

## Numerical methods for dynamical systems

### Homework n° 5

#### Goal(s)

- ★ Implementation of shooting methods to solve two point boundary value problems
- ★ Implementaion of finite difference method to solve two point boundary value problems

#### Exercise 1 – Shooting method

The goal of this exercise is to implement simple shooting method to solve two-point boundary value problem for ODE

We recal that IVP-ODE is defined by

$$\dot{\mathbf{y}} = f(t, \mathbf{y}) \quad \text{with} \quad \mathbf{y}(0) = \mathbf{y}_0 . \quad (1)$$

Application of forward Euler's methods for this IVP-ODE with a step-size  $h$  defined an iterative function

$$\mathbf{y}_{n+1} = \mathbf{y}_n + hf(t_n, \mathbf{y}_n) \quad \text{et} \quad t_{n+1} = t_n + h .$$

Dans un premier temps, la résolution des BVP pourra utiliser cette méthode mais rien n'interdit d'utiliser les méthodes plus sophistiquées vues en cours.

We will consider this simple BVP problem

$$\ddot{y} = \frac{3}{2}y^2$$

avec  $y(0) = 4$  et  $y(1) = 1$

Note that two solutions exist for this problem (see [https://en.wikipedia.org/wiki/Shooting\\_method](https://en.wikipedia.org/wiki/Shooting_method))

- $\dot{y}(0) = -8$
- $\dot{y}(0) \approx -35.858548$

#### Question 1

Implement the simple shooting method with a bisection approach

#### Question 2

Change the numerical method to solve this problem to use variable step-size approach still using bisection approach. Compare the speed to solve this problem.

#### Question 3

Change the root finding method to use Newton approach with finite difference method to approximate the Jacobian. Compare the speed to solve this problem with fixed step-size and variable step-size integrator.

#### Exercise 2 – Finite difference method

##### Question 1

Apply finite difference approach to solve the BVP-ODE problem. Compare the speed to solve this problem with various discretization step-size  $h$ .

**Note** you should use Python function in numpy to solve the system

**TO SUBMIT**

- A small report should be sent summarize the answers to the questions.

— This report should be associated to the source code.

Send the archive containing the report and the source codes in a mail which title is

[numerical methods for dynamical systems] FIRSTNAME LASTNAME

to [alexandre.chapoutot@ensta-paris.fr](mailto:alexandre.chapoutot@ensta-paris.fr)

**before the next lecture, Friday October 23, 2020.**