

# Efficient resolution of logical models

## ENSTA-IA303

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ENSTA Paris

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# About the “second part” of IA303

Contact information:

- via email: sergio.mover <at> lix.polytechnique.fr
- “on-demand” office hours: Friday from 2pm to 3pm
- Get in touch also if you are interested in research in:
  - ▶ Formal methods (formal verification, decision procedures, ...)
  - ▶ Artificial intelligence (mainly related to the use logics, symbolic AI, planning, ...)
  - ▶ Cyber-Physical systems (e.g., hybrid systems, ...)

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In the next 4 classes:

- Introduction to Satisfiability Modulo Theories (SMT) (week 4, today)
- How some theory solvers works: EUF (week 5) and LRA/LIA (week 6)
- Some applications of SMT in formal verification (week 7)

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Main take-away points:

- SMT is a powerful and mature tool, with wide applications
- How to formalize a problem in SMT and use an SMT solver
- How an SMT solver works and why is it efficient (despite the problem complexity)

# Lecture 4: Satisfiability Modulo Theories and DPLL( $\mathcal{T}$ )

# Main goals for today

In class<sup>1</sup>:

- Why and where do we use Satisfiability Modulo Theories (SMT)?
- What is SMT precisely?
- How can we efficiently decide the SMT problem?

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<sup>1</sup>Main references:

- The Calculus of Computation [Bradley and Manna, 2007], Chapter 2 (First-Order Logic) and Chapter 3 (First-Order Theories)
- Satisfiability Modulo Theories [Barrett et al., 2009]
- Lazy Satisfiability Modulo Theories [Sebastiani, 2007]
- Satisfiability modulo theories: introduction and applications [de Moura and Bjørner, 2011]  
- CACM article, good first reading!

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- Why and where do we use Satisfiability Modulo Theories (SMT)?
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- How can we efficiently decide the SMT problem?

In the tutorial:

- How do you use an SMT solver?
- How do you formalize a problem (i.e., encode) as an SMT problem?
- How can you write a program that uses an SMT solver?
- How can you automate the encoding generation for a class of problems?

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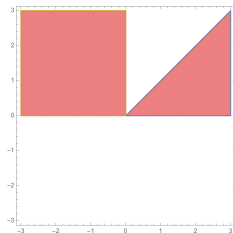
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  - Why SMT?
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## SMT in a nutshell - informal intuition

- Extend of the propositional satisfiability problem to represent specific domains. For example, real numbers:

$$(x - y \geq 0 \vee x < 0) \wedge y > 0$$



- There are more theories: bitvectors, rational and integers linear arithmetic, uninterpreted functions, arrays, strings, separation logics, floating point arithmetic, ...
- SMT is an expressive language.

# What problems can we solve with SMT?

We use SMT to express different have constraints satisfaction problems for several applications:

- Formal Verification for software, hardware, cyber-physical systems, protocols, neural networks (e.g., [Henzinger et al., 2004, McMillan and Padon, 2020, Dutertre et al., 2018, Cimatti et al., 2016, Cimatti et al., 2015])

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- Planning (e.g., [Wolfman and Weld, 1999, Cashmore et al., 2020, Cimatti et al., 2018])
- ...

Active area of research!

With applications in formal methods, programming languages, software engineering, AI, ...

