ ($\alpha > 0$):

$$a_{scal}(e, \mathbb{T}e) \geq \alpha \|e\|_{H_0^1(\Omega)}^2, \quad \forall e \in H_0^1(\Omega) \quad \iff \quad \mathbb{T}v = \begin{cases} v_1 & \text{in } \Omega_1 \\ -v_2 + 2\mathcal{R}(v|_{\Sigma}) & \text{in } \Omega_2 \end{cases}.$$

Then, the *coercive+compact framework* is recovered (for $|\kappa_{\mu}|$ "large enough").

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For all h , let V^h be the discrete subspace of $H_0^1(\Omega)$.

Define $\mathbb{T}^h \in \mathcal{L}(V^h)$ such that:

- the form $a_{scal}(\cdot, \cdot)$ is \mathbb{T}^h -coercive, with a coercivity constant independent of h ;
- the $(\mathbb{T}^h)_h$ are uniformly continuous.

The *error estimate* is recovered (via a uniform stability estimate for a_{scal} over $(V^h)_h$):

$$\exists C > 0, \exists h_0 > 0, \forall h \in]0, h_0] \quad \|u - u^h\|_{H_0^1(\Omega)} \leq C \inf_{v^h \in V^h} \|u - v^h\|_{H_0^1(\Omega)}.$$

Back to the Maxwell problem

In addition to a compact embedding result, establish either

- (1) \mathbb{T} - and uniform \mathbb{T}^h - coercivity, or
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● [Bonnet-Jr-Zwölf'08] on approach (2):

- The embedding of $\mathcal{X}_0(\varepsilon; \Omega)$ into $L^2(\Omega)^3$ is compact.
- The two-field formulation, with $\underline{\mathcal{H}}_2 := \left(\frac{1}{|\mu_2|} \mathbf{curl} \mathcal{E} \right)_{|\Omega_2}$:

$$\begin{cases} \mathcal{E} \in \{ \mathcal{F} \in \mathcal{X}_0(\varepsilon; \Omega) \mid \operatorname{div} \varepsilon \mathcal{F} = 0 \} \\ \underline{\mathcal{H}}_2 \in H(\mathbf{curl}; \Omega_2) \end{cases}$$

fits into the *coercive+compact framework*.

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- (2) a well-posed two-field formulation.

● [Bonnet-Jr-Zwölf'08] on approach (2):

- The embedding of $\mathcal{X}_0(\varepsilon; \Omega)$ into $L^2(\Omega)^3$ is compact.
- The two-field formulation, with $\underline{\mathcal{H}}_2 := \left(\frac{1}{|\mu_2|} \mathbf{curl} \mathcal{E} \right)_{|\Omega_2}$:

$$\begin{cases} \mathcal{E} \in \{ \mathcal{F} \in \mathcal{X}_0(\varepsilon; \Omega) \mid \operatorname{div} \varepsilon \mathcal{F} = 0 \} \\ \underline{\mathcal{H}}_2 \in H(\mathbf{curl}; \Omega_2) \end{cases}$$

fits into the *coercive+compact framework*.

Assumptions:

- Compact embedding: smooth interface and $|\kappa_\varepsilon|$ "large enough".
- Two-field formulation: $|\kappa_\mu|$ "large enough".

Numerical experiments

- In the unit cube, split in two halves (with $\Sigma := \{\frac{1}{2}\} \times]0, 1[\times]0, 1[$).
- An *exact* piecewise smooth solution is available.
- Discretization of the natural formulation (with $s|_{\Omega_i} = 1/(\mu_i \varepsilon_i^2)$):
Find $\mathcal{E} \in \mathcal{X}_0(\varepsilon; \Omega)$ such that

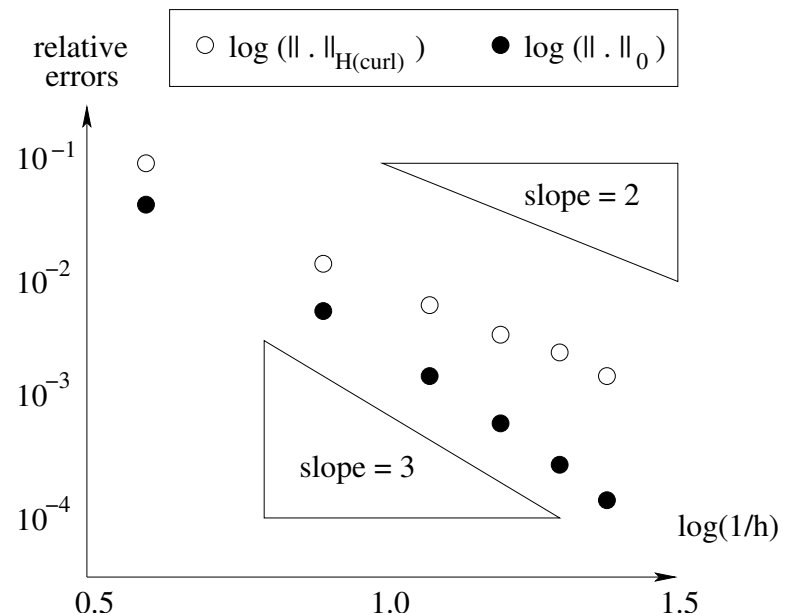
$$\int_{\Omega} \frac{1}{\mu} (\mathbf{curl} \mathcal{E} \cdot \mathbf{curl} \bar{\mathcal{E}}' + \operatorname{div} \mathcal{E} \operatorname{div} \bar{\mathcal{E}}') d\Omega - \omega^2 \int_{\Omega} \varepsilon \mathcal{E} \cdot \bar{\mathcal{E}}' d\Omega = \int_{\Omega} \mathcal{F} \cdot \bar{\mathcal{E}}' d\Omega, \quad \forall \mathcal{E}' \in \mathcal{X}_0(\varepsilon; \Omega).$$

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"Usual" case: $\omega = 4$,
 $(\varepsilon_1, \mu_1) = (+1, +1)$,
 $(\varepsilon_2, \mu_2) = (+1, +1)$,
 with P_2 Lagrange FE.