## Software verification

```
float weighted_sum(unsigned int x,
                  unsigned int y) {
    unsigned int i;
    float sum;

    if (y > x) { // swap x and y
        x = x^y; y = y^x; x = x^y;
    }

    sum = 0;
    for (i = 0; i <= (x-y)-1; ++i) {
        float tmp;
        tmp = ((i + 1)) / (x - y);
        sum = sum + tmp;
    }

    return sum;
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Compute  $\sum_{i=1}^{|x-y|} \left(\frac{i}{|x-y|}\right)$   
Is the implementation correct?



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Software verification uses SMT to faithfully model the program semantic

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  - **The SMT problem**
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## Syntax

A *term*  $t$  is either:

- A *constant*  $a, b, c, \dots, 0, 1, \dots$  (or a 0-ary function)
- A *variable*  $x, y, z, \dots$
- An  $n$ -ary *function*  $f(t_1, \dots, t_n)$

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A FOL formula  $\phi$  is either:

- an atom  $a$
- $\neg\psi$ , with  $\psi$  a FOL formula
- $\psi_1 \wedge \psi_2$ , with  $\psi_1$  and  $\psi_2$  FOL formulas.  
Other operators:  $\psi_1 \vee \psi_2 := \neg(\neg\psi_1 \wedge \neg\psi_2)$ ,  $\psi_1 \rightarrow \psi_2 := \neg\psi_1 \vee \psi_2$
- $\exists x.\psi$ , with  $x$  a variable and  $\psi$  a FOL formula
- $\forall x.\phi$ , with  $x$  a variable and  $\psi$  a FOL formula

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We will “almost always” avoid quantifiers

# First-Order Logic - Some examples of syntax

- Terms:
  - ▶  $1, a, b$  are constants
  - ▶  $x, y, z$  are variables
  - ▶  $f(x), g(x, z)$ , and  $g(f(x), y)$  are functions

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- Predicates
  - ▶  $p(a, b), p(a, f(x)), q(x, y)$
- FOL formulas
  - ▶  $p(a, b)$
  - ▶  $\neg p(a, b)$
  - ▶  $(p(a, b) \wedge q(x, y))$
  - ▶  $\forall x. x = y \wedge f(x, y)$
  - ▶  $\forall x. \exists y. (x = y \rightarrow f(x) = f(y))$

# First-Order Logic - Semantic

While Propositional Logic evaluates over true and false, in FOL we have domains and assignments .

A *FOL Interpretation*  $\mathcal{I}$  is the pair  $\mathcal{I} = (\mathcal{D}_{\mathcal{I}}, \alpha_{\mathcal{I}})$ :

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- $\mathcal{D}_{\mathcal{I}}$  is the *domain* of  $\mathcal{I}$ : it's a non-empty set of elements (e.g., values, objects, ...)
- $\alpha_{\mathcal{I}}$  is an *assignment* that maps constants, functions, and predicates to elements, functions, and predicates of  $\mathcal{D}_{\mathcal{I}}$ :

$$\alpha_{\mathcal{I}}(x) := x_{\mathcal{I}} \quad x_{\mathcal{I}} \in \mathcal{D}_{\mathcal{I}}$$

$$\alpha_{\mathcal{I}}(f) := f_{\mathcal{I}} \quad f_{\mathcal{I}} : \mathcal{D}_{\mathcal{I}}^n \rightarrow \mathcal{D}_{\mathcal{I}}$$

Note that constants are 0-ary functions!  $\alpha_{\mathcal{I}}(p) := p_{\mathcal{I}} \quad p_{\mathcal{I}} : \mathcal{D}_{\mathcal{I}}^n \rightarrow \{\text{true}, \text{false}\}$

# First-Order Logic - an example of interpretation

- Consider the FOL formula <sup>2</sup>:  $x + y > z \rightarrow y > z - x$
- A possible interpretation over the integer numbers  $\mathbb{Z}$ 
  - ▶  $\mathcal{D}_{\mathcal{I}} = \mathbb{Z} = \{\dots, -2, -1, 0, 1, 2, \dots\}$
  - ▶ the function  $+$ ,  $-$  are assigned to the plus and minus function in  $\mathbb{Z}$  (i.e.,  $+_{\mathbb{Z}}$ ,  $-_{\mathbb{Z}}$ )
  - ▶ the predicates  $>$  is assigned to  $>_{\mathbb{Z}}$
  - ▶  $x, y, z$  are 0-ary functions of integer type
  - ▶  $\alpha_{\mathcal{I}} := \{x \mapsto 13, y \mapsto 2, z \mapsto 4, > \mapsto >_{\mathbb{Z}}, + \mapsto +_{\mathbb{Z}}, - \mapsto -_{\mathbb{Z}}, \dots\}$

---

<sup>2</sup>Example 2.7 from [Bradley and Manna, 2007]

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- we evaluate a term  $t$  with  $\alpha_{\mathcal{I}}(t)$ , recursively:
  - ▶ for a variable  $x$   $\alpha_{\mathcal{I}}(x)$ ,  $\alpha_{\mathcal{I}}(a)$
  - ▶  $\alpha_{\mathcal{I}}(f(t_1, \dots, t_n)) = \alpha_{\mathcal{I}}(f)(\alpha_{\mathcal{I}}(t_1), \dots, \alpha_{\mathcal{I}}(t_n))$
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- $\mathcal{I} \models \neg\phi$  iff  $\mathcal{I} \not\models \phi$

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- we evaluate a term  $t$  with  $\alpha_{\mathcal{I}}(t)$ , recursively:
  - ▶ for a variable  $x$   $\alpha_{\mathcal{I}}(x)$ ,  $\alpha_{\mathcal{I}}(a)$
  - ▶  $\alpha_{\mathcal{I}}(f(t_1, \dots, t_n)) = \alpha_{\mathcal{I}}(f)(\alpha_{\mathcal{I}}(t_1), \dots, \alpha_{\mathcal{I}}(t_n))$
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- $\mathcal{I} \models \neg\phi$  iff  $\mathcal{I} \not\models \phi$
- $\mathcal{I} \models \phi_1 \wedge \phi_2$  iff  $\mathcal{I} \models \phi_1$  and  $\mathcal{I} \models \phi_2$

# First-Order Logic - Semantic

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- $\mathcal{I} \models \exists x.\psi$ , if there is some  $a \in \mathcal{D}_{\mathcal{I}}$ ,  $(\mathcal{D}_{\mathcal{I}}, \alpha_{\mathcal{I}}[x \mapsto a]) \models \psi$
- $\mathcal{I} \models \forall x.\phi$ , if for all  $a \in \mathcal{D}_{\mathcal{I}}$ ,  $(\mathcal{D}_{\mathcal{I}}, \alpha_{\mathcal{I}}[x \mapsto a]) \models \phi$ .

# First-Order Logic - Semantic (Example)

- formula <sup>3</sup>  $\phi := x + y > z \rightarrow y > z - x$
- interpretation  $\mathcal{I} = (\mathbb{Z}, \alpha_{\mathcal{I}})$ :

$$\alpha_{\mathcal{I}} := \{x \mapsto 13, y \mapsto 2, z \mapsto 4, > \mapsto >_{\mathbb{Z}}, + \mapsto +_{\mathbb{Z}}, - \mapsto -_{\mathbb{Z}}, \dots\}$$

- the truth value of  $\phi$  under  $\mathcal{I}$  is:

- 1  $\mathcal{I} \models x + y > 0$
- 2  $\mathcal{I} \models y > z - x$
- 3  $\mathcal{I} \models \phi$

since  $\mathcal{I}[x + y > 0] = 13_{\mathbb{Z}} +_{\mathbb{Z}} 2_{\mathbb{Z}} >_{\mathbb{Z}} 0_{\mathbb{Z}}$   
since  $\mathcal{I}[y > z - x] = 2_{\mathbb{Z}} >_{\mathbb{Z}} 4_{\mathbb{Z}} -_{\mathbb{Z}} 13_{\mathbb{Z}}$   
by 1,2, and the semantic of  $\rightarrow$

---

<sup>3</sup>Example 2.8 from [Bradley and Manna, 2007]

# First-Order Logic - Satisfiability and Validity

A FOL formula  $\phi$  is:

- *satisfiable* iff there exists an interpretation  $\mathcal{I}$  such that  $\mathcal{I} \models \phi$
- *valid* iff for all interpretations  $\mathcal{I}$ ,  $\mathcal{I} \models \phi$

Decidability results (see [Bradley and Manna, 2007]):

- validity is semi-decidable: if  $\phi$  is valid, then there exists a procedure that eventually terminates and says yes
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So, what can we do?

# Restricting the domains and interpretations of FOL

In a lot of cases we know the domains and operations appearing in the formulas.  
For example:

- planning with resources: integer or real numbers