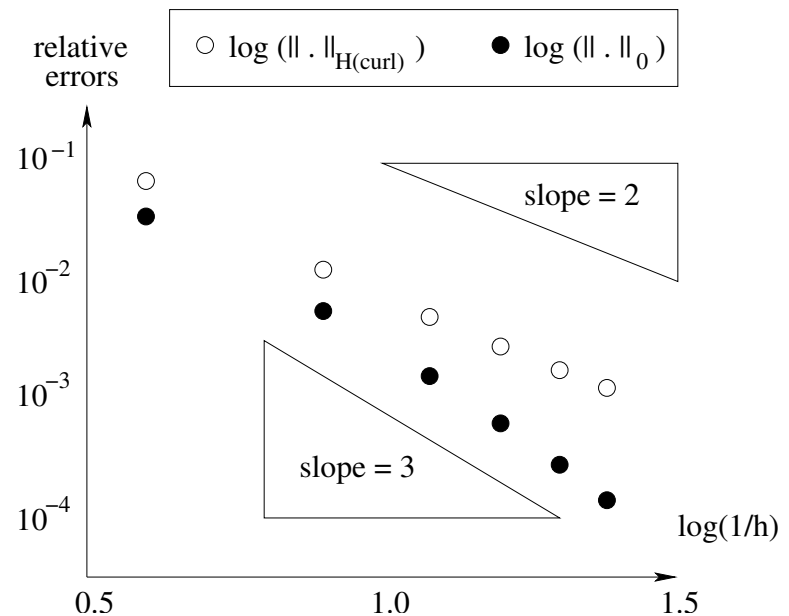


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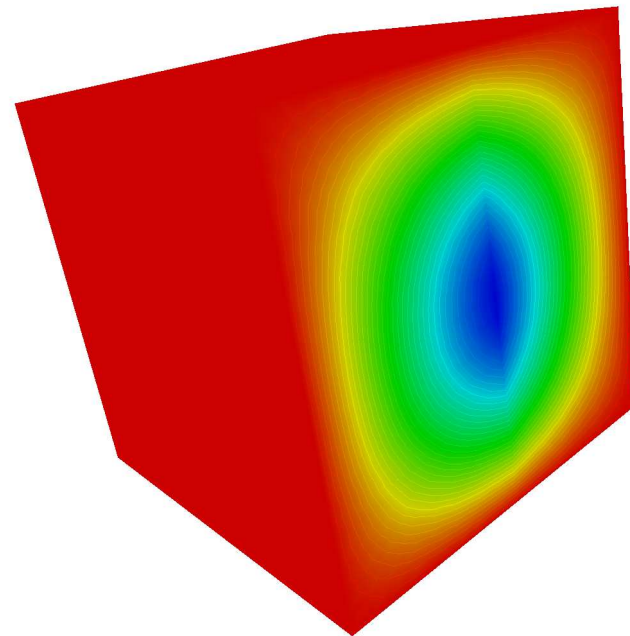


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computed electric field (\mathcal{E}_y^h).

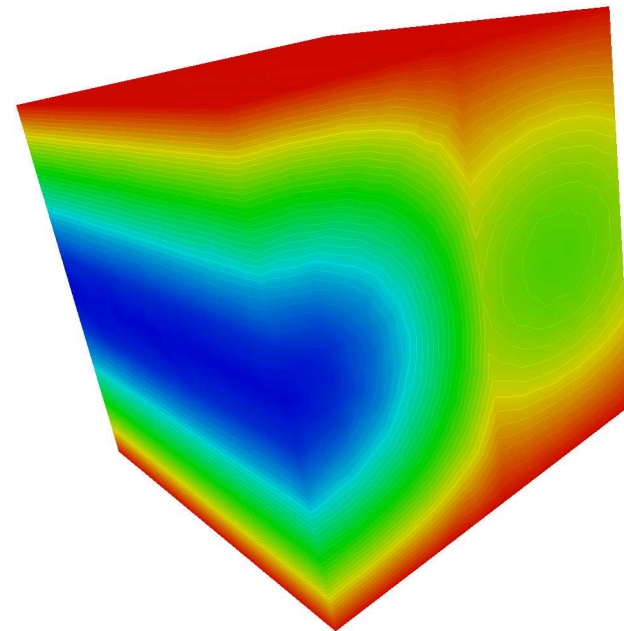


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 $(\varepsilon_2, \mu_2) = (-2, -\frac{1}{2})$,
computed magnetic field (\mathcal{H}_z^h).



Perspectives

- For the Maxwell problem:
 - remove the regularity assumptions on the interface (allow corners and edges) ;
 - prove \mathbb{T} - and uniform \mathbb{T}^h - coercivity ;
 - enforce the divergence condition (with a Lagrange multiplier).

Perspectives

- For the Maxwell problem:
 - remove the regularity assumptions on the interface (allow corners and edges);
 - prove \mathbb{T} - and uniform \mathbb{T}^h - coercivity;
 - enforce the divergence condition (with a Lagrange multiplier).
- For both the scalar and the Maxwell problems, investigate the case when $\kappa_\mu \in]\kappa_\mu^{\text{inf}}, \kappa_\mu^{\text{sup}}[$, $\kappa_\varepsilon \in]\kappa_\varepsilon^{\text{inf}}, \kappa_\varepsilon^{\text{sup}}[$:
 - (re)define a mathematical framework;
 - are the models derived from physics still relevant?