- numerical programs manipulating memory: arrays and integer numbers
- microcode (of CPUs): bounded-length bit vectors
- html web sanitizers: strings
- ...

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If we restrict FOL to such ~~domains and operations~~ **first-order theories** the satisfiability problem **for quantifier-free formulas** becomes decidable.

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# First-Order Theories - Definition

## Theory $\mathcal{T}$

A theory  $\mathcal{T}$  is defined with:

- a signature  $\Sigma$ : set of constants, functions, predicates
- a set of axioms  $\mathcal{A}$ : set of closed FOL formulas (i.e., no free variables) containing constants, functions, predicates from  $\Sigma$

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- $\mathcal{I}$  also satisfy  $\phi$  ( $\mathcal{I} \models_{\mathcal{T}} \phi$ )

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An example please!

# Equalities and Uninterpreted functions

The Theory of Equalities and Uninterpreted functions  $\mathcal{T}_E$  is defined as:

- the signature  $\Sigma_E := \{=, a, b, c, \dots, f, g, h, \dots, p, q, r, \dots\}$ 
  - ▶  $=$  is a binary predicate and is *interpreted* as the equality
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- the set of axioms  $\mathcal{A}$ :

①  $\forall x. x = x$

[reflexivity]

②  $\forall x, y. x = y \rightarrow y = x$

[symmetry]

③  $\forall x, y, z. (x = y \wedge y = z) \rightarrow x = z$

[transitivity]



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④ Function and predicate congruence

★ For each  $n \in \mathbb{N}$  and  $n$ -ary function symbol  $f$ :

$$\forall x_1, \dots, x_n, y_1, \dots, y_n. \left( \bigwedge_{i=1}^n x_i = x_j \right) \rightarrow f(x_1, \dots, x_n) = f(y_1, \dots, y_n)$$

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## Some concrete examples

$$a \neq b$$

Is sat?

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Hint: treat  $*$  and  $+$  as an uninterpreted function.

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Is the satisfiability of EUF-formulas decidable?

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Is the satisfiability of EUF-formulas decidable? More next week!



## Some theories of interest I

- Linear rational and Integer Arithmetic (LRA and LIA) - (week 3)

$$(x + y < 3 \wedge y > 2) \rightarrow x < 1$$

*Used to model arithmetic (note that constraints are linear!)*

- Difference logic

$$(a - b \leq 3 \wedge c - a \leq 2) \vee b - c \leq 10$$

*Used to model arithmetic (note the restrictions, only difference of 2 constants, no strict inequalities)*

- Reals (i.e., polynomial inequalities over the reals)

$$a^2 + 3ab + c \leq 3 \vee a - b \leq 2$$

*Model geometric problems, problems in engineering, ...*

## Some theories of interest II

- Arrays

$$\neg((\text{write}(a, i, v_1) \wedge j = i + 1) \rightarrow (\text{read}(a, i) < \text{read}(a, j, v)))$$

*Model unbounded memory in programs*

- Bit-Vectors - a bit-vector  $x_{[n]}$  is a vector of bits of length  $n$

$$x_{32}[15 : 0] = y_{[16]}[7 : 0] :: y_{[16]}[15 : 8]$$

*Model hardware operations and low-level software*

- Strings

$$y = "a" \cdot x \wedge x = z \cdot "b" \rightarrow y = "a" \cdot w \cdot "b"$$

*Model string constraints, for example for testing or security*

# Satisfiability Modulo Theory Problem

## SMT Problem

The problem of deciding the satisfiability of quantifier-free formulas expressed in some *decidable* first order theory  $\mathcal{T}$

Some remarks:

- Usually quantifier-free formulas, but SMT solver can deal with quantifiers (semi-decidable or focus on decidable subsets, like Effectively Propositional Logic)
- Also consider formulas obtained combining multiple theories, e.g.,  
 $\mathcal{T}_1 \cup \mathcal{T}_2 \cup \dots \cup \mathcal{T}_n$

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- We can enumerate all the  $\mu^b$  Propositional models of  $(P_1 \vee P_2) \wedge (P_3 \vee P_4)$

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- For each model  $\mu^b$ , we can check if the conjunction is *consistent* in the theory  $\mathcal{T}$ :

$$x > 3 \wedge \neg x + y = 0 \wedge y < 0 \wedge \neg x < 3$$

It's satisfiable:  $\mu := \{x \mapsto 4, y \mapsto 0\}$

This is the lazy approach to SMT (e.g., see [\[Sebastiani, 2007\]](#))

# Offline lazy approach to SMT solving

**procedure**  $\mathcal{T}$ -DPLL-offline( $\phi$ )

$\phi^b := TO_{\mathbb{B}}(\phi)$

**while** true **do**

$res, \mu^b := DPLL(\phi^b)$

**if**  $res = true$  **then**

$\mu := TO_{\mathcal{T}}(\mu^b)$

$res := \mathcal{T}consistent(\mu)$

**if**  $res = true$  **then**

**return** SAT

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- **Boolean reasoning**: delegates the enumeration to the DPLL (or CDCL solver)
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- **Boolean reasoning**: delegates the enumeration to the DPLL (or CDCL solver)
- **Theory reasoning**: check consistency of  $\mathcal{T}$ -literals (simpler problem) with a dedicated  $\mathcal{T}$ -solver
- **Boolean reasoning**: add a blocking clause  $\mu_b$  to avoid to “visit” the same Boolean model

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  - ▶ What is the effect on the backjumping of CDCL?
  - ▶ What is the effect on learning clauses?
- Check for  $\mathcal{T}$ -consistency of full models  $\mu$  could be unsatisfiable “earlier”
  - ▶ Can we detect unsatisfiability due to theory “earlier” in the search?
  - ▶ Can we generalize Boolean constraint Propagation to the theory  $\mathcal{T}$ ?

Could we have a tighter integration of CDCL and the  $\mathcal{T}$ -Solver?

# The online approach - DPLL( $\mathcal{T}$ )

Similar architecture to CDCL, but integrates the theory reasoning:

**procedure** DPLL- $\mathcal{T}(\phi)$

May pre-process  $\phi$  (e.g., propagation)

$\mu := \emptyset$

$\phi^b := TO_{\mathbb{B}}(\phi); \mu^b = TO_{\mathbb{B}}(\mu)$

**while true do**

$\mathcal{T} - Decide(\phi^b, \mu^b)$

**while true do**

$res := \mathcal{T} - Deduce(\phi^b)$

**if**  $res = true$  **then**

$\mu := TO_{\mathcal{T}}(\mu^b)$

**return SAT**

**else if**  $res = conflict$  **then**

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- **analyze**: detect the conflict clauses and determines the decision level to backtrack to.
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- **backtrack**: block the conflict clause and backtracks to the level  $lvl$  (similar to DPLL)
  - ▶  $\mathcal{T}$ -backjumping and  $\mathcal{T}$ -learning

## $\mathcal{T}$ -backjumping and $\mathcal{T}$ -learning

When we invoke the  $\mathcal{T}$ -solver on an assignment  $\mu$ , and  $\mu$  is not consistent:

- we would like to infer a small subset  $\nu \subseteq \mu$  such that  $\nu$  is not consistent (i.e.,  $\nu$  is a *conflict set* )

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In practice, we can consider  $\mathcal{T}$ -propagations (see later) as unit-propagation in the implication graph.
- $\neg\nu^b$  can be learned as a conflict clause by the sat solver

Ideally, the  $\mathcal{T}$ -solver should search for a minimal conflict set  $\nu \subseteq \mu$

- in practice, finding a minimal set  $\nu$  is expensive
- $\mathcal{T}$ -solvers compromise performance and size of the conflict set  $\nu$

# $\mathcal{T}$ -Backjumping and $\mathcal{T}$ -Learning

Examples <sup>4</sup> over the theory of Linear Integer Arithmetic:

$$\neg(2x_2 - x_3 > 2) \vee A_1$$

$$\neg A_2 \vee x_1 - x_5 \leq 1$$

$$3x_1 - 2x_2 \leq 3 \vee A_2$$

$$\neg(2x_3 + x_4 \geq 5) \vee \neg(3x_1 - x_3 \leq 6) \vee \neg A_1 \quad \neg B_4 \vee \neg B_5 \vee \neg A_1$$

$$A_1 \vee 3x_1 - 2x_2 \leq 3$$

$$x_2 - x_4 \leq 6 \vee x_5 = 5 - 3x_4 \vee \neg A_1$$

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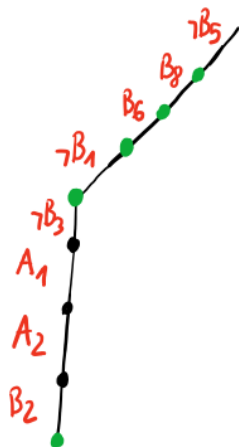
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- $\mu^b := \neg B_5, B_8, B_6, \neg B_1, \neg B_3, A_1, A_2, B_2$



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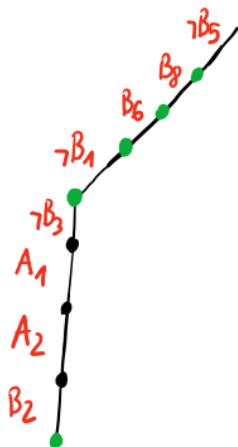
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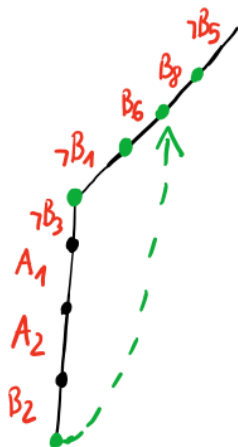
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- The solver backtracks removing all literals up to  $\{\neg B_5, B_8\}$ .



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# $\mathcal{T}$ -Propagation

- Used in  $\mathcal{T}$  – *decide* to deduce the value of unassigned literals:
  - ▶ When the current (partial) assignment  $\mu$  is satisfiable
  - ▶ The  $\mathcal{T}$ -solver can return a set  $\nu$  of unassigned literals such that  $\mu \models_{\mathcal{T}} \nu$
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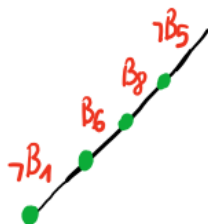
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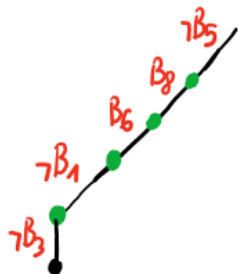
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- $\neg(3x_1 - x_3 \leq 6) \wedge x_3 = 3x_5 + 4 \wedge x_2 - x_4 \leq 6 \wedge (2x_2 - x_3 > 2) \models_{\mathcal{T}} \neg(3x_1 - 2x_2 \leq 3)$



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- Abstract DPLL: abstract formulation of DPLL as a transition system  
Allow to reason about the properties of different variants of the algorithm (e.g., correctness, completeness, termination)
- Model-Constructing Satisfiability:
  - ▶ Assignments (e.g., decisions) to theory variables, not just Propositional  
i.e., no Boolean abstraction anymore, and no enumeration of the models of the Boolean Abstraction.
  - ▶ Decisions and explanations can be done for new atoms (obtained from unsatisfiable proofs)
  - ▶ Several implementation, efficient for Non-Linear Real Arithmetic


## To sum up

What did we see today:





- SMT is a fundamental tool in several area (e.g., verification, program analysis, planning, ...)
- Satisfiability of (full) First Order logic is undecidable - so what can we do?
- Theories allow us to have decision procedures - motivation to look at the SMT problem
- The lazy approach to SMT: best of both worlds (CDCL SAT solver) and efficient theory solvers

**Next week:** how to decide consistency for the theory of Equalities and Uninterpreted Functions

